

# Differential Geometry: Handwritten notes

by

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## KEYWORDS

### Curves with torsion:

Curve, space curve, equation of tangent, normal plane, principal normal curvature, derivation of curvature, plane of the curvature or osculating plane, principal normal or binormal, rectifying plane, equation of binormal, torsion, Serret Frenet formulae, radius of torsion, the circular helix, skew curvature, centre of circle of curvature, spherical curvature, locus of centre of spherical curvature, helices, spherical indicatrix, evolute, involute.

### Differential geometry of surfaces:

Surface, tangent plane and normal, equation of tangent plane, equation of normal, one parameter family of surfaces, characteristic of surface, envelopes, edge of regression, equation of edge of regression, developable surfaces, osculating developable, polar developable, rectifying developable.

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It is highly recommended that DON'T use these notes as a reference.

Reference: C. E. Weatherburn, *Differential geometry of three dimensions*, Cambridge at the university press, 1955. ( <http://archive.org/details/differentialgeom003681mbp> )

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**DIFFERENTIAL GEOMETRY**

CHAPTER I

"CURVES WITH TORSION"

CURVE : The locus of a point  $P(x, y, z)$  whose position vector  $\underline{r}$  relative to a fixed origin may be expressed as a function of a single variable parameter is called a curve. The cartesian coordinates can be expressed as  $x = f_1(t)$ ,  $y = f_2(t)$ ,  $z = f_3(t)$   $t$  is called parameter.  $f_1, f_2$  and  $f_3$  are fns of  $t$ .

SPACE CURVE. When the curve is not a plane curve, it is said to be skew or twisted or Torsuous curve.

Examples (i) The set of equations  $\begin{cases} z = x^2 + y^2 + 2z \\ \underline{r} = a \cos t \underline{i} + b \sin t \underline{j} + z \underline{k} \end{cases}$   
 as  $x = a \cos t$   $y = b \sin t$   $z = 0$ ,  $0 \leq t \leq 2\pi$

represent a circle, with centre at  $O$  and radius  $a$ .

$$\left. \begin{aligned} \frac{x}{a} &= \cos t \\ \frac{y}{a} &= \sin t \end{aligned} \right\} \text{ Squaring \& adding} \\ x^2 + y^2 &= a^2$$

$$\left. \begin{aligned} \underline{r}(t) &= a \cos t \underline{i} + b \sin t \underline{j} + z \underline{k} \\ \underline{r}(t) &= x \underline{i} + y \underline{j} + z \underline{k} \end{aligned} \right\} \text{ Comparing} \\ x &= a \cos t \\ y &= b \sin t, \quad z = 0$$

$$\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 = \cos^2 t + \sin^2 t = 1$$

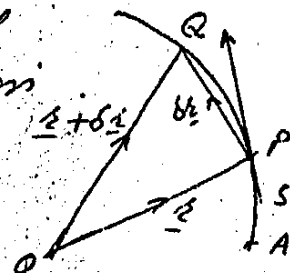
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

Eq of ellipse

EQUATION OF A TANGENT at a pt on a curve.

Suppose that position vector  $\underline{r}$  of a point  $P$  on a curve is function of  $S$ , (length of arc), from a fixed point  $A$  on it.

Let  $P, Q$  be the neighbouring pts on the curve with p. vectors  $\underline{r} + \underline{r} + \delta \underline{r}$  resp corresponding to the values  $S$  and  $S + \delta S$  of.



By C.E. Macfarlane (Cambridge Univ Press)

The parameter, then  $\delta r$  is the vector  $\vec{PQ}$ . The quotient  $\frac{\delta r}{\delta s}$  is a vector along  $\delta r$  and in the limit as  $\delta s \rightarrow 0$ , this direction becomes that of the Tangent at P.

Also, in the limit  $\frac{\delta r}{\delta s}$  when  $Q \rightarrow P$  and  $\delta s \rightarrow 0$  tends to unity & it is a unit vector  $\parallel$  to Tangent at P in the positive direction. It is denoted by  $\underline{t}$  & called as unit Tangent at P.

Thus  $\underline{t} = \lim_{\delta s \rightarrow 0} \frac{\delta r}{\delta s} = \frac{dr}{ds} = \dot{r}$   $\rightarrow$  (1)  
 For the point on the Tangent, if  $\underline{R}$  is its p.v. then  $\underline{R} = \underline{r} + U\underline{t}$  where  $U$  is any real no. +ve or -ve. This is the equation of Tangent.

### NORMAL PLANE :-

The normal plane at P is the plane through P perpendicular to the Tangent to a curve.

#### Equation of Normal plane:

Let  $P(x, y, z)$  be a pt on the curve w.r.t a rectangular coordinate system.

then  $\underline{r} = x\underline{i} + y\underline{j} + z\underline{k}$

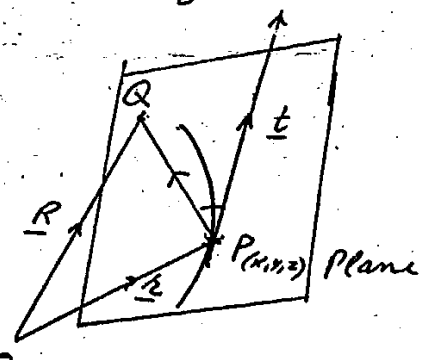
Suppose  $\underline{R}$  be in p.v. of a pt Q in the plane. Then  $\underline{R} - \underline{r}$  is the p.v. of the line  $\vec{PQ}$ .

then  $\frac{d\underline{r}}{ds} = \frac{dx}{ds}\underline{i} + \frac{dy}{ds}\underline{j} + \frac{dz}{ds}\underline{k} = x'\underline{i} + y'\underline{j} + z'\underline{k} = \underline{t}$   
 where  $\frac{dx}{ds}, \frac{dy}{ds}, \frac{dz}{ds}$  are direction cosines of  $\underline{t}$ .

The equation of normal plane is

$(\underline{R} - \underline{r}) \cdot \underline{t} = 0$  ( $\because \underline{R} - \underline{r} \perp \underline{t}$ )

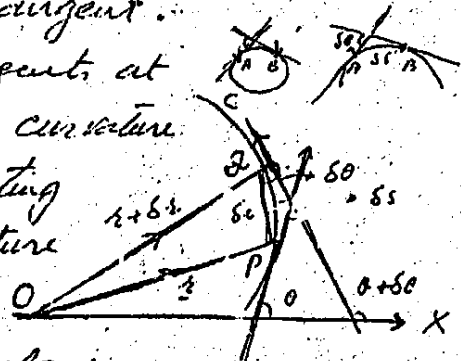
Then every line through P in this plane is a normal to the curve. are  $\perp$  to each other



## PRINCIPAL NORMAL, CURVATURE.

Def The curvature of the curve at any pt. is the arc-rate of rotation of the Tangent.

If  $\delta\theta$  is the angle between the Tangents at P and Q,  $\frac{\delta\theta}{\delta s}$  is the average curvature of the arc PQ and its limiting value as  $\delta s \rightarrow 0$  is the curvature at the pt. P. This is called the first curvature or the oscular curvature and is denoted by  $K$ . (Keppner)



Thus

$$K = \lim_{\delta s \rightarrow 0} \left( \frac{\delta\theta}{\delta s} \right) = \frac{d\theta}{ds} = \theta' \quad \text{when } \widehat{PQ} = \delta s$$

### Derivation of Curvature

Let  $C$  be a curve and  $Ox$  as a fixed direction. Suppose  $P$  and  $Q$  be two pts on the curve  $C$  with  $p$  vs  $t$  and  $t + \delta t$  w.r.t  $O$  and  $\theta$  vs  $\theta + \delta\theta$  be the angles of Tangents at  $P$  and  $Q$  resp.

The angle  $\delta\theta$  is the angle between two tangents at  $P$  and  $Q$ , where arc  $\delta s = \widehat{PQ}$

Then  $\frac{\delta\theta}{\delta s}$  is the average curvature of arc  $\widehat{PQ}$ . The limiting value of  $\frac{\delta\theta}{\delta s}$  when  $\delta s \rightarrow 0$  is called curvature at  $P$

$$\text{Thus } K = \lim_{\delta s \rightarrow 0} \left( \frac{\delta\theta}{\delta s} \right) = \frac{d\theta}{ds} = \theta'$$

Def The reciprocal of  $K$  is defined as

$\rho = \frac{1}{K}$ , as radius of curvature which is taken to be +ve.

$$\therefore \cos 0 = 1 \Rightarrow 1 = 1$$

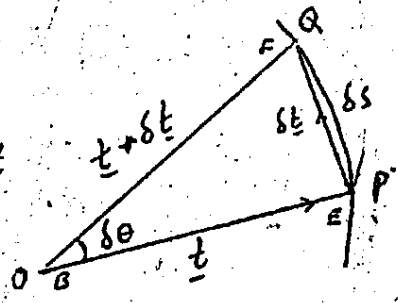
### Normal Plane of Curvature or Osculating plane.

Since  $\underline{t}$  is unit Tangent &  $\underline{t} \cdot \underline{t} = 1$

$$\text{Diff w.r.t } s \quad 2 \underline{t} \cdot \frac{d\underline{t}}{ds} = 0$$

$$\Rightarrow \underline{t} \cdot \frac{d\underline{t}}{ds} = 0 \quad \text{since direction of } \underline{t} \text{ changes from pt to pt on the } C$$

$\therefore \frac{d\hat{t}}{ds} \neq 0$  since  $\hat{t} \neq 0, \frac{dt}{ds} \neq 0$   
 The gradient  $\frac{\delta\hat{t}}{\delta s}$  is a vector  $\parallel \hat{t}$   $\delta\hat{t}$   
 and therefore, in the limit as  $\delta s \rightarrow 0$   
 its direction is  $\perp$  to the Tangent-



at P since  $|\hat{t}| = 1, |\hat{t} + \delta\hat{t}| = 1$ . The limiting value  
 of  $\frac{\delta\hat{t}}{\delta s}$  is the limiting value of  $\frac{\delta\theta}{\delta s}$  which is  $K$ . Hence

$\frac{d\hat{t}}{ds} = \lim_{\delta s \rightarrow 0} \frac{\delta\hat{t}}{\delta s} = K \hat{n}$  where  $\hat{n}$  is a unit  
 vector  $\perp$  to  $\hat{t}$ , and in the plane of the Tangent at P  
 and a consecutive pt. Q.

Def The plane containing two consecutive ~~pts~~  
 Tangents and therefore containing 3 cons. pts  
 at P, is called the plane of curvature or  
 the osculating plane.

If  $R$  is any pt in this plane, the vectors  
 $R - \underline{r}, \hat{t}$  and  $\hat{n}$  are coplanar. Hence  
 the relation  $[(R - \underline{r}, \hat{t}, \hat{n})] = 0$  which is the  
 equation of osculating plane. It is also  
 expressed as

$$[(R - \underline{r}, \hat{t}', \hat{t}'')] = 0$$

The unit vectors  $\hat{t}$  and  $\hat{n}$  are  $\perp$  to each  
 other and their plane is plane of curvature.

### PRINCIPAL NORMAL & BINORMAL

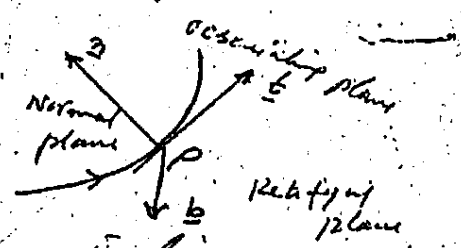
The straight line through P parallel to  $\hat{n}$   
 ( $\perp$  to  $\hat{t}$ ) and lying in the osculating plane  
 is called Principal normal at P  
 and denoted as  $\hat{n}$ .

Its equation is clearly

$$\underline{R} = \underline{r} + u \hat{n}$$

where  $\underline{R}$  being a current pt. on the line.

Def The normal at P which is  $\perp$  to the Osculating  
 plane is called "Binormal" at P and  
 it is denoted as  $\hat{b}$ . The vectors  $\hat{t}, \hat{b}$  and  
 $\hat{n}$  are  $\perp$  to one another. Note that  $\hat{b}$  is along  $\hat{t} \times \hat{n}$   
 (form R.H. System)  
 of unit vectors



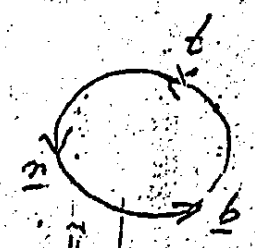
Note that  $\underline{t} \cdot \underline{t}' = \underline{m} \cdot \underline{n} = \underline{b} \cdot \underline{b} = 1$

$$\underline{t} \cdot \underline{n} = \underline{n} \cdot \underline{b} = \underline{b} \cdot \underline{t} = 0$$

also

$$\left. \begin{aligned} \underline{t} \times \underline{n} &= \underline{b} \\ \underline{n} \times \underline{b} &= \underline{t} \\ \underline{b} \times \underline{t} &= \underline{n} \end{aligned} \right\}$$

$$\underline{b} \times \underline{t} = \underline{n} \times \underline{n} = \underline{b} \cdot \underline{b} = 0$$

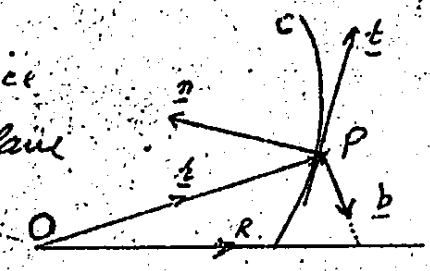


### Rectifying plane

The plane through the point P and  $\perp$  to the normal is called rectifying plane.

### Equation of Binormal

Let  $P(\underline{r})$  be a point on C. Since a unit vector  $\underline{b} \perp$  to osculating plane is called binormal where  $\underline{n}$  &  $\underline{t}$  are <sup>unit</sup> normal & unit tangent at P.



The equation of Principal normal is  $\underline{R} = \underline{r} + u \underline{n}$  (i) where  $\underline{R}$  is a current pt on the line. Similarly equation of Binormal can also be written as

$$\underline{R} = \underline{r} + u \underline{b} \quad \text{--- (ii)}$$

$$\begin{aligned} \text{or } \underline{R} &= \underline{r} + u (\underline{t} \times \underline{n}) \quad \because \underline{b} \parallel \underline{t} \times \underline{n} \\ &= \underline{r} + v (\underline{t}' + \underline{t}''/k) \end{aligned}$$

Let  $v = u/k$  then

$$\underline{R} = \underline{r} + v (\underline{t}' \times \underline{t}'') \quad \text{--- (iii)}$$

(ii) & (iii) are the eqs of binormal at P.

$$\begin{aligned} \underline{t}' &= \underline{t}'' \\ \frac{d\underline{t}}{ds} &= \underline{t}'' \\ \frac{d\underline{t}}{ds} &= k \underline{n} \\ \underline{n} &= \frac{\underline{t}''}{k} \end{aligned}$$

$k$  (kappa)

### TORSION

The measure of arc-rate of turning of the unit binormal vector  $\underline{b}$  is called Torsion of the curve at the point P. It is of course, the rate of rotation of the osculating plane, and it is denoted as  $T$ .

Since  $k$  is +ve but Torsion may be +ve or -ve

as  $\frac{d\underline{b}}{ds} = -T \underline{n}$ , -ve sign shows  $\rightarrow$

That the Torsion is regarded as Positive when the rotation of the binormal as  $s$  increases is in the same sense that of a right handed screw travelling in the direction of  $t$ . From figure, it is clear that in this case  $t$  is the opposite direction to  $m$ .

## SERRET FRENET FORMULAE.

These <sup>1857</sup> formulae for the derivatives of  $ds$  for Tangent, normal & binormal <sup>1852</sup>

1: For Tangent  $\frac{dt}{ds} = K \underline{n}$

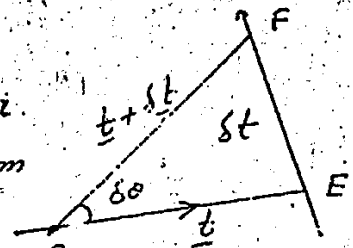
2: For Binormal  $\frac{db}{ds} = -\tau \underline{t}$

3: For <sup>Principal</sup> normal  $\frac{dn}{ds} = \tau \underline{b} - K \underline{t}$

Proofs.

1: To prove  $\frac{dt}{ds} = K \underline{n}$

Since the unit-tangent is not a constant vector as its direction changes from point to point of the curve



Let  $\underline{t}$  and  $\underline{t} + \delta \underline{t}$  be values of unit tangent at E and F resp. The vectors  $\vec{BE}$  and  $\vec{BF}$  are resp. equal to these. Then  $\vec{EF} = \delta \underline{t}$  & let angle  $\widehat{EBF} = \delta \theta$

The quotient  $\frac{\delta \underline{t}}{\delta s}$  is a vector parallel to  $\delta \underline{t}$ . As  $\delta s \rightarrow 0$  its direction is  $\perp$  to tangent at  $\underline{t}$ .

Moreover  $\vec{BE}$  and  $\vec{BF}$  are of unit-lengths

The modulus of limiting value of  $\frac{\delta \underline{t}}{\delta s}$  is equal to limiting value of  $\frac{\delta \theta}{\delta s}$ , which is  $K$  (Kappa)

Hence the relation

$$\frac{dt}{ds} = \lim_{\delta s \rightarrow 0} \left( \frac{\delta \underline{t}}{\delta s} \right) = K \underline{n}$$

where  $\underline{n}$  is unit-

vector  $\perp$  to  $\underline{t}$  and in the plane of tangents at two consecutive pts.

2: To prove  $\frac{db}{ds} = -\tau \underline{m}$

Proof (consider  $\underline{b} \cdot \underline{b} = b^2 = 1$ , diff w.r.t  $s$ )

$$2\underline{b} \cdot \frac{d\underline{b}}{ds} = 0$$

$$\text{or } \underline{b} \cdot \underline{b}' = 0 \rightarrow 0 \quad \therefore \frac{d\underline{b}}{ds} = \underline{b}'$$

$$\Rightarrow \underline{b}' \perp \underline{b}$$

Consider the relation:

$$\underline{t} \cdot \underline{b} = 0$$

Diff w.r.t  $s$

$$\underline{t} \cdot \frac{d\underline{b}}{ds} + \frac{d\underline{t}}{ds} \cdot \underline{b} = 0$$

$$\underline{t} \cdot \underline{b}' + \kappa \underline{n} \cdot \underline{b} = 0 \quad \left| \because \frac{d\underline{t}}{ds} = \kappa \underline{n} \right.$$

$$\Rightarrow \underline{t} \cdot \underline{b}' = 0 \quad \text{as } \underline{n} \cdot \underline{b} = 0$$

$$\Rightarrow \underline{b}' \perp \underline{t} \quad \text{--- (ii)}$$

But from (i) it is proved that  $\underline{b}' \perp \underline{b}$  so  $\underline{b}'$  is parallel to  $\underline{n}$ , we may write it

$$\underline{b}' = -\tau \underline{n} \quad \text{where } \tau \text{ measures}$$

the rate of turning of unit vector  $\underline{b}$  and -ve sign ~~has~~ has been chosen to keep  $\tau$  ~~pos.~~ positive.

3: To prove  $\frac{d\underline{n}}{ds} = \tau \underline{b} - \kappa \underline{t}$

Consider  $\underline{n} = \underline{b} \times \underline{t}$  --- (i)

Diff (i) w.r.t  $s$

$$\frac{d\underline{n}}{ds} = \underline{b} \times \frac{d\underline{t}}{ds} + \frac{d\underline{b}}{ds} \times \underline{t}$$

$$= \underline{b} \times \kappa \underline{n} + (-\tau \underline{n}) \times \underline{t}$$

$$= \kappa (\underline{b} \times \underline{n}) - \tau (\underline{n} \times \underline{t})$$

$$= -\kappa \underline{t} + \tau \underline{b}$$

$$(\underline{b} \times \underline{n} = -\underline{t})$$

$$\frac{d\underline{n}}{ds} = \underline{n}' = \tau \underline{b} - \kappa \underline{t}$$



Example: To prove that  $T = \frac{1}{K^2} (r' \cdot r'' \cdot r''')$

Sol

Since  $\frac{dr}{ds} = \underline{t} \Rightarrow r' = \underline{t}$

$\frac{dt}{ds} = r'' = K \underline{n}$

and  $\frac{d^2t}{ds^2} = \cancel{K' \underline{n}} + K \frac{dn}{ds}$   
 $= K' \underline{n} + K (\tau \underline{b} - K \underline{t})$

In the notation of scalar triple product

$$\begin{aligned} r' \cdot r'' \times r''' &= (r' \cdot r'' \cdot r''') = (\underline{t} \cdot K \underline{n} \cdot (K' \underline{n} + K (\tau \underline{b} - K \underline{t}))) \\ &= \{ \underline{t} \cdot (K \underline{n}) \times (2K' + K \tau \underline{b} - K^2 \underline{t}) \} \\ &= \{ \underline{t} \cdot K \underline{n} \times \underline{n} K' \} + \{ \underline{t} \cdot K \underline{n} \times K \tau \underline{b} \} \\ &\quad - \{ \underline{t} \cdot K \underline{n} \times K^2 \underline{t} \} = 0 + K^2 \tau (\underline{t} \cdot \underline{n} \times \underline{b}) + 0 \\ &= K^2 \tau \cdot (1) \end{aligned}$$

hence the value of Torsion is given by  $\underline{n} \times \underline{b} = \underline{t}$

$T = \frac{1}{K^2} (r' \cdot r'' \cdot r''')$  Q.E.D

Def Radius of Torsion

The reciprocal of the Torsion is defined as the radius of Torsion and is denoted by  $\sigma$

Thus  $\sigma = \frac{1}{T}$ . But there is no circle of torsion or centre of torsion associated with the curve in the same way as the circle or centre of curvature.

02/20/19

Example The circular Helix

This is a curve drawn on the surface of circular cylinder cutting the generators at the constant angle  $\beta$ . The position vector  $\underline{r}$  of a point on the curve may be expressed as

$\underline{r} = a \cos \theta \underline{i} + a \sin \theta \underline{j} + a \theta \cot \beta \underline{k}$

Dif wrt  $\theta$ , we have

$\dot{r} = \frac{dr}{ds} = \underline{t} = a(-\sin\theta, \cos\theta, \cot\beta) \dot{\theta}$   
 but this is a unit vector so that its square is unity and therefore,  $|\underline{t}|^2 = 1 \Rightarrow a^2 \dot{\theta}^2 = \sin^2\beta$   
 Thus  $\dot{\theta}$  is constant. To find the curvature we have, on diff  $\underline{t}$  wrt  $s$

$$K \underline{n} = \underline{r}'' = -a(\cos\theta, \sin\theta, 0) \dot{\theta}^2$$

Thus the principal normal is ~~vector~~ the unit vector  $\underline{n} = -(\cos\theta, \sin\theta, 0)$

$$\therefore K = a \dot{\theta}^2 = \frac{1}{a} \sin^2\beta$$

To find the Torsion, we have

$$\underline{r}''' = a(\sin\theta, -\cos\theta, 0) \dot{\theta}^3$$

& therefore,  $\underline{r}'' \times \underline{r}''' = a^2(0, 0, 1) \dot{\theta}^5$

$$\text{Hence } K^2 \tau = [\underline{r}' \ \underline{r}'' \ \underline{r}'''] = a^3 \cot\beta \dot{\theta}^6$$

On putting the value of  $K$  and  $\dot{\theta}$ , we have

$$\tau = \frac{1}{a} \sin\beta \cos\beta$$

Thus the curvature and Torsion are both constant & therefore, their ratio is constant.

II/03 Ex. on Page (18.)

Q(1) Prove that  $\underline{r}''' = K' \underline{n} - K^2 \underline{t} + K\tau \underline{b}$  & hence

$$\text{Find } \underline{r}'''' = (K'' - K^3 - K\tau^2) \underline{n} - 3KK' \underline{t} + (2K'\tau + \tau K') \underline{b}$$

Solution &

$$\text{Let } \underline{r} = \underline{r}(s)$$

$$\underline{r}' = \frac{dr}{ds} = \underline{t}$$

$$\underline{r}'' = \frac{d\underline{t}}{ds} = \frac{d^2 \underline{r}}{ds^2} \quad \text{---}$$

$$\text{also } \underline{r}'' = K \underline{n}$$

$$\underline{r}''' = \frac{d^3 \underline{r}}{ds^3} = \frac{d}{ds}(K \underline{n}) = K' \underline{n} + \underline{n} K'$$

$$= K[\tau \underline{b} - K \underline{t}] + \underline{n} K'$$

$$= K\tau \underline{b} - K^2 \underline{t} + \underline{n} K' = K' \underline{n} - K^2 \underline{t} + K\tau \underline{b}$$

For  $\underline{h}'''' = \frac{d^4 \underline{h}}{ds^4} = \frac{d}{ds} \left( \frac{d^3 \underline{h}}{ds^3} \right)$

$$\begin{aligned} \underline{n}' &= \underline{\tau} \underline{b} - \underline{k} \underline{t} \\ \underline{t}' &= \underline{k} \underline{n} \\ \underline{b}' &= -\underline{n} \underline{\tau} \end{aligned}$$

$$= \frac{d}{ds} ( \underline{k}' \underline{n} - \underline{k}^2 \underline{t} + \underline{k} \underline{\tau} \underline{b} )$$

$$= \underline{k}'' \underline{n} + \underline{k}' \underline{n}' - \underline{k}^2 \underline{t}' - 2 \underline{k} \underline{k}' \underline{t} + \underline{k}' \underline{\tau} \underline{b} + \underline{k} \underline{\tau}' \underline{b} + \underline{k} \underline{\tau} \underline{b}'$$

$$= \underline{k}'' \underline{n} + \underline{k}' ( \underline{\tau} \underline{b} - \underline{k} \underline{t} ) - \underline{k}^2 ( \underline{k} \underline{n} ) - 2 \underline{k} \underline{k}' \underline{t} + \underline{k}' \underline{\tau} \underline{b} + \underline{k} \underline{\tau}' \underline{b} + \underline{k} \underline{\tau} \underline{b}'$$

$$= \underline{k}'' \underline{n} + \underline{k}' ( \underline{\tau} \underline{b} - \underline{k} \underline{t} ) - \underline{k}^3 ( \underline{n} ) - 2 \underline{k} \underline{k}' \underline{t} + \underline{k}' \underline{\tau} \underline{b} + \underline{k} \underline{\tau}' \underline{b} - \underline{k} \underline{\tau} ( -\underline{n} \underline{\tau} )$$

$$= \underline{k}'' \underline{n} - \underline{k} \underline{n} - \underline{k} \underline{\tau}^2 \underline{n} - 3 \underline{k} \underline{k}' \underline{t} + 2 \underline{k}' \underline{\tau} \underline{b} + \underline{k} \underline{\tau}' \underline{b}$$

$$= ( \underline{k}'' - \underline{k}^3 - \underline{k} \underline{\tau}^2 ) \underline{n} - 3 \underline{k} \underline{k}' \underline{t} + ( 2 \underline{k}' \underline{\tau} + \underline{\tau}' \underline{k} ) \underline{b}$$

Q(2) as Q(1) Prove that  $\underline{h}' \cdot \underline{h}'' = 0$

~~$\underline{h}'' \cdot \underline{h}''' = \underline{k} \underline{k}'' + 2 \underline{k}^2 \underline{k}' + \underline{k}^2 \underline{\tau} \underline{\tau}' + \underline{k} \underline{k} \underline{\tau}^2$~~

$\underline{h}'' \cdot \underline{h}''' = \underline{k} ( \underline{k}'' - \underline{k}^3 - \underline{k} \underline{\tau}^2 )$        $\underline{h}' \cdot \underline{h}'''' = -3 \underline{k} \underline{k}'$

Q(3) If the  $n$ th Derivative of  $\underline{z}$  w.r.t.  $S$  is given by  $\underline{z}^{(n)} = a_n \underline{t} + b_n \underline{n} + c_n \underline{b}$  ——— (1)

Prove the Reduction formulae.

$$\begin{aligned} a_{n+1} &= a_n' - \underline{k} b_n \\ b_{n+1} &= b_n' + \underline{k} a_n - \underline{\tau} c_n \\ c_{n+1} &= c_n' + \underline{\tau} b_n \end{aligned}$$

Solution

From Given formula, we can write

$$\underline{z}^{(n+1)} = a_{n+1} \underline{t} + b_{n+1} \underline{n} + c_{n+1} \underline{b} \quad \text{--- (2)}$$

Diff (2) w.r.t.  $S$

$$\begin{aligned} \underline{z}^{(n+1)} &= a_n \frac{d\underline{t}}{ds} + \underline{t} a_n' + b_n \frac{d\underline{n}}{ds} + \underline{n} (b_n') + c_n \frac{d\underline{b}}{ds} + \underline{b} c_n' \\ &= a_n ( \underline{k} \underline{n} ) + \underline{t} a_n' + b_n ( \underline{\tau} \underline{b} - \underline{k} \underline{t} ) + \underline{n} b_n' + c_n ( -\underline{n} \underline{\tau} ) + \underline{b} c_n' \end{aligned}$$

$$= \underline{n} (a_n k + b'_n + T C_n) + t (a'_n + k b_n) + \underline{b} (\underline{c}'_n + T \underline{b}_n)$$

Compare coeffs in (A) & (B)

$$a_{n+1} = a'_n - k b_n$$

$$b_{n+1} = b'_n + k a_n - T C_n$$

$$c_{n+1} = c'_n + T b_n$$

as required

Q(4) i) If  $k$  is zero at all pts, the curve is a st-line  
 1999 ii) If  $T$  is zero at all pts, the curve is plane

The necessary and sufficient condition that the curve is plane is  $(r' r'' r''') = 0$

Solution - Using Serret & Frenet formulas

$$\underline{t}' = k \underline{n}$$

$$\text{If } k = 0 \text{ then } \underline{t}' = 0$$

$$\Rightarrow \underline{t} = \text{constant}$$

Tangent is fixed, it is possible only when curve is st-line

$$(ii) \text{ Also } \underline{b}' = -T \underline{m}$$

$$\text{if } T = 0 \text{ then } \underline{b}' = 0$$

which is possible only  $\Rightarrow \underline{b}$  is constant when curve is plane.

(iii) Necessary condition

Suppose curve be plane then  $T = 0$   
 then we know that  $(r' r'' r''') = 0$

$$\text{as } T = \frac{(r' r'' r''')}{k^2} = 0$$

$$\Rightarrow 0 \Rightarrow (r' r'' r''') = 0$$

Curve is plane

Cond is sufficient if  $(r' r'' r''') = 0$  then

$$\text{Curve is plane} \\ \text{then } (r' r'' r''') = 0 \Rightarrow T = \frac{(r' r'' r''')}{k^2} = 0 \\ T = 0 \text{ curve is plane}$$

Q(5) Prove that  $\underline{t}' \cdot \underline{b}' = -KT$

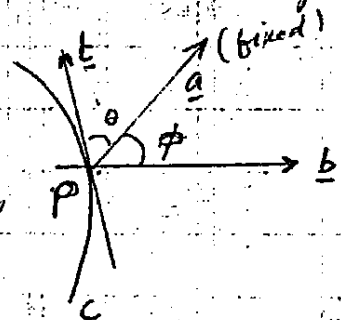
Since  $\frac{d\underline{t}}{ds} = K\underline{n}$  &  $\frac{d\underline{b}}{ds} = -T\underline{n}$

$$\begin{aligned} \therefore \underline{t}' \cdot \underline{b}' &= K\underline{n} \cdot -T\underline{n} \\ &= -KT \underline{n} \cdot \underline{n} \\ &= -KT (1) \end{aligned}$$

Q(6) If the Tangent and the Binormal at a point of a curve make angle  $\theta$  and  $\phi$  resp with a fixed direction, then

sol  $\frac{\sin \theta d\theta}{\sin \phi d\phi} = -K/T$

Let  $C$  be a given curve. Let  $\underline{t}$  and  $\underline{b}$  be unit tangent and unit binormal at  $P$ . Suppose  $\underline{a}$  be a unit vector along any fixed direction and  $\theta$  &  $\phi$  are angles of  $\underline{t}$  and  $\underline{b}$  with it.



then  $\underline{a} \cdot \underline{t} = \cos \theta \quad \text{--- (1)}$

$\underline{a} \cdot \underline{b} = \cos \phi \quad \text{--- (2)}$

$|\underline{t}| = |\underline{a}| = |\underline{b}| = 1$

Diff (1) & (2) wrt  $s$

$\underline{t}' \cdot \underline{a} = -\sin \theta \frac{d\theta}{ds} \Rightarrow K\underline{n} \cdot \underline{a} = -\sin \theta \frac{d\theta}{ds} \quad \text{--- (3)}$

$\underline{b}' \cdot \underline{a} = -\sin \phi \frac{d\phi}{ds} \Rightarrow -T\underline{n} \cdot \underline{a} = -\sin \phi \frac{d\phi}{ds} \quad \text{--- (4)}$

Dividing (3) by (4)

$$\frac{K (\underline{n} \cdot \underline{a})}{-T (\underline{n} \cdot \underline{a})} = \frac{-\sin \theta \frac{d\theta}{ds}}{-\sin \phi \frac{d\phi}{ds}} \Rightarrow \frac{\sin \theta d\theta}{\sin \phi d\phi} = -\frac{K}{T}$$

Q(7) Show that the Principal normals at consecutive pts do not intersect unless  $T=0$

Sol Suppose  $P$  &  $Q$  be two consecutive pts with p.v.s  $\underline{r}$  &  $\underline{r} + d\underline{r}$  and unit principal normals be  $\underline{n}$  &  $\underline{n} + d\underline{n}$ . For intersections of the principal normals, the necessary condition is that the three vectors,  $d\underline{r}$ ,  $\underline{n}$  and  $\underline{n} + d\underline{n}$  be coplanar.

20. That  $\underline{t}'$ ,  $\underline{n}$ ,  $\underline{n}'$  be coplanar, this requires

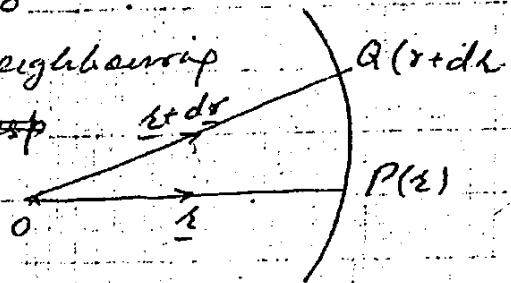
$$\Rightarrow [\underline{t}, \underline{n}, \underline{Tb - kt}] = 0 \quad \left| \begin{array}{l} \underline{t}' = \underline{t} \\ \underline{n}' = \underline{Tb - kt} \end{array} \right.$$

$$\underline{T} [\underline{t}, \underline{n}, \underline{b}] = 0 \quad [\underline{t}, \underline{n}, \underline{b}] \neq 0$$

$$\Rightarrow \underline{T} = 0 \quad \left( \text{which holds only when } \underline{T} = 0 \right)$$

Q(8) Prove that the shortest distance between the principal normal at consecutive pts, distant  $s$  & apart is  $\frac{\rho ds}{\sqrt{\rho^2 + \sigma^2}}$  and that it divides the radius of curvature in the ratio  $\rho^2 : \sigma^2$ .

Sol. Let  $P$  and  $Q$  be two neighbouring pts with p.vectors  $\underline{t}$  and  $\underline{t} + d\underline{t}$  resp and  $\underline{n}$  and  $\underline{n} + d\underline{n}$  be unit Principal normals at  $P$  &  $Q$  resp.



The vector  $\perp$  to both  $\underline{n}$  &  $\underline{n} + d\underline{n}$  is  $\underline{n} \times (\underline{n} + d\underline{n})$

$$\begin{aligned} \text{then } \underline{n} \times (\underline{n} + d\underline{n}) &= \underline{n} \times \underline{n} + \underline{n} \times d\underline{n} \\ &= 0 + \underline{n} \times d\underline{n} = \underline{n} \times \frac{d\underline{n}}{ds} ds \\ &= \underline{n} \times (\underline{Tb} - k\underline{t}) ds \quad \left| \because \frac{d\underline{n}}{ds} = \underline{Tb} - k\underline{t} \right. \\ &= [\underline{T}(\underline{n} \times \underline{b}) - k(\underline{n} \times \underline{t})] ds \\ &= [\underline{T}(\underline{t}) - k(-\underline{b})] ds \\ &= (\underline{T}\underline{t} + k\underline{b}) ds \end{aligned}$$

This is the vector  $\perp$  to both  $\underline{n}$  and  $\underline{n} + d\underline{n}$ . To find its unit vector, let  $\hat{e}$  be unit vector along it, then

$$\begin{aligned} \hat{e} &= \frac{(\underline{T}\underline{t} + k\underline{b}) ds}{|(\underline{T}\underline{t} + k\underline{b}) ds|} \\ &= \frac{(\underline{T}\underline{t} + k\underline{b}) ds}{\sqrt{\underline{T}^2 + k^2} ds} \Rightarrow \hat{e} = \frac{\underline{T}\underline{t} + k\underline{b}}{\sqrt{\underline{T}^2 + k^2}} \end{aligned}$$

is the unit vector  $\perp$  to both  $\underline{n}$  &  $\underline{n} + d\underline{n}$ .

To find shortest distance between two Principal normals at  $P$  &  $Q$ .

$$\begin{aligned} \text{Shortest distance} &= \text{Projection of } d\underline{s} \text{ upon } \hat{e} \\ &= \hat{e} \cdot d\underline{r} \end{aligned}$$

$$\begin{aligned}
 S.D. &= (\hat{e} \cdot \frac{dr}{ds}) ds = (\hat{e} \cdot \underline{t}) ds \\
 &= \left[ \frac{(\tau \underline{t} + \kappa \underline{b}) \cdot \underline{t}}{\sqrt{\tau^2 + \kappa^2}} \right] ds \\
 &= \left[ \frac{\tau (\underline{t} \cdot \underline{t}) + \kappa (\underline{b} \cdot \underline{t})}{\sqrt{\tau^2 + \kappa^2}} \right] ds
 \end{aligned}$$

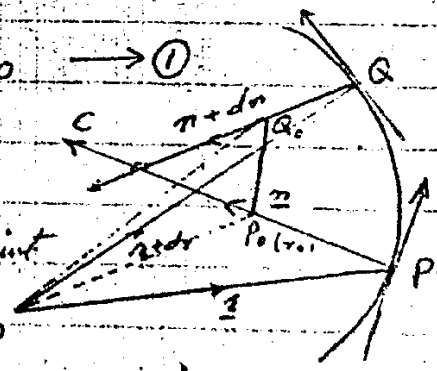
Put  $\tau = \frac{1}{\rho}$   
 $\kappa = \frac{1}{\rho}$

$$\begin{aligned}
 &= \left( \frac{\tau + \kappa(0)}{\sqrt{\tau^2 + \kappa^2}} \right) ds \\
 S.D. &= \frac{\frac{1}{\rho} ds}{\sqrt{\frac{1}{\rho^2} + \frac{1}{\rho^2}}} = \frac{1}{\rho} \frac{ds}{\sqrt{2}}
 \end{aligned}$$

For (ii) Suppose the line of shortest distance meet the unit principal normal  $\underline{n}$  at  $P_0$  and  $\underline{n} + d\underline{n}$  at  $Q_0$ , then the vectors  $\vec{QP_0}$ ,  $\vec{QQ_0}$  and  $\vec{P_0Q_0}$  - ~~then the vectors  $\vec{QP_0}$ ,  $\vec{QQ_0}$~~  are coplanar.

then  $[\vec{QP_0} \vec{QQ_0} \vec{P_0Q_0}] = 0 \rightarrow (1)$   
 (Scalar Triple product)

If  $C$  is the centre of curvature of the circle at point  $P$  of the curve, then



To show that  $\frac{CP_0}{P_0P} = \frac{\tau^2}{\kappa^2} = \frac{\rho^2}{\sigma^2}$  
 $\begin{cases} \tau = \frac{1}{\rho} \\ \kappa = \frac{1}{\rho} \end{cases}$

Since  $\vec{QQ_0}$  is  $\parallel$  to  $\underline{n} + d\underline{n}$  and the vector  $\vec{P_0Q_0}$  is  $\parallel$  to the vector  $\perp$  to both  $\underline{n}$  and  $\underline{n} + d\underline{n}$  i.e. unit vector  $\underline{e}$ .

then if  $\underline{r_0}$  is p.v. of  $P_0$ , then  $\vec{QP_0} = \underline{r_0} - (\underline{r} + d\underline{r})$  and  $\vec{QQ_0}$  is along  $\underline{n} + d\underline{n}$  and  $\vec{P_0Q_0}$  is along  $(\tau \underline{t} + \kappa \underline{b}) ds$

By putting values of all vectors in eq (1), we have

$$[\underline{r_0} - (\underline{r} + d\underline{r}) \quad \underline{n} + d\underline{n} \quad (\tau \underline{t} + \kappa \underline{b}) ds] = 0$$

Now eq. of Principal normal at  $P$  is  $\rightarrow (2)$

$R = \underline{t} + U \underline{n}$  & since  $P_0(\underline{r_0})$  is on this line, therefore

$$\underline{r}_0 = \underline{r} + U_0 \underline{n} \quad \text{where } U_0 = |\underline{P}_0 \underline{P}|$$

Hence from eq (i)

$$\left[ \underline{k} + U_0 \underline{n} - \underline{k} - d\underline{k} \quad \underline{n} + d\underline{n} \quad (\underline{T} + \underline{k}) ds \right] = 0$$

$$\left[ U_0 \underline{n} - d\underline{k} \quad \underline{n} + d\underline{n} \quad (\underline{T} + \underline{k}) ds \right] = 0$$

$$\text{or } \left[ U_0 \underline{n} - \frac{d\underline{k}}{ds} ds \quad \underline{n} + \frac{d\underline{n}}{ds} ds \quad (\underline{T} + \underline{k}) ds \right] = 0$$

$$\text{or } \left[ U_0 \underline{n} - \underline{k} ds \quad \underline{n} + (\underline{T} - \underline{k}) ds \quad (\underline{T} + \underline{k}) ds \right] = 0$$

$$\begin{vmatrix} \textcircled{1} & \textcircled{2} & \textcircled{3} \\ -ds & U_0 & 0 \\ -k ds & 1 & T ds \\ T ds & 0 & k ds \end{vmatrix} = 0$$

$$(ds)^2 \begin{vmatrix} -1 & U_0 & 0 \\ -k & 1 & T \\ T & 0 & k \end{vmatrix} = 0 \Rightarrow \text{if } (ds)^2 \neq 0$$

Then

$$\begin{vmatrix} -1 & U_0 & 0 \\ -k & 1 & T \\ T & 0 & k \end{vmatrix} = 0 \quad -1(k) - U_0(-k^2 - T^2) = 0$$

$$k = U_0(k^2 + T^2)$$

$$U_0 = \frac{k}{k^2 + T^2}$$

So then  $U_0 = |\underline{P}_0 \underline{P}| = \frac{k}{k^2 + T^2}$

Now from figure  $\vec{CP}_0 = \vec{CP} - \vec{PP}_0$

$$= \underline{P} - U_0$$

$$= \frac{1}{k} - \frac{k}{k^2 + T^2}$$

Hence

$$\frac{\vec{CP}_0}{\vec{PP}_0} = \frac{T^2}{k(k^2 + T^2)} \cdot U_0$$

$$= \frac{T^2}{k(k^2 + T^2)} \cdot \frac{k}{k^2 + T^2} = \frac{T^2}{k^2} = \frac{P^2}{\sigma^2}$$

Hence the result.



Q(9) Prove that  $b'' = T(\kappa t - T b) - T' n$   
 and find similar expression for  $b'''$  and  $n'''$ .

Solution

Since  $b' = -T n$   
 diff wrt  $s$   

$$b'' = -T' n - T n'$$

$$= -T' n - T(\kappa t - T b)$$

again Diff wrt  $s$

$$b''' = T'(\kappa t - T b) + T(\kappa t' + \kappa t' - T' b - T b')$$

$$- T'' n - T' n'$$

$$= T'(\kappa t - T b) + T[(\kappa t' - T' b) + \kappa(T b - \kappa t) - T(-T n)]$$

$$- T'' n - T'(\kappa t - T b)$$

$$= T' \kappa t - T T' b + T \kappa t' - T T' b + \kappa T^2 b - \kappa^2 T t$$

$$+ T^2 n + T^2 n = T'' n - T T' b + \kappa T' t$$

$$= 2 T' \kappa t - 3 T T' b + T \kappa t' + \kappa T^2 b - \kappa^2 T t$$

$$+ T^2 n - T'' n$$

$$= (2 \kappa T' + T \kappa' - \kappa^2 T) t + (\kappa T^2 - 3 T T') b + (T^2 - T'') n$$

Again  $n' = T b - \kappa t$   
 diff wrt  $s$ , we have

$$n'' = T b' + T' b - \kappa' t - \kappa t'$$

$$= T' b - \kappa' t + T(-T n) - \kappa(\kappa n)$$

$$= T' b - \kappa' t - T^2 n - \kappa^2 n$$

$$= -\kappa' t + T' b - (T^2 + \kappa^2) n$$

Similarly for  $n'''$

Q(10)

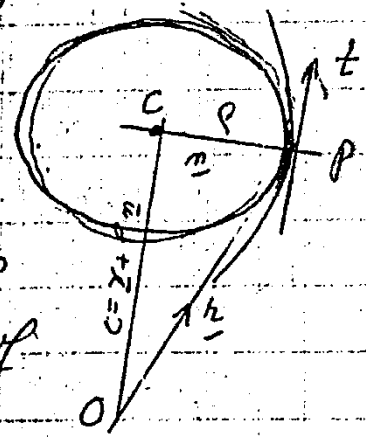
Def. SKEW CURVATURE

The arc rate of turning of the Principal normal  $\underline{n}$  is called the skew curvature denoted as  $\frac{d\underline{n}}{ds} = \underline{\dot{n}}$  and its magnitude is the modulus of  $\underline{\dot{n}}$ .

Since  $\frac{d\underline{n}}{ds} = \tau \underline{b} - \kappa \underline{t}$ , the mag. of skew curvature is  $\sqrt{\tau^2 + \kappa^2} = |\underline{\dot{n}}|$

Centre of Curvature

The centre of curvature at P is the point of intersection of Principal normal at P with the normal at the consecutive pt P' which lies in the Osculating plane at P



Let  $\underline{c}$  be p.v. of centre of curvature and  $\underline{r}$  be p.v. of P w.r.t O. Then

$\underline{c} = \underline{r} + \rho \underline{n}$  where  $\rho$  is the radius of curvature. The tangent to its locus being parallel to  $\frac{d\underline{c}}{ds}$ , is therefore parallel to

$$\frac{d\underline{c}}{ds} = \underline{c}' = \frac{d\underline{r}}{ds} + \rho \frac{d\underline{n}}{ds} + \rho' \underline{n}$$

$$= \underline{t} + \rho(\tau \underline{b} - \kappa \underline{t}) + \rho' \underline{n}$$

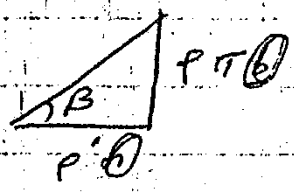
$$= \underline{t} + \rho \tau \underline{b} - \rho \kappa \underline{t} + \rho' \underline{n}$$

$$= \rho' \underline{n} + \rho \tau \underline{b}$$

$$\frac{\kappa}{\rho} = \frac{1}{\rho} \\ \rho \kappa = 1$$

It is therefore, lies in the normal plane of the original curve. Tangent is inclined to  $\underline{n}$  at an angle  $\beta$  s.t.  $\tan \beta = \frac{\rho \tau}{\rho'}$

$$\tan \beta = \frac{\tau}{\rho'}$$



Q(9) If the position vector  $\underline{r}$  of the current point is a function of any parameter  $u$  and dashes denotes Diff wrt  $u$ . Then show that

(i)  $\underline{r}' = s' \underline{t}$  (ii)  $\underline{r}'' = s'' \underline{t} + \kappa \dot{s}' \underline{n}$  and

(iii)  $\underline{r}''' = (s''' - \kappa^2 \dot{s}'^3) \underline{t} + (3\kappa s'' + \kappa \dot{s}'^2) \underline{n} + (\kappa \tau \dot{s}'^3) \underline{b}$

Solution (i)  $\underline{r}' = \frac{d\underline{r}}{du} = \frac{d\underline{r}}{ds} \frac{ds}{du} = \underline{t} s'$  (i)  $\underline{b} = \frac{\underline{r}' \times \underline{r}''}{\kappa (s')^3}$  (ii)  $\kappa^2 = \frac{r''^2 - s''^2}{s'^4}$  &  $\tau = \frac{r' \cdot r'''}{\kappa^2 s'^6}$

(ii)  $\underline{r}'' = \frac{d}{du} (\underline{t} s')$

$= \frac{d}{ds} (\underline{t} s') \frac{ds}{du} = \underline{t}' (s')^2 + \underline{t} s''$   $\frac{d}{du} (\underline{t} s') = \frac{d}{ds} (\underline{t} \frac{ds}{du})$   
 $(+ \underline{t} s'')$

$= \kappa \underline{n} (s')^2 + \underline{t} s''$

and (iii)

$\underline{r}''' = \frac{d}{du} (\underline{t} s'' + \kappa \underline{n} (s')^2)$

$= s''' \underline{t} + s'' \frac{d\underline{t}}{ds} + \kappa (\dot{s}')^2 \underline{n} + 2\kappa \dot{s}' s'' \underline{n}$

$+ \kappa (s')^2 \frac{d\underline{n}}{ds}$


$= s''' \underline{t} + s'' \underline{t}' \frac{ds}{du} + \kappa (\dot{s}')^2 \underline{n} + 2\kappa \dot{s}' s'' \underline{n}$

$+ \kappa s'' \frac{d\underline{n}}{ds} \frac{ds}{du}$

$= s''' \underline{t} + s' s'' \underline{t}' + \kappa (\dot{s}')^2 \underline{n} + 2\kappa \dot{s}' s'' \underline{n} + \kappa (\dot{s}')^3 \underline{n}$

$= s''' \underline{t} + s s'' (\kappa \underline{n}) + \kappa (\dot{s}')^2 \underline{n} + 2\kappa s s'' \underline{n} + \kappa (\dot{s}')^2 (\tau \underline{b} - \kappa \underline{t})$

$= (s''' - \kappa^2 \dot{s}'^3) \underline{t} + s' (3\kappa s'' + \kappa \dot{s}'^2) \underline{n} + \kappa \tau \dot{s}'^3 \underline{b}$

To find  $\underline{r}' \times \underline{r}'' = s' \underline{t} \times (s'' \underline{t} + \kappa \dot{s}'^2 \underline{n})$  

$= 0 + s' \kappa \dot{s}'^2 (\underline{t} \times \underline{n}) = \kappa (s')^3 \underline{b}$

$\underline{b} = \frac{\underline{r}' \times \underline{r}''}{\kappa (s')^3}$  (Proved)

To prove  $s' \underline{r}'' - s'' \underline{r}' = s' (s'' \underline{t} + \kappa \dot{s}'^2 \underline{n}) - s'' s' \underline{t}$

$= \kappa (\dot{s}')^2 \underline{n}$

$\underline{n} = \frac{s' \underline{r}'' - s'' \underline{r}'}{\kappa \dot{s}'^2}$  Similarly for  $\kappa^2 = \frac{r''^2 - s''^2}{s'^4}$

& others

$\tau = \frac{r' \cdot r'''}{\kappa^2 s'^6}$

Exercise 10 For the curve

$$x = 4a \cos^3 u, \quad y = 4a \sin^3 u, \quad z = 3c \cos 2u$$

Prove that  $\underline{n} = (\sin u \cos u, 0)$

Sol  $\quad \underline{k} = \frac{a}{6(a^2+c^2) \sin 2u}$

Let  $\underline{r} = (4a \cos^3 u, 4a \sin^3 u, 3c \cos 2u)$

$$\frac{d\underline{r}}{ds} = (-12a \cos^2 u \sin u, 12a \sin^2 u \cos u, -6c \sin 2u) \frac{du}{ds}$$

$$\underline{t} = -6 \sin 2u (-a \cos u, a \sin u, -c) \frac{du}{ds} \quad (1)$$

$$\underline{t} \cdot \underline{t} = 36 \sin^2 2u (a^2 \cos^2 u + a^2 \sin^2 u + c^2) \left(\frac{du}{ds}\right)^2$$

$$1 = 36 \sin^2 2u (a^2 + c^2) \left(\frac{du}{ds}\right)^2$$

$$\left(\frac{du}{ds}\right)^2 = \frac{1}{36 \sin^2 2u (a^2 + c^2)} \Rightarrow \frac{du}{ds} = \frac{1}{6\sqrt{a^2+c^2} \sin 2u} \rightarrow (2)$$

Put in (1)

$$\underline{t} = \frac{-6 \sin 2u (-a \cos u, a \sin u, -c)}{6\sqrt{a^2+c^2} \sin 2u}$$

$$\underline{t} = \frac{1}{\sqrt{a^2+c^2}} (-a \cos u, a \sin u, -c)$$

again diff w.r.t S

$$\frac{d\underline{t}}{ds} = \frac{1}{\sqrt{a^2+c^2}} (a \sin u, a \cos u, 0) \frac{du}{ds}$$

$$\underline{k} \underline{n} = \frac{1}{\sqrt{a^2+c^2}} \frac{1}{6\sqrt{a^2+c^2} \sin 2u} (a \sin u, a \cos u, 0) \quad (3)$$

$$\underline{k} \underline{n} = \frac{(a \sin u, a \cos u, 0)}{6(a^2+c^2) \sin 2u}$$

$$\Rightarrow \underline{k} \underline{n} \cdot \underline{k} \underline{n} = \frac{a^2 \sin^2 u + a^2 \cos^2 u}{36(a^2+c^2)^2 \sin^2 2u}$$

$$k^2 = \frac{a^2}{36(a^2+c^2)^2 \sin^2 2u} \quad k = \frac{a}{6 \sin 2u (a^2+c^2)}$$

Now from eq (3), we have

$$\underline{\eta} = \frac{1}{K} \frac{1}{\delta \sin u (a^2 + c^2)} (a \delta \sin u, a \cos u, 0)$$

$$= \frac{\delta \sin u (a^2 + c^2) (a \delta \sin u, a \cos u, 0)}{a \delta \sin u (a^2 + c^2)}$$

$$\underline{\eta} = (\sin u, \cos u, 0) \quad (\text{proved})$$

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(12) Find  $K$  and  $T$   $x = a(u - \sin u)$

$$y = a(1 - \cos u)$$

$$z = bu$$

Sol.

$$\text{Let } \underline{r} = (a(u - \sin u), a(1 - \cos u), bu)$$

Diff wrt  $u$

$$\underline{\dot{r}} = (a(1 - \cos u), a \sin u, b) \quad \text{--- (1)}$$

$$|\dot{r}| = \sqrt{a^2(1 - \cos u)^2 + a^2 \sin^2 u + b^2}$$

$$= \sqrt{b^2 + 2a^2(1 - \cos u)}$$

Again Diff (1) wrt  $u$

$$\underline{\ddot{r}} = (a \sin u, a \cos u, 0) \quad \text{--- (2)}$$

$$\text{Then } \underline{\dot{r}} \times \underline{\ddot{r}} = \begin{vmatrix} i & j & k \\ a(1 - \cos u) & a \sin u & b \\ a \sin u & a \cos u & 0 \end{vmatrix} = -i(0 - ab \cos u) \\ -j(ab \sin u) \\ = (-ab \cos u, ab \sin u, a^2(\cos u - 1)) \quad \left( \begin{matrix} \leftarrow a^2 \cos u \\ \leftarrow a^2 \sin u \end{matrix} \right)$$

$$|\dot{r} \times \ddot{r}| = \sqrt{a^2 b^2 \cos^2 u + a^2 b^2 \sin^2 u + a^4 (\cos u - 1)^2}$$

$$= a \sqrt{b^2 + a^2 (\cos u - 1)^2}$$

Diff eq (ii) wrt  $u$

$$\underline{\ddot{\ddot{r}}} = (a \cos u, -a \sin u, 0)$$

$$K = \frac{|\dot{r} \times \ddot{r}|}{|\dot{r}|^3} \\ = \frac{a \sqrt{b^2 + a^2 (\cos u - 1)^2}}{(b^2 + 2a^2(1 - \cos u))^{3/2}}$$

$$\text{Also } \{i \ \dot{r} \ \ddot{r}\} = -ab$$

$$T = \frac{-ab}{a^3 (b^2 + a^2 (\cos u - 1)^2)}$$

$$\text{When } T = \frac{\{i \ \dot{r} \ \ddot{r}\}}{(\dot{r} \times \ddot{r})^2}$$

Q(13) If the plane of curvature at every point of a curve passes through a fixed pt, show that curve is plane.

Solution: The equation of plane of curvature (Osculating plane) at a point P with p.v.  $\underline{\xi}$  is given as  $(\underline{R} - \underline{\xi}) \cdot \underline{b} = 0$

Let  $R_0$  be a fixed pt, then  $R_0$  satisfies the above eq  $(R_0 - \underline{\xi}) \cdot \underline{b} = 0$  — (1)

Diff wrt  $s$

$$(0 - \frac{d\underline{\xi}}{ds}) \cdot \underline{b} + (R_0 - \underline{\xi}) \cdot \frac{d\underline{b}}{ds} = 0$$

$$-\underline{\xi}' \cdot \underline{b} + (R_0 - \underline{\xi}) \cdot \underline{b}' = 0 \quad \underline{t} \cdot \underline{b} = 0$$

$$-\underline{t} \cdot \underline{b} + (R_0 - \underline{\xi}) \cdot (-T\underline{n}) = 0$$

$$0 + (R_0 - \underline{\xi}) \cdot (-T\underline{n}) + \underline{\xi} \cdot T\underline{n} = 0$$

$$-T(R_0 - \underline{\xi}) \cdot \underline{n} = 0$$

If  $T \neq 0$  then  $(R_0 - \underline{\xi}) \cdot \underline{n} = 0$

$\Rightarrow R_0 - \underline{\xi}$  is  $\perp$  to  $\underline{n}$ . } also from equation (1)  $(R_0 - \underline{\xi})$  is  $\perp$  to  $\underline{b}$  } — (2)

From these results, we conclude that

$(R_0 - \underline{\xi})$  is  $\parallel$  to  $\underline{t}$

Therefore,  $(R_0 - \underline{\xi}) = \lambda \underline{t}$   $\lambda$  is real no.

Then  $\underline{R_0} = \underline{\xi} + \lambda \underline{t}$  This is eq of Tangent.

Hence  $R_0$  satisfies eq of Tangent at every pt.

$\Rightarrow R_0$  is the point of intersection of all Tangents to the curve  $\Rightarrow$  curve is a straight line

This is contradiction to our assumption that the curve is not plane.

Hence the curve is a plane.

Q(14) If  $m_1, m_2, m_3$  are the moments about the origin of unit vectors  $\underline{t}, \underline{n}, \underline{b}$  localized in the Tangent-normal & binormal and dashes denotes diff wrt  $s$  we have  $m_1' = \kappa m_2, m_2' = \tau b - \kappa m_1 + \tau m_3, m_3' = -\tau - \tau m_2$

Solution If  $\underline{r}$  is a current point, then by definition of moment of forces about a pt

$$m_1 = \underline{r} \times \underline{t}, \quad m_2 = \underline{r} \times \underline{n} \quad \& \quad m_3 = \underline{r} \times \underline{b}$$

Diff  $m_1 = \underline{r} \times \underline{t}$  wrt  $s$

$$m_1' = \underline{r}' \times \underline{t} + \underline{r} \times \underline{t}'$$

$$= \underline{t} \times \underline{t} + \underline{r} \times (\kappa \underline{n})$$

$$m_1' = 0 + \kappa (\underline{r} \times \underline{n}) = \kappa m_2$$

Diff  $m_2 = \underline{r} \times \underline{n}$  wrt  $s$

$$m_2' = \underline{r}' \times \underline{n} + \underline{r} \times \underline{n}'$$

$$= \underline{t} \times \underline{n} + \underline{r} \times (\tau \underline{b} - \kappa \underline{t})$$

$$= \underline{b} + \tau (\underline{r} \times \underline{b}) - \kappa (\underline{r} \times \underline{t})$$

$$= \underline{b} + \tau m_3 - \kappa m_1$$

Diff  $m_3 = \underline{r} \times \underline{b}$  wrt  $s$

$$m_3' = \underline{r}' \times \underline{b} + \underline{r} \times \underline{b}'$$

$$= \underline{t} \times \underline{b} + \underline{r} \times (-\tau \underline{n})$$

$$= -\underline{n} + \tau \underline{r} \times \underline{n}$$

$$m_3' = -(\underline{n} + \tau m_2)$$

Q(15) Prove that the position vector of the current point on a curve satisfies the diff Eq

$$\frac{d}{ds} \left\{ \sigma \frac{d}{ds} \left( \rho \frac{d^2 \underline{r}}{ds^2} \right) \right\} + \frac{d}{ds} \left( \frac{\sigma}{\rho} \frac{d\underline{r}}{ds} \right) + \frac{\rho}{\sigma} \frac{d^2 \underline{r}}{ds^2} = 0$$

Hint (Use Serret-Frenet Formulae)

Sol Since  $\sigma = 1/\tau$  &  $\rho = 1/\kappa$

$$\text{LHS: } \frac{d}{ds} \left\{ \frac{1}{\tau} \frac{d}{ds} \left( \frac{1}{\kappa} \frac{d^2 \underline{r}}{ds^2} \right) \right\} + \frac{d}{ds} \left[ \frac{\kappa}{\tau} \underline{t} \right] + \frac{\tau}{\kappa} \underline{t}' = 0$$

$$\Rightarrow \frac{d}{ds} \left\{ \frac{1}{\rho} \frac{d}{ds} \left( \frac{1}{\kappa} \kappa \underline{n} \right) \right\} + \frac{d}{ds} \left( \frac{\kappa}{\tau} \underline{t} \right) + \frac{\rho}{\kappa} (\kappa \underline{n})$$

$$\Rightarrow \frac{d}{ds} \left\{ \frac{1}{\tau} \left( \frac{d\underline{m}}{ds} \right) \right\} + \frac{d}{ds} \left( \frac{\kappa}{\tau} \underline{t} \right) + \tau \underline{n}$$

$$= \frac{d}{ds} \left( \frac{1}{\tau} (\tau \underline{b} - \kappa \underline{t}) \right) + \frac{d}{ds} \left( \frac{\kappa}{\tau} \underline{t} \right) + \tau \underline{n}$$

$$\Rightarrow \frac{d\underline{b}}{ds} - \frac{\kappa}{\tau} \frac{d\underline{t}}{ds} + \frac{\kappa}{\tau} \frac{d\underline{t}}{ds} + \tau \underline{n}$$

$$\Rightarrow -\tau \underline{n} - \frac{\kappa}{\tau} \underline{n} + \frac{\kappa}{\tau} \kappa \underline{n} + \tau \underline{n}$$

$$= -\tau \underline{n} + \tau \underline{n} = 0 \quad \text{RHS}$$

Q(16) If  $s_1$  is the arc length of the locus of Centre of curvature, show that  $\frac{ds_1}{ds} = \frac{1}{\kappa} \sqrt{\kappa^2 \tau^2 + \kappa^2}$

Solution

Since  $\underline{t} = \frac{dr}{ds}$ ,  $\underline{b}$ ,  $\underline{n}$  are

Tangent, binormal & normal for the curve  $C$ , Similarly  $\underline{t}_1 = \frac{ds_1}{ds}$ ,  $\underline{b}_1$ ,  $\underline{n}_1$  are Tangent, binormal and normal for the curve formed by the locus of centre of curvature.

The  $\underline{c}$  of locus of centre of curvature is

$$\underline{c} = \underline{t} + \rho \underline{n} \quad \rightarrow \textcircled{1}$$

Diff wrt  $ds$

$$\frac{d\underline{c}}{ds} = \frac{d\underline{t}}{ds} + \rho \frac{d\underline{n}}{ds} + \frac{d\rho}{ds} \underline{n}$$

$$\frac{d\underline{c}}{ds} \cdot \frac{ds_1}{ds} = \underline{t} + \rho (\tau \underline{b} - \kappa \underline{t}) + \rho' \underline{n} \quad \rho = \frac{1}{\kappa}$$

$$t_1 \frac{ds_1}{ds} = \underline{t} + \rho \tau \underline{b} - \frac{\rho}{\kappa} \underline{t} + \rho' \underline{n}$$

$$t_1 \frac{ds_1}{ds} = \rho \tau \underline{b} + \rho' \underline{n} \quad \rightarrow \textcircled{2}$$

Taking dot product of  $\textcircled{2}$  with it-self

$$\left( \frac{ds_1}{ds} \right)^2 (t_1 \cdot t_1) = \rho^2 \tau^2 (\underline{b} \cdot \underline{b}) + (\rho')^2 \underline{n} \cdot \underline{n}$$

$$\left( \frac{ds_1}{ds} \right)^2 = \rho^2 \tau^2 + \rho'^2$$



$$\frac{ds_1}{ds} = \sqrt{\frac{\rho^2}{\sigma^2} + \rho'^2}$$

Let  $\rho = \frac{1}{k}$

$$\frac{d\rho}{ds} = -\frac{1}{k^2} k'$$

$$(\rho')^2 = \frac{1}{k^4} (k')^2 \quad \text{Hence } \frac{ds_1}{ds} = \sqrt{\frac{\rho^2}{\sigma^2} + \frac{k'^2}{k^4}}$$

$$\frac{ds_1}{ds} = \frac{1}{k^2} \sqrt{\tau^2 k^2 + k'^2}$$

Q(17) In the case of a curve of constant curvature. Find the curvature and Torsion of the locus of its centre of curvature  $C$ .

Sol The p.v of  $C$  on the curve of centre of curvature is

$$\underline{C} = \underline{r} + \rho \underline{n} \quad \text{Hence } \rho \text{ is constant.}$$

Diff wrt  $s$

$$d\underline{C} = (\underline{t} + \rho(\underline{T}\underline{b} - \underline{k}\underline{t})) ds$$

$$= (\underline{t} + \rho \underline{T}\underline{b} - \frac{\rho}{k} \underline{t}) ds$$

$$d\underline{C} = (\rho \underline{T}\underline{b}) ds = \frac{\rho}{k} \underline{b} ds$$

$$\text{or } \frac{d\underline{C}}{ds} = \frac{\rho}{k} \underline{b}$$

$$\frac{d\underline{C}}{ds_1} \frac{ds_1}{ds} \Rightarrow t_1 \frac{ds_1}{ds} = \frac{\rho}{k} \underline{b} \rightarrow \textcircled{1}$$

Taking dot product of  $\textcircled{1}$  with itself.

$$\underline{t_1} \cdot \underline{t_1} \left(\frac{ds_1}{ds}\right)^2 = \frac{\rho^2}{k^2} (\underline{b} \cdot \underline{b})$$

$$\left(\frac{ds_1}{ds}\right)^2 = \frac{\rho^2}{k^2} = \rho^2 \tau^2$$

$$\frac{ds_1}{ds} = \rho \tau \rightarrow \textcircled{2}$$

From  $\textcircled{1}$

$$t_1 = \underline{b}$$

Diff last relation w.r.t  $s$

$$\frac{dt_1}{ds} = \frac{d\underline{b}}{ds} = -\underline{T}\underline{n}$$

$$\frac{db_1}{ds} = \frac{db_1}{ds_1} \cdot \frac{ds_1}{ds} = -\tau \underline{n}$$

$$b'_1 = -\tau \underline{n}$$

$$b'_1 = -k_1 \underline{n}_1$$

$$(k_1 \underline{n}_1)(\rho \tau) = -\tau \underline{n}$$

from (ii)

$$k_1 \underline{n}_1 = \frac{-\tau}{\rho}$$

$$k_1 \underline{n}_1 = -k \underline{n} \Rightarrow \boxed{k_1 = k} \quad (iii)$$

$$\& \underline{n}_1 = -\underline{n} \quad (iv)$$

For Torsion,  $b_1 = t_1 \times n_1$

$$= \underline{b} \times \underline{n}_1$$

$$\therefore t_1 = \underline{b}$$

$$= \underline{b} \times (-\underline{n}) = \underline{n} \times \underline{b}$$

$$b_1 = \underline{t}$$

Diff wrt s

$$\frac{db_1}{ds} = \frac{dt}{ds}$$

$$\Rightarrow \frac{db_1}{ds_1} \cdot \frac{ds_1}{ds} = +k \underline{n}$$

$$-\tau \underline{n}_1 \frac{ds_1}{ds} = +k \underline{n}$$

$$\therefore \frac{ds_1}{ds} = \tau/k$$

$$-\tau \underline{n}_1 \tau/k = +k \underline{n}$$

$$-\underline{n}_1 = \underline{n}$$

$$\tau \underline{n} \tau/k = k \underline{n}$$

$$\boxed{\tau = \frac{k^2}{T}}$$

6 (a)

Q (18) Prove that for any curve

$$[t' \ t'' \ t'''] = [r'' \ r''' \ r''']$$

$$\& [b' \ b'' \ b'''] = \tau^3 (k' \tau - k \tau') = \tau^5 \frac{d}{ds} \left( \frac{\tau}{k} \right)$$

Solution: Since  $\frac{dr}{ds} = \underline{t} \Rightarrow r' = \underline{t}$

Diff wrt s

$$r'' = t'$$

& again diff  $r''' = t''$  & again diff  $r^{(iv)} = t'''$

So we have  $[t' \ t'' \ t'''] = [r'' \ r''' \ r^{(iv)}]$

Also, since  $t' = \kappa \underline{m}$

$$\begin{aligned} t'' &= \kappa' \underline{m} + \kappa \underline{m}' \\ &= \kappa' \underline{m} + \kappa (\tau \underline{b} - \kappa \underline{t}) \\ &= \kappa' \underline{m} + \kappa \tau \underline{b} - \kappa^2 \underline{t} \end{aligned}$$

Diff w.r.t  $s$  again

$$\begin{aligned} t''' &= \kappa'' \underline{m} + \kappa' \underline{m}' + \kappa' \tau \underline{b} + \kappa \tau' \underline{b} + \kappa \tau \underline{b}' \\ &= 2\kappa \kappa' \underline{t} - \kappa^2 \underline{t}' \\ &= \kappa'' \underline{m} + \kappa' (\tau \underline{b} - \kappa \underline{t}) + \kappa' \tau \underline{b} + \kappa \tau' \underline{b} + \kappa \tau (-\tau \underline{m}) \\ &\quad - 2\kappa \kappa' \underline{t} - \kappa^2 (-\kappa \underline{m}) \\ &= \kappa'' \underline{m} + \kappa' \tau \underline{b} - \kappa \kappa' \underline{t} + \kappa' \tau \underline{b} + \kappa \tau' \underline{b} - \kappa \tau^2 \underline{m} \\ &\quad - 2\kappa \kappa' \underline{t} + \kappa^3 \underline{m} \\ &= (\kappa'' - \kappa \tau^2 + \kappa^3) \underline{m} - 3\kappa \kappa' \underline{t} + (2\kappa' \tau + \kappa \tau') \underline{b} \end{aligned}$$

Then, we have

$$\begin{aligned} [t', t'', t'''] &= \begin{vmatrix} 0 & \kappa & 0 \\ -\kappa^2 & \kappa' & \kappa \tau \\ -3\kappa \kappa' & \kappa'' - \kappa \tau^2 + \kappa^3 & 2\kappa' \tau + \kappa \tau' \end{vmatrix} \\ &= -\kappa \left[ -\kappa^2 (2\kappa' \tau + \kappa \tau') - \kappa \tau (-3\kappa \kappa') \right] \\ &= -\kappa \left[ \kappa^2 \kappa' \tau - \kappa^3 \tau' \right] \\ &= \kappa^4 \tau' - \kappa^3 \kappa' \tau = \kappa^3 [\kappa \tau' - \kappa' \tau] \quad \text{Q.E.D.} \end{aligned}$$

Also

$$[t', t'', t'''] = \kappa^3 \kappa^2 \left[ \frac{\kappa \tau' - \kappa' \tau}{\kappa^2} \right] = \kappa^5 \frac{d}{ds} \left( \frac{\tau}{\kappa} \right)$$

(ii)

Since  $\underline{b}' = -\tau \underline{m}$

Diff w.r.t  $s$

$$\begin{aligned} \underline{b}'' &= -\tau' \underline{m} - \tau \underline{m}' \\ &= -\tau' \underline{m} - \tau (\tau \underline{b} - \kappa \underline{t}) \\ &= -\tau' \underline{m} - \tau^2 \underline{b} + \kappa \tau \underline{t} \end{aligned}$$

again Diff w.r.t  $s$

$$\begin{aligned}
b''' &= -\tau'' z - \tau' z' - 2\tau z \tau' - \tau^2 b' + k\tau z + k\tau' z \\
&\quad + k\tau z' \\
&= -\tau'' z - \tau'(\tau z - k z) - 2\tau \tau' z - \tau^2(-\tau z) \\
&\quad + k'\tau z + k\tau' z + k\tau k z \\
&= (2k\tau' + k'\tau) z + (k^2\tau - \tau'' + \tau^3) z - 3\tau \tau' z
\end{aligned}$$

Therefore, we have

$$\begin{aligned}
\begin{bmatrix} b' & b'' & b''' \end{bmatrix} &= \begin{bmatrix} 0 & -\tau & 0 \\ k\tau & -\tau' & -\tau^2 \\ 2k\tau' + k'\tau & k^2\tau - \tau'' + \tau^3 & -3\tau\tau' \end{bmatrix} \\
&= \tau \begin{bmatrix} -3k\tau^2\tau' + \tau^2(2k\tau' + k'\tau) \\ -3k\tau^2\tau + 2k\tau^2\tau' + \tau^3 k' \\ k'\tau - k\tau' \end{bmatrix} \\
&= \tau^3 \begin{bmatrix} -3k\tau^2\tau' + \tau^2(2k\tau' + k'\tau) \\ -3k\tau^2\tau + 2k\tau^2\tau' + \tau^3 k' \\ k'\tau - k\tau' \end{bmatrix}
\end{aligned}$$

QED

This can also be written as

$$\begin{aligned}
\begin{bmatrix} b' & b'' & b''' \end{bmatrix} &= \tau^3 \tau^2 \left( \frac{k'\tau - k\tau'}{\tau^2} \right) \\
&= \tau^5 \frac{d}{ds} \left( \frac{k}{\tau} \right) \quad (\text{Proved})
\end{aligned}$$

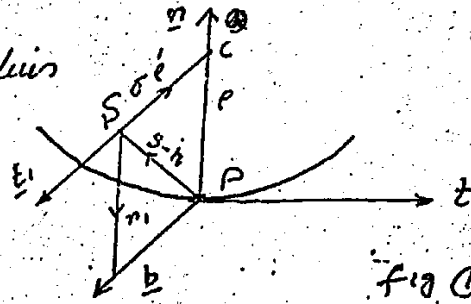
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### § SPHERICAL CURVATURE.

13/3

The sphere of closest contact with the curve at P is that which passes through four points on the curve ultimately coincident with P. This is called the Osculating sphere or the sphere of curvature at P.

Its centre S and radius R are called the centre and radius of spherical curvature.



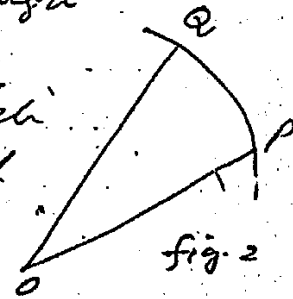
- 1 4 3
- X 9 6
- 7, 8, 10
- 9 10 X
- 12 13 X
- X 15 17
- 18 19 20
- 21 22 X
- 24 25
- 26 27
- 28 29
- 30 31

#### Theorem

To derive an expression for the radius of spherical curvature.

Let  $t$  be the p.v. of P on the curve and  $s$  is the p.v. of centre of the spherical curvature.

Thus the centre of sphere through P and an adjacent point Q on the curve lies on the plane which is the right bisector of PQ and limiting position of this plane is the normal plane at P.



Thus the centre of spherical curvature is the limiting position of the intersection of three normal planes at adjacent pts. Now eq of normal plane at point P( $t$ ) is

$$(s-t) \cdot \underline{t} = 0 \quad \text{--- (1)}$$

Where  $s$  is current pt. on the plane

Diff (1) w.r.t  $s$  (arc length)

$$(s-t) \cdot \frac{dt}{ds} + \frac{ds}{ds} \cdot \underline{t} - \frac{dt}{ds} \cdot \underline{t} = 0$$

$$(s-t) K \underline{n} + \frac{ds}{ds} \cdot \underline{t} - \underline{t} \cdot \underline{t} = 0$$

$$(\underline{s} - \underline{r}) \cdot \kappa \vec{n} + \left( \frac{ds}{ds} \cdot \underline{t} \right) - 1 = 0 \quad \left| \begin{array}{l} \text{As } \underline{s} \text{ is} \\ \text{along } \eta \\ \frac{ds}{ds} \text{ is a} \\ \text{unit vector to} \\ \frac{ds}{ds}, \underline{t} = 0 \end{array} \right.$$

$$(\underline{s} - \underline{r}) \cdot \vec{n} = \frac{1}{\kappa}$$

$$(\underline{s} - \underline{r}) \cdot \underline{n} = \rho \quad \text{--- (2)}$$

Diff wrt  $s$

$$(\underline{s} - \underline{r}) \cdot \frac{d\underline{n}}{ds} + \left( \frac{ds}{ds} - \frac{dr}{ds} \right) \cdot \vec{n} = \rho'$$

$$(\underline{s} - \underline{r}) \cdot (\underline{T} \underline{b} - \kappa \underline{t}) + \frac{ds}{ds} \cdot \vec{n} - \frac{dr}{ds} \cdot \vec{n} = \rho'$$

$$(\underline{s} - \underline{r}) \cdot (\underline{T} \underline{b} - \kappa \underline{t}) + \frac{ds}{ds} \cdot \vec{n} - \underline{t} \cdot \vec{n} = \rho'$$

$$(\underline{s} - \underline{r}) \cdot \underline{T} \underline{b} - (\underline{s} - \underline{r}) \cdot \kappa \underline{t} + 0 - 0 = \rho'$$

$$\Rightarrow \underline{T} (\underline{s} - \underline{r}) \cdot \underline{b} - \kappa (\underline{s} - \underline{r}) \cdot \underline{t} = \rho'$$

$$\underline{T} (\underline{s} - \underline{r}) \cdot \underline{b} - \kappa (0) = \rho' \quad \text{by eq (1)}$$

$$(\underline{s} - \underline{r}) \cdot \underline{b} = \frac{\rho'}{\underline{T}} = \sigma \rho' \quad \text{--- (3)}$$

The vector  $\underline{s} - \underline{r}$  satisfies (1) (2) + (3), then

It is clear that

$$\underline{s} - \underline{r} = \rho \underline{n} + \sigma \rho' \underline{b} \quad \text{--- (4)}$$

$$\underline{s} = \underline{r} + \rho \underline{n} + \sigma \rho' \underline{b}$$

This eq determines the p.v  $\underline{s}$  of the centre of spherical curvature. Now  $\rho \underline{n}$  is the vector  $\vec{PC}$  and therefore,  $\sigma \rho' \underline{b}$  is the vector  $\vec{CS}$ . Therefore, the centre of spherical curvature is on the axis of the circle of curvature at a distance  $\sigma \rho'$  from the centre of curvature.

To find the radius of spherical curvature, take square of both sides of (4)

$$(\underline{s} - \underline{r})^2 = \rho^2 + (\sigma \rho')^2$$

$$\underline{R}^2 = \rho^2 + \sigma^2 \rho'^2 \quad \text{as } \underline{s} - \underline{r} = \underline{R}$$

$$\text{or } |\underline{R}| = \sqrt{\rho^2 + \sigma^2 \rho'^2} \quad \text{--- (5)}$$

Remark For the curve of constant curvature,

$\rho' = 0$ , therefore, (5) becomes

$$R = \rho$$

Centre of spherical curvature coincides with the centre of circular curvature

### § Locus of Centre of Spherical Curvature:

The position vector  $\underline{S}$  of the centre of sp. curvature has been shown to be

$$\underline{S} = \underline{r} + \rho \underline{n} + \sigma \rho' \underline{b} \quad \text{--- (6)}$$

Hence for a small displacement  $ds$  of the current point  $P$  along the original curve  $C$ , the displacement of  $\underline{S}$  is  $\left. \begin{array}{l} \rho k = 1 \\ \sigma \tau = \dots \end{array} \right\}$

$$\frac{d\underline{S}}{ds} = \underline{t} + \rho' \underline{n} + \rho(\tau \underline{b} - k \underline{t}) + \sigma' \rho' \underline{b} + \sigma \rho'' \underline{b} + \sigma \rho' \tau \underline{t}$$

$$d\underline{S} = (\underline{t} + \rho' \underline{n} + \rho \tau \underline{b} - \underline{t} + \rho' \sigma' \underline{b} + \sigma \rho'' \underline{b} - \rho' \underline{n}) ds$$

$$d\underline{S} = (\rho \tau \underline{b} + \rho' \sigma' \underline{b} + \sigma \rho'' \underline{b}) ds$$

$$= ds \left( \frac{\rho}{\sigma} \underline{b} + \rho' \sigma' \underline{b} + \sigma \rho'' \underline{b} \right)$$

$$= ds \left( \frac{\rho}{\sigma} + \rho' \sigma' + \sigma \rho'' \right) \underline{b}$$

Thus the Tangent to locus of  $\underline{S}$  is  $\parallel$  to  $\underline{b}$  (fig 11), we may measure the arc-length  $s_1$  of the locus  $\underline{S}$  in that direction which makes its unit Tangent  $\underline{t}_1$  have the same direction as  $\underline{b}$

Thus  $\underline{t}_1 = \underline{b}$ , & since  $\frac{d\underline{S}}{ds} = \underline{t}_1$ ,  $ds_1$  it follows that

$$\frac{ds_1}{ds} = \frac{\rho}{\sigma} + \frac{d}{ds} (\sigma \rho')$$

To find the curvature  $K_1$  of the locus  $S$ ,  
diff the eq  $\underline{t}_1 = \underline{b}$  wrt  $s_1$

$$\frac{d}{ds_1}(\underline{t}_1) = \frac{d}{ds}(\underline{b})$$

$$\underline{t}_1' = K_1 \underline{n}_1 = \frac{db}{ds} \cdot \frac{ds}{ds_1} = -\tau \underline{n} \frac{ds}{ds_1}$$

$$\Rightarrow \text{Diagram showing vector relationships: } \underline{t}_1 \text{ and } \underline{n}_1 \text{ are parallel to } \underline{t} \text{ and } \underline{n} \text{ respectively, with } \underline{n}_1 = -\underline{n}.$$

Thus  
 $\Rightarrow$  the Principal normal to the locus of  $S$   
 is parallel to the principal normal of the  
 original curve. (Here we may choose  
 the direction of  $\underline{n}_1$  as opposite to that of  $\underline{n}$ . Thus

$$\underline{n}_1 = -\underline{n}$$

The unit binormal  $\underline{b}_1$  of the locus  $S$  is  
 then

$$\underline{b}_1 = \underline{t}_1 \times \underline{n}_1 = \underline{b} \times (-\underline{n}) = \underline{t}$$

and is thus equal to the unit Tangent of  
 the original curve and the curvature

$$K_1 = \tau \frac{ds}{ds_1}$$

Again  $\underline{t}_1 = \underline{b}$  &  $\underline{n}_1 = -\underline{n}$ .

$$\underline{t}_1 \times \underline{n}_1 = -\underline{b} \times \underline{n}$$

$$\underline{b}_1 = \underline{t}$$

$\Rightarrow$  Binormal of  $C_1$  is || to the Tangent of  $C$ .  
 The curvature  $K_1$  as found above is thus equal  
 to

$$K_1 = \tau \frac{ds}{ds_1}$$

The Torsion  $\tau_1$  is obtained by diff  $\underline{b}_1 = \underline{t}$

$$\frac{d}{ds_1}(\underline{b}_1) = \frac{dt}{ds_1}$$

$$\frac{d}{ds_1}(\underline{b}_1) = \frac{dt}{ds} \cdot \frac{ds}{ds_1}$$

$$-\tau_1 \underline{n}_1 = K \tau \frac{ds}{ds_1}$$

$$\tau_1 \underline{n} = K \tau \frac{ds}{ds_1} \Rightarrow \tau_1 = K \frac{ds}{ds_1}$$

From the last two results  
 it follows  $K K_1 = \tau \tau_1$

$$-\underline{n}_1 = \underline{n}$$



\* Example 1) Prove that for curves drawn on the surface of a sphere (or for spherical curve), we have  $\frac{p'}{\sigma} + \frac{d}{ds}(\sigma p') = 0$  or  $\frac{p'}{\sigma} + \sigma' p' + \sigma p'' = 0$

Solution :-

For curves drawn on the surface of a sphere, the osculating sphere at every pt. of the curve is the same sphere on the surface of which it is drawn. — already done — as locus of centre of spherical curvature.

✓ Example 2) If the radius of a spherical curvature is constant. Prove that the curve either lies on the surface of a sphere or else has a constant curvature.

Solution Let  $R$  be the radius of spherical curvature then

$$R^2 = p^2 + (\sigma p')^2 \quad \text{--- (1) } (R^2 \text{ is const})$$

Diff w.r.t  $s$

$$0 = 2pp' + 2(\sigma p') \left[ \frac{d}{ds}(\sigma p') \right]$$

$$0 = 2p' \left[ p + \sigma \frac{d}{ds}(\sigma p') \right] = 0$$

Then either  $p' = 0$  or  $\Rightarrow p$  is constant

The curve has a constant curvature

or if  $p + \sigma \frac{d}{ds}(\sigma p') = 0$

then locus of the centre of sp curvature

$S$  is given by  $S = \underline{t} + p\underline{n} + \sigma p' \underline{b}$  (Eq. 2)

Diff w.r.t  $s$   $\frac{dS}{ds} = \underline{t}' + p\underline{n}' + p'\underline{n} + \sigma p' \underline{b}$

$$\frac{dS}{ds} = \underline{t}' + p(\underline{\tau} \underline{b} - k \underline{t}) + p' \underline{n} + \sigma p' \underline{b} + \sigma p'' \underline{b} + \sigma p' \underline{b}'$$

$$\frac{dS}{ds} = \left[ \frac{p'}{\sigma} + \frac{d}{ds}(\sigma p') \right] \underline{b}$$

Hence, if  $\rho + \sigma \frac{d}{ds} (\sigma \rho') = 0$

$$\text{or } \rho/\sigma + \frac{d}{ds} (\sigma \rho') = 0 \Rightarrow \underline{S} = 0$$

$\Rightarrow \underline{S}$  is constant.

Therefore curve lies on the surface of a sphere.

### § HELICES:

Def A curve traced on the surface of the cylinder and cutting the generators at a constant angle, is called a HELIX.

If  $\underline{t}$  is unit tangent to the helix and  $\underline{a}$  is a constant vector  $\parallel$  to the generator of cylinder, we have  $\underline{t} \cdot \underline{a} = \text{constant}$

& Diff w.r.t.  $s$ , we have  $K \underline{n} \cdot \underline{a} = 0$

Thus since the curvature of the helix does not vanish, the principal normal is every where perpendicular to the generator. Hence fixed direction of the generator is parallel to the plane of  $\underline{t}$  and  $\underline{b}$ , and since it makes a constant angle with  $\underline{t}$ , it also makes a constant angle with  $\underline{b}$ .

### Theorem:

The necessary and sufficient condition for a curve to be a helix is that the ratio of its curvature and Torsion is constant i.e.  $K/\tau = \text{constant}$

Proof: If  $\underline{t}$  is a unit tangent to the helix and  $\underline{a}$  is constant vector  $\parallel$  to generator of cylinder

Then  $\underline{t} \cdot \underline{a} = \text{constant} \quad \text{--- (1)}$

Diff w.r.t  $s$   $\frac{d\underline{t}}{ds} \cdot \underline{a} = 0$

$$\left. \begin{array}{l} \underline{t} \cdot \underline{a} = 1 \cdot 1 \cdot \cos \theta \\ = \cos \theta \\ \underline{t} = K \underline{n} \end{array} \right\}$$

If  $K = 0$  then curve is a straight line & theorem is proved

If  $K \neq 0$  then  $\underline{n} \cdot \underline{a} = 0 \Rightarrow \underline{n} \perp \underline{a}$

Then  $\underline{a}$  will lie in the plane determined by  $\underline{t}$  and  $\underline{b}$ , ~~hence~~ To prove this,

Diff  $\underline{n} \cdot \underline{a} = 0$ , wrt  $s$ , we have

$$\underline{n}' \cdot \underline{a} = 0$$

$$(T\underline{b} - K\underline{t}) \cdot \underline{a} = 0 \Rightarrow \underline{a} \text{ is } \perp \underline{t}$$

~~the plane of  $\underline{b}$  and  $\underline{t}$~~  vector  $T\underline{b} - K\underline{t}$ . But  $\underline{a}$  is parallel to the plane of  $\underline{t}$  &  $\underline{b}$ .

$$\text{Hence } \underline{a} = \cos \alpha \underline{t} + \sin \alpha \underline{b}$$

$$\text{Diff wrt } s \quad 0 = \cos \alpha \underline{t}' + \sin \alpha \underline{b}'$$

$$\Rightarrow \cos \alpha (-K\underline{n}) + \sin \alpha (-T\underline{n}) = 0$$

Since  $\underline{n} \neq 0$ ,  $\underline{n} (K \cos \alpha - T \sin \alpha) = 0$

$$\Rightarrow K \cos \alpha - T \sin \alpha = 0 \quad \tan \alpha = \frac{K}{T}$$

$$\alpha = \tan^{-1} \left( \frac{K}{T} \right) \Rightarrow \frac{K}{T} \text{ is constant}$$

Condition is Sufficient

Given  $\frac{K}{T} = \text{constant}$ , to show curve is Helix.

or  $\underline{t} \cdot \underline{a}$  is constant

Let  $T = cK$ ,  $c$  is constant.

Then since  $\underline{t}' = K\underline{n}$  and  $\underline{b}' = -T\underline{n} = -cK\underline{n}$

It follows that

$$\underline{b}' + c \underline{t}' = -cK\underline{n} + cK\underline{n} = 0$$

$$\frac{d}{ds} (\underline{b} + c \underline{t}) = 0$$

$$\Rightarrow \underline{b} + c \underline{t} = \underline{a} \quad (\text{constant vector})$$

Taking scalar product with  $\underline{t}$

$$\underline{b} \cdot \underline{t} + c \underline{t} \cdot \underline{t} = \underline{a} \cdot \underline{t}$$

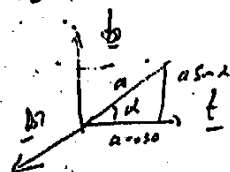
$$0 + c(1) = \underline{a} \cdot \underline{t} \Rightarrow \underline{a} \cdot \underline{t} = c$$

$$\Rightarrow \underline{t} \cdot \underline{a} \text{ is constant}$$

Remarks (i) Thus  $\underline{t}$  is inclined at a constant angle to the fixed direction of  $\underline{a}$  and curve is therefore, Helix

(ii) If ratio  $\frac{K}{T} = 0$  then curve is a line

(iii) If  $\frac{K}{T} = \alpha$ , then curve is a plane curve ( $\alpha$  being angle between  $\underline{t}$  and  $\underline{a}$ )



$\underline{t}$  &  $\underline{b}$  are  $\perp$  to each other  
 $\underline{a}$  makes const with  $\underline{t}$  &  $\underline{b}$

# § SPHERICAL INDICATRIX.

Def. The locus of a point, whose position vector is equal to the unit Tangent  $\underline{t}$  of a given curve, is called the Spherical Indicatrix of the Tangent to the curve. Such a locus lies on the surface of a unit sphere. (Hence the name)

## Theorem

To show that the curvature of the Spherical Indicatrix of Tangents is the ratio of skew curvature to the circular curvature of the Curve.

~~Proof~~. i.e.  $K_1 = \frac{\sqrt{\tau^2 + \kappa^2}}{\kappa}$ ; Also prove  $\tau_1 = \frac{\kappa\tau' - \tau\kappa'}{\kappa(\kappa^2 + \tau^2)}$

Proof:

Let  $\underline{r}_1$  be the p.v. of a point of the spherical indicatrix of the Tangent to a curve, then  $\underline{r}_1 = \underline{t} \rightarrow$  Diff wrt  $s$

$$\frac{d\underline{r}_1}{ds} = \frac{d\underline{t}}{ds}$$

$$\Rightarrow \frac{d\underline{r}_1}{ds_1} \cdot \frac{ds_1}{ds} = \underline{t}'$$

As total:  $\underline{t}_1 \frac{ds_1}{ds} = \kappa \underline{n}$ , we measure

$$\frac{ds_1}{ds} = \kappa \quad \text{then} \quad \underline{t}_1 = \underline{n} \quad \text{--- (i)}$$

Diff again wrt  $s$

$$\frac{d\underline{t}_1}{ds} = \frac{d\underline{n}}{ds}$$

$$\Rightarrow \frac{d\underline{t}_1}{ds_1} \cdot \frac{ds_1}{ds} = \underline{n}'$$

$$\therefore \frac{d\underline{t}_1}{ds_1} = \kappa_1 \underline{n}_1$$

$$\therefore \frac{ds_1}{ds} = \kappa$$

$$\kappa(\kappa_1 \underline{n}_1) = \tau \underline{b} - \kappa \underline{t}$$

$$\kappa_1 \underline{n}_1 = \frac{\tau \underline{b} - \kappa \underline{t}}{\kappa} \quad \text{--- (ii)}$$

Squaring both sides

$$\kappa_1^2 (\underline{n}_1 \cdot \underline{n}_1) = \left( \frac{\tau^2 + \kappa^2}{\kappa^2} \right)$$

$$\kappa_1 = \frac{\sqrt{\tau^2 + \kappa^2}}{\kappa} = \text{Skew Curvature} / \text{Curvature}$$

Now the equation of osculating sphere is

$$R^2 = \rho^2 + (\sigma \rho')^2 \quad \text{--- (1)}$$

As the indicatrix lies on the sphere of unit radius  $\therefore R=1$  and by (1) takes the form

$$1 = \rho^2 + (\sigma \rho')^2$$

$$1 = \frac{1}{K^2} + \frac{1}{T^2} \rho^2 \quad \text{as } \rho = \frac{1}{K}$$

As  $\rho = \frac{1}{K}$  &

$$\sigma = \frac{1}{T}$$

$$\rho' = (\frac{1}{K})' = -\frac{K'}{K^2} = \frac{K'}{K^2}$$

$$(\rho')^2 = \frac{K'^2}{K^4}$$

Putting in (A)  $1 = \frac{1}{K^2} + \frac{1}{T^2} \left( \frac{K'^2}{K^4} \right)$

$$1 - \frac{1}{K^2} = \frac{1}{T^2} \left( \frac{K'^2}{K^4} \right)$$

$$K^2 - 1 = \frac{K'^2}{K^2 T^2} \Rightarrow T^2 = \frac{K'^2}{K^2 (K^2 - 1)}$$

$$T = \frac{K'}{K \sqrt{K^2 - 1}} \quad \text{--- (ii)}$$

Also from  $K = \frac{\sqrt{K^2 + T^2}}{K}$

Diff wrt  $S_1$

$$K' = \frac{d}{ds} \left( \frac{\sqrt{K^2 + T^2}}{K} \right) \frac{ds}{ds_1}$$

$$K' = \left\{ \frac{K \left( \frac{2KK' + 2TT'}{2\sqrt{K^2 + T^2}} \right) - \sqrt{K^2 + T^2} \cdot \frac{K'}{K} \right\} \frac{1}{K} \because \frac{ds}{ds_1} = \frac{1}{K}$$

$$= \frac{\left\{ K (KK' + TT') - (K^2 + T^2) K' \right\}}{K^2 \sqrt{K^2 + T^2}}$$

$$K' = \frac{K^2 K' + KTT' - K^2 K' - T^2 K'}{K^3 \sqrt{K^2 + T^2}} = \frac{KTT' - T^2 K'}{K^3 \sqrt{K^2 + T^2}}$$

Putting values of  $K$  and  $K'$  in (ii), we have

$$T = \frac{KTT' - T^2 K'}{K^3 \sqrt{K^2 + T^2}} \times \frac{1}{\frac{\sqrt{K^2 + T^2}}{K} \sqrt{\frac{K^2 + T^2}{K^2} - 1}}$$

$$T_1 = \frac{T(KT' - TK)}{K^2 \sqrt{K^2 + T^2}} \cdot \frac{K}{\sqrt{K^2 + T^2}} \cdot \frac{1}{\sqrt{K^2}} \\ = \frac{T(KT' - TK)}{K^2 \sqrt{K^2 + T^2}} \cdot \frac{K}{T \sqrt{K^2 + T^2}}$$

$$T_1 = \frac{KT' - TK}{K(\sqrt{K^2 + T^2})^2} = \frac{KT' - TK}{K(K^2 + T^2)}$$

Theorem: Prove that the curvature and torsion of the spherical indicatrix of the Binormal is given by

$$K_1 = \frac{\sqrt{K^2 + T^2}}{T} \quad \text{and} \quad T_1 = \frac{KT' - TK}{T(K^2 + T^2)}$$

Proof The eq. of the spherical indicatrix of the binormal is

$$\underline{r}_1 = \underline{b}$$

Diff wrt  $s_1$

$$\frac{d\underline{r}_1}{ds_1} = \frac{d\underline{b}}{ds} \cdot \frac{ds}{ds_1}$$

$$\underline{t}_1 = \underline{b}' \frac{ds}{ds_1}$$

$$\underline{t}_1 = -T\underline{n} \frac{ds}{ds_1}$$

$$\text{Since } \underline{t}_1 = -\underline{n} = -T\underline{n} \frac{ds}{ds_1} \Rightarrow T \frac{ds}{ds_1} = 1$$

$$\Rightarrow \frac{ds_1}{ds} = T \quad \text{--- (1)} \Rightarrow \frac{ds}{ds_1} = \frac{1}{T}$$

Now  $\underline{t}_1 = -\underline{n}$

Diff wrt  $s_1$

$$\frac{d\underline{t}_1}{ds_1} = -\frac{d\underline{n}}{ds} \cdot \frac{ds}{ds_1}$$

$$K_1 \underline{m}_1 = -[T\underline{b}' - K\underline{t}] \frac{1}{T} \quad \text{by (1)}$$

$$K_1 \underline{m}_1 = \frac{K\underline{t} - T\underline{b}'}{T}$$

Squaring both sides

$$K_1^2 = \frac{K^2 + T^2}{T^2}$$

$$K_1 = \frac{\sqrt{K^2 + T^2}}{T} \quad \text{--- (2)}$$

As the indicatrix lies on the unit sphere.

$$R^2 = p^2 + (\sigma p')^2 \quad \therefore R = 1$$

$$1 = p_1^2 + (\sigma_1 p_1')^2$$

$$1 = \frac{1}{K_1^2} + \frac{1}{T_1^2} (p_1')^2 \quad \text{--- (B)}$$

As  $p_1 = 1/K_1 \Rightarrow p_1' = -\frac{K_1'}{K_1^2}$

$$\therefore (p_1')^2 = \frac{K_1'^2}{K_1^4}$$

Putting in B

$$1 = \frac{1}{K_1^2} + \frac{1}{T_1^2} \frac{K_1'^2}{K_1^4}$$

$$1 - \frac{1}{K_1^2} = \frac{1}{T_1^2} \left( \frac{K_1'^2}{K_1^4} \right)$$

$$\frac{K_1^2 - 1}{K_1^2} = \frac{1}{T_1^2} \frac{K_1'^2}{K_1^4}$$

$$T_1^2 = \frac{K_1'^2}{(K_1^2 - 1)K_1^2} \Rightarrow T_1 = \frac{K_1'}{K_1 \sqrt{K_1^2 - 1}} \quad \text{--- (3)}$$

From (2)  $K_1 = \frac{\sqrt{K^2 + T^2}}{KT}$

Diff w.r.t  $S_1$

$$K_1' = \frac{d}{ds_1} \left( \frac{(K^2 + T^2)^{1/2}}{T} \right)$$

$$K_1' = \frac{d}{ds} \frac{(K^2 + T^2)^{1/2}}{T} \cdot \frac{ds}{ds_1}$$

$$= \frac{T \left( \frac{2KK' + 2TT'}{2\sqrt{K^2 + T^2}} - \sqrt{K^2 + T^2} \cdot \frac{T'}{T^2} \right)}{T^2} \cdot \frac{1}{T}$$

$$= \frac{K(TK' - KT')}{T^3 \sqrt{K^2 + T^2}}$$

Putting these values of  $K_1$  and  $K_1'$  in (3)

$$T_1 = \frac{K(TK' - KT')}{T^3 \sqrt{K^2 + T^2}} \cdot \frac{1}{\frac{\sqrt{K^2 + T^2}}{T} \sqrt{\frac{K^2 + T^2}{T^2} - 1}}$$

$$\tau_1 = \frac{K'(TK' - KT')}{T^3(\sqrt{K^2 + T^2})^2} \cdot \frac{T^2}{K} = \frac{K'T - KT'}{T(K^2 + T^2)}$$

Example Find out Spri, indicatrix (Image) of the circular Helix.

Let  $\underline{r} = (a \cos \theta, a \sin \theta, c\theta)$  ,  $c \neq 0$

Diff wrt  $\theta$

$$\underline{r}' = \underline{t} = (-a \sin \theta, a \cos \theta, c) \frac{d\theta}{ds} \quad \text{--- (1)}$$

Squaring both sides

$$1 = (a^2 \sin^2 \theta + a^2 \cos^2 \theta + c^2) \left(\frac{d\theta}{ds}\right)^2$$

$$1 = (a^2 + c^2) \left(\frac{d\theta}{ds}\right)^2$$

$$\left|\frac{d\theta}{ds}\right|^2 = \frac{1}{a^2 + c^2} \Rightarrow \frac{d\theta}{ds} = \frac{1}{\sqrt{a^2 + c^2}}$$

Say,  $\frac{ds}{d\theta} = \sqrt{a^2 + c^2} = \lambda$  (Constant)  $\rightarrow$  (2)

Put in (1)

$$\underline{t} = (-a \sin \theta, a \cos \theta, c) \frac{1}{\lambda} \quad \text{--- (3)}$$

Diff wrt  $\theta$

$$\frac{d\underline{t}}{ds} = \frac{d}{d\theta} (-a \sin \theta, a \cos \theta, c) \frac{1}{\lambda} \frac{d\theta}{ds}$$

$$\underline{K_n} = (-a \cos \theta, -a \sin \theta, 0) \frac{1}{\lambda^2}$$

Squaring both sides

$$K^2 = (a^2 \cos^2 \theta + a^2 \sin^2 \theta) \frac{1}{\lambda^4}$$

$$K^2 = \frac{a^2}{\lambda^4}$$

$$K = \frac{a}{\lambda^2} \quad \text{--- (4)}$$

Eq. (4) can be written as

$$\underline{K_n} = (-\cos \theta, -\sin \theta, 0) \frac{a}{\lambda^2}$$

$$\underline{K_n} = (-\cos \theta, -\sin \theta, 0) K$$



$$\Rightarrow \vec{n} = (-\cos \theta, -\sin \theta, 0) \rightarrow (5)$$

Now  $\underline{b} \times \underline{t} \times \underline{n}$

$$= \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ -\frac{a \sin \theta}{\lambda} & \frac{a \cos \theta}{\lambda} & \frac{c}{\lambda} \\ -\cos \theta & -\sin \theta & 0 \end{vmatrix} \quad \left. \vphantom{\begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ -\frac{a \sin \theta}{\lambda} & \frac{a \cos \theta}{\lambda} & \frac{c}{\lambda} \\ -\cos \theta & -\sin \theta & 0 \end{vmatrix}} \right\} \text{From 3 \& 5}$$

$$= \frac{1}{\lambda} \left\{ \underline{i} \left( 0 + \frac{c \sin \theta}{\lambda} \right) - \underline{j} \left( c \cos \theta \right) + \underline{k} \left( a \sin^2 \theta + a \cos^2 \theta \right) \right\}$$

$$= \frac{1}{\lambda} \left( c \sin \theta, -c \cos \theta, a \right) \rightarrow (6)$$

From (4), (5) & (6) we can find Spherical Images for Tangent.

as  $x = -\frac{a \sin \theta}{\lambda}, y = \frac{a \cos \theta}{\lambda}, z = \frac{c}{\lambda}$

for Principal normal,

$$x = -\cos \theta, y = -\sin \theta, z = 0$$

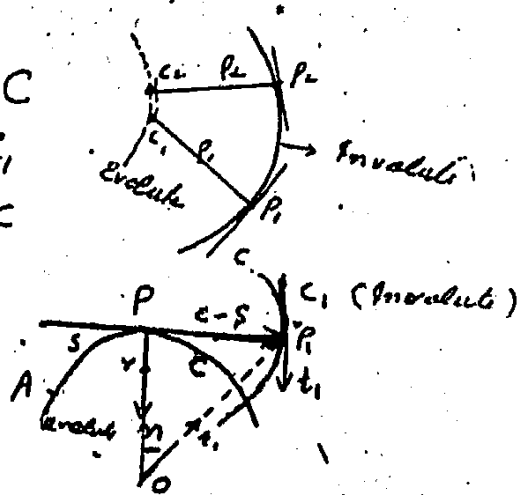
& for Principal Binormal are

$$x = \frac{c \sin \theta}{\lambda}, y = -\frac{c \cos \theta}{\lambda}, z = \frac{a}{\lambda}$$

### 8. INVOLUTES & EVOLUTES

Def: When the Tangents to a curve C are normal to another curve C<sub>1</sub>, then C<sub>1</sub> is called an Involute of C and C is called an evolute of C<sub>1</sub>.

Let  $t_1$  be the p.v. of a pt. P<sub>1</sub> on C<sub>1</sub> and  $\underline{t}$  be p.v. of P on which lies on the Tangent at the pt  $\underline{k}$  of Curve C is given by  $\underline{t}_1 = \underline{k} + u \underline{t}$  where u is to be determined.



Let  $ds_1$  be the arc length of the involute corresponding to the element  $ds$  of the curve C. Then the Tangent to C<sub>1</sub> is

$$\underline{t}_1 = \frac{d\underline{r}_1}{ds_1} = \frac{d(\underline{k} + u \underline{t})}{ds_1} = \left( \underline{t} + u \underline{t}' + \underline{t} \frac{du}{ds_1} \right) \frac{ds}{ds_1}$$

$$= \left[ (1 + u') \underline{t} + u K \underline{n} \right] \frac{ds}{ds_1} \quad \text{--- (2)}$$

To satisfy the conditions for an involute, this vector must be  $\perp$  to  $\underline{t}$ , Hence

Putting the value of  $U$  in (1), we have

$$\left. \begin{aligned} 1+U' &= 0 \\ U' &= -1 \\ U &= -s+c \end{aligned} \right\} \begin{array}{l} c \text{ is constant} \end{array}$$

$$\underline{r}_1 = \underline{r} + (c-s) \underline{t}$$

where  $c$  is constant, due to  $c$  we conclude that there are  $\infty$  nos of involutes for each evolute and the unit-Tangent (from eq(2)) is

$$\underline{t}_1 = \frac{d\underline{r}_1}{ds_1} = \left( \underline{t} + U' \underline{t} + UK \underline{n} \right) \frac{ds}{ds_1}$$

from (3) & (4)

$$\underline{t}_1 = \left( \underline{t} + (-1) \underline{t} + (c-s) K \underline{n} \right) \frac{ds}{ds_1}$$

$$\underline{t}_1 = (c-s) K \underline{n} \frac{ds}{ds_1}$$

Since  $\underline{t}_1 = \underline{n}$  — (5)  $+ (c-s) K \frac{ds}{ds_1} = 1$

Thus  $\underline{t}_1 \parallel \underline{n}$  &  $\frac{ds_1}{ds} = K(c-s)$

From  $\underline{t}_1 \parallel \underline{n}$ , we note that Tangent at the point  $P$  to  $C_1$  is parallel to the normal of the point  $P$  to  $C$ .

To find curvature of Involute, we consider

from (5)  $\underline{t}_1 = \underline{n}$

Diff wrt  $s_1$ ,  $\frac{d\underline{t}_1}{ds_1} = \frac{d\underline{n}}{ds} \frac{ds}{ds_1}$

$$K_1 \underline{n}_1 = \underline{n}' \frac{ds}{ds_1}$$

$$K_1 \underline{n}_1 = (T\underline{t} - K\underline{t}) \frac{1}{K(c-s)}$$

Squaring both sides

$$K_1^2 (1) = \sqrt{T^2 + K^2} \frac{(T^2 + K^2)}{K^2 (c-s)^2}$$

$$K_1 = \frac{\sqrt{T^2 + K^2}}{K(c-s)}$$

which is

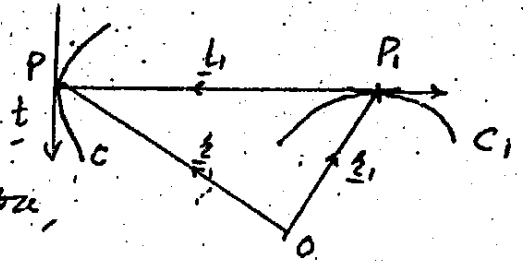
the required expression for curvature of involute  $C_1$ .

# Theorem For Evolutes

Statement To show there are an infinite family of evolutes for the space curve  $C$ .

Proof Let  $C$  be space curve with  $\underline{r} = \underline{r}(s)$  as its eq.

Since the Tangent at  $P_1$  of  $C_1$  is normal at a corresponding pt  $P$  of  $C$  i.e. the Tangent at  $P_1$  of  $C_1$



lies in the normal plane, therefore,

or  $\underline{r}_1$  of  $P_1$  can be expressed as

$\underline{r}_1 = \underline{r} + U\underline{n} + V\underline{b}$  — (1) where  $U$  and  $V$  are to be determined

$$\begin{aligned} \frac{d\underline{r}_1}{ds} &= \underline{r}' + U'\underline{n} + U\underline{n}' + V'\underline{b} + V\underline{b}' \\ &= \underline{t} + U'\underline{n} + U(\tau\underline{b} - \kappa\underline{t}) + V'\underline{b} + V(-\tau\underline{n}) \\ &= \underline{t}(1 - U\kappa) + (U' - \tau V)\underline{n} + (U\tau + V')\underline{b} \end{aligned}$$

As  $\frac{d\underline{r}_1}{ds} = \underline{0}$  lies in normal plane — (2)

we have  $\frac{d\underline{r}_1}{ds} = U\underline{n} + V\underline{b}$  — (3)

Comparing (2) & (3)

$$\Rightarrow 1 - U\kappa = 0 \quad (4)$$

$$\frac{U' - V\tau}{U} = \frac{U\tau + V'}{V} \quad (5)$$

From (4)

$$U = \frac{1}{\kappa} = \rho$$

from (5) & (6)

$$U'V - V^2\tau = U^2\tau + UV'$$

$$(U^2 + V^2)\tau = U'V - UV'$$

$$\tau = \frac{U'V - UV'}{U^2 + V^2}$$

Integrating

w.r.t  $s$

$$\int \tau ds = \frac{1}{1 + \frac{V^2}{U^2}} \left( \frac{U'V - UV'}{V^2} \right)$$

Since  $U = \rho$

we write

$$\psi = \int \tau ds = \int \tan^{-1} \left( \frac{V}{\rho} \right) ds$$

$$\psi + c = \tan^{-1} \left( \frac{V}{\rho} \right)$$

$$\tan(\psi + c) = \frac{V}{\rho}$$

$$V = -\rho \tan(\psi + \alpha) \quad \text{where } \frac{1}{\rho} = \frac{1}{R}$$

$$\therefore \underline{r}_1 = \underline{r} + \rho \left[ \underline{n} - \tan(\psi + \alpha) \underline{b} \right]$$

Which is equation of the evolute  $C_1$  and for different values of arcl. constants, we can obtain different evolutes and hence  $\infty$  many different evolutes  $C_1$  for the given curve  $C$ .

Example: Prove that the locus of centre of curvature is an evolute only when the curve is a plane curve.

Solution: The equation of Evolute can be written as

$$\underline{r}_1 = \underline{r} + \rho \underline{n} - \rho \tan(\psi + \alpha) \cdot \underline{b} \quad \text{--- (1)}$$

For different values of  $\alpha$  we have different evolutes, also the locus of centre of curvature can be written as  $\underline{c} = \underline{r} + \rho \underline{n}$  --- (2)

Equation (1) and (2) are identical, if

\*  $\underline{b}$  is a unit vector so it can't be equal to zero  $\Rightarrow$  if  $\underline{b} \neq 0, \rho \neq 0$ , then

$$\tan(\psi + \alpha) = 0$$

$$\Rightarrow \tan(\psi + \alpha) = \tan n\pi \quad n \text{ is any integer,}$$

$$\Rightarrow \psi + \alpha = n\pi$$

$$\psi(s) = n\pi - \alpha$$

$$\psi'(s) = 0 \quad \text{--- (3)}$$

$$\text{but } \psi = \int \tau ds \Rightarrow \tau = \psi'(s)$$

$$\Rightarrow \tau = 0$$

Hence the curve is a plane curve.

Theorem Prove that the ratio of the torsion and curvature of an evolute of a space curve (evolutes) is

$$\frac{\tau_1}{\kappa_1} = -\tan(\psi + \alpha) \quad \text{where } \psi = \int \tau ds$$

Proof The equation of the evolute is

$$\underline{r}_1 = \underline{r} + \rho \underline{n} - \rho \tan(\psi + a) \underline{b}$$

Diff wrt  $s_1$

$$\frac{d\underline{r}_1}{ds_1} = \left\{ \underline{t}' + \rho' \underline{n} + \rho \underline{n}' - \rho' \tan(\psi + a) \underline{b} - \rho \underline{b}' \tan(\psi + a) - \rho \underline{b} \sec^2(\psi + a) \frac{d\psi}{ds} \right\} \frac{ds}{ds_1}$$

$$= \left\{ \underline{t} + \rho' \underline{n} + \rho (\tau \underline{b} - \kappa \underline{t}) - \rho' \tan(\psi + a) \underline{b} - \rho \kappa - \tau \rho \tan(\psi + a) - \rho \underline{b} \sec^2(\psi + a) \tau \right\} \frac{ds}{ds_1}$$

$$= \left\{ \underline{t} + \rho' \underline{n} + \rho \tau \underline{b} - \rho \kappa \underline{t} - \rho' \tan(\psi + a) \underline{b} + \rho \tau \underline{n} \tan(\psi + a) - \rho \underline{b} (1 + \tan^2(\psi + a)) \tau \right\} \frac{ds}{ds_1}$$

$$= \left\{ \underline{t} + \rho' \underline{n} + \rho \tau \underline{b} - \underline{t} - \rho' \tan(\psi + a) \underline{b} + \rho \tau \underline{n} \tan(\psi + a) - \tau \rho \tan^2(\psi + a) \underline{b} - \rho \tau \underline{b} \right\} \frac{ds}{ds_1} \quad \left( \text{By putting } \rho = \frac{1}{\kappa} \right)$$

$$= \left\{ \rho' \underline{n} + \rho \tau \underline{n} \tan(\psi + a) - \rho' \tan(\psi + a) \underline{b} - \rho \tau \tan^2(\psi + a) \underline{b} \right\} \frac{ds}{ds_1}$$

$$= \left\{ (\rho' + \rho \tau \tan(\psi + a)) \underline{n} - \tan(\psi + a) \{ \rho' + \rho \tau \tan(\psi + a) \} \underline{b} \right\} \frac{ds}{ds_1}$$

$$t_1 = \frac{d\underline{r}_1}{ds_1} = \left\{ (\rho' + \rho \tau \tan(\psi + a)) (\underline{n} - \tan(\psi + a) \underline{b}) \right\} \frac{ds}{ds_1} \quad \longrightarrow \textcircled{1}$$

Squaring both sides

$$1 = (\rho' + \rho \tau \tan(\psi + a))^2 (1 + \tan^2(\psi + a)) \left( \frac{ds}{ds_1} \right)^2$$

$$1 = (\rho' + \rho \tau \tan(\psi + a))^2 \sec^2(\psi + a) \left( \frac{ds}{ds_1} \right)^2$$

$$\left( \frac{ds_1}{ds} \right)^2 = (\rho' + \rho \tau \tan(\psi + a))^2 \sec^2(\psi + a)$$

$$\frac{ds_1}{ds} = (\rho' + \rho \tau \tan(\psi + a)) \sec(\psi + a)$$

$$\Rightarrow \frac{ds}{ds_1} = \frac{1}{(\rho' + \rho \tau \tan(\psi + a)) \sec(\psi + a)}$$

Using result in eq ①, we get

$$t_1 = \left\{ \cancel{(\rho' + \rho \tau \tan(\psi + a))} (\underline{n} - \tan(\psi + a) \underline{b}) \right\} \times \frac{\cos(\psi + a)}{(\rho' + \rho \tau \tan(\psi + a))} = \frac{\underline{n} - \tan(\psi + a) \underline{b}}{\sec(\psi + a)}$$

$$\underline{t}_1 = \left( n - \frac{\sin(\psi+a)}{\cos(\psi+a)} \underline{b} \right) \cos(\psi+a)$$

$$\underline{t}_1 = \left( n \cos(\psi+a) - \underline{b} \sin(\psi+a) \right) \quad \text{--- (2)}$$

Diff. w.r.t  
s,

$$\frac{dt_1}{ds_1} = \frac{d}{ds} \left( n \cos(\psi+a) - \underline{b} \sin(\psi+a) \right) \frac{ds}{ds_1}$$

$$= \left\{ \underline{n}' \cos(\psi+a) - n \sin(\psi+a) \psi' - \underline{b}' \sin(\psi+a) - \underline{b} \cos(\psi+a) \psi' \right\} \frac{ds}{ds_1}$$

$$K_1 n_1 = \left\{ (T \underline{b} - K \underline{t}_1) \cos(\psi+a) - n \sin(\psi+a) T + T n \sin(\psi+a) - \underline{b} \cos(\psi+a) T \right\} \frac{ds}{ds_1}$$

$$K_1 n_1 = \left\{ T \underline{b} \cos(\psi+a) - K \underline{t}_1 \cos(\psi+a) - n \sin(\psi+a) T + n T \sin(\psi+a) - \underline{b} T \cos(\psi+a) \right\} \frac{ds}{ds_1}$$

$$= \left[ -K \underline{t}_1 \cos(\psi+a) \right] \frac{ds}{ds_1}$$

$$\text{or } \Rightarrow n_1 = -\underline{t}_1 \frac{K_1}{K} \quad K_1 = K \cos(\psi+a) \frac{ds}{ds_1} \quad \text{--- (3)}$$

Now Consider  $\underline{b}_1 = t_1 \times n_1$

$$\text{using (2) } \underline{b}_1 = \left( n \cos(\psi+a) - \underline{b} \sin(\psi+a) \right) \times \left( -\underline{t}_1 \right)$$

$$\underline{b}_1 = -n \times \underline{t}_1 \cos(\psi+a) + \underline{b} \times \underline{t}_1 \sin(\psi+a)$$

$$= \underline{b} \cos(\psi+a) + n \sin(\psi+a)$$

$$\text{Now } \frac{db_1}{ds_1} = \frac{d}{ds} \left( \underline{b} \cos(\psi+a) + n \sin(\psi+a) \right) \frac{ds}{ds_1}$$

$$-T_1 n_1 = \left[ \underline{b}' \cos(\psi+a) - \underline{b} \sin(\psi+a) \psi' + n' \sin(\psi+a) + n \cos(\psi+a) \psi' \right] \frac{ds}{ds_1}$$

$$-T_1 n_1 = \left[ -T n \cos(\psi+a) - \underline{b} \sin(\psi+a) T + (T \underline{b} \sin(\psi+a) - K \underline{t}_1 \sin(\psi+a) + n T \cos(\psi+a)) \right] \frac{ds}{ds_1}$$

$$-T_1 n_1 = -K \underline{t}_1 \sin(\psi+a) \frac{ds}{ds_1}$$

$$T_1 n_1 = K \underline{t}_1 \sin(\psi+a) \frac{ds}{ds_1} \Rightarrow n_1 = -\underline{t}_1 \frac{T_1}{K} \quad T_1 = -K \sin(\psi+a) \frac{ds}{ds_1} \quad \text{--- (5)}$$

Dividing (5) by (3)

$$\frac{T_1}{K_1} = \frac{-K \sin(\psi+a) \frac{ds}{ds_1}}{K \cos(\psi+a) \frac{ds}{ds_1}} = \frac{-\sin(\psi+a)}{\cos(\psi+a)} = -T \tan(\psi+a)$$

where  $\psi = \int T ds$  or  $\psi' = T$

## CHAPTER - 2

### § Diff. Geometry of Surfaces.

Def. A surface is the locus of a point  $P(x, y, z)$  whose coordinates are functions of two indept. parameters  $u$  and  $v$ , thus

$$x = f_1(u, v), \quad y = f_2(u, v), \quad z = f_3(u, v) \rightarrow (1)$$

are parametric eqs of a surface.

If we eliminate  $u$  &  $v$  from these eqs we have  $F(x, y, z) = 0$  as eq. of surface.

#### Examples

① The Parametric eq of a sphere with centre at  $O$  and radius  $a$  is

$$x = a \cos \theta \cos \phi$$

$$y = a \cos \theta \sin \phi$$

$$z = a \sin \theta$$

Eliminating  $\phi$  and  $\theta$  from these equations

$$\begin{aligned} x^2 + y^2 + z^2 &= a^2 \cos^2 \theta \cos^2 \phi + a^2 \cos^2 \theta \sin^2 \phi + a^2 \sin^2 \theta \\ &= a^2 \cos^2 \theta (\cos^2 \phi + \sin^2 \phi) + a^2 \sin^2 \theta \\ &= a^2 (\cos^2 \theta + \sin^2 \theta) = a^2 \end{aligned}$$

Eq of a sphere centre at  $O$  and rad =  $a$

Examp. ② The Parametric eqs of Ellipsoid

$$x = a \cos \theta \cos \phi$$

$$y = b \cos \theta \sin \phi$$

$$z = c \sin \theta$$

Eliminating  $\theta$  and  $\phi$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1 \quad \text{Eq. of Ellipsoid}$$

Examp. ③ The Parametric eqs of a cone are

$$x = \mu \sin \phi \cos \psi$$

$$y = \mu \sin \phi \sin \psi$$

$$z = \mu \cos \phi$$

$$x^2 + y^2 = \mu^2 (\sin^2 \phi) (\cos^2 \psi + \sin^2 \psi)$$

$$= \mu^2 \sin^2 \phi$$

$$= \frac{\mu^2 \sin^2 \phi}{\cos^2 \phi} \cdot \cos^2 \phi$$

$$= \mu^2 \cos^2 \phi \tan^2 \phi$$

Required eq. of a cone

$$x^2 + y^2 = z^2 \tan^2 \phi$$

### § TANGENT PLANE & NORMAL

Def The Tangent to any curve drawn on a surface is called a Tangent line to the surface. ~~Thus~~  
~~all Tangent~~

Def: Tangent plane to a surface, at a point  $P$  is the plane containing all Tangent lines to the surface at this point.

§ To find Eq of Tangent plane & eq of normal at a pt  $P$  to the surface  $F(x, y, z) = 0$

Let  $F(x, y, z) = 0$  be the equation of surface. Let  $C$  be any curve drawn on it. Suppose  $s$  be the arc length measured from a fixed pt.  $A$  up to a current pt  $P(x, y, z)$ . Since  $F(x, y, z) = 0$  has the same value at all points of the surface, it remains constant along the curve as  $s$  varies, thus

$$\text{Differentiate } \Rightarrow \frac{dF}{ds} = \frac{\partial F}{\partial x} \frac{dx}{ds} + \frac{\partial F}{\partial y} \frac{dy}{ds} + \frac{\partial F}{\partial z} \frac{dz}{ds} = 0$$

$$\Rightarrow F_x x' + F_y y' + F_z z' = 0$$

$$\text{or } (F_x, F_y, F_z) \cdot (x', y', z') = 0 \quad \text{--- (2)}$$

Now the vector  $(x', y', z')$  is the unit Tangent to the curve where the vector  $(x, y, z)$  is the unit Tangent to the curve at  $P(x, y, z)$ . Eq (2) shows that it is  $\perp$  to the vector  $(F_x, F_y, F_z)$ . All Tangent lines to the surface at  $(x, y, z)$  are  $\perp$  to the vector  $(F_x, F_y, F_z)$  and hence lie in the plane through  $(x, y, z)$   $\perp$  to this vector. This plane is called Tangent plane & normal to the plane at  $P$ , the pt of contact, is called normal to the surface at that pt. The vector  $(F_x, F_y, F_z)$  is called grad  $F$ , denoted as  $\nabla F$ .

Since the line joining any point  $R(X, Y, Z)$  on the Tangent plane to the point of contact is  $\perp$  to the normal, it follows that  $(R - P) \cdot \nabla F = 0$ ,  $P$  is p.v. of pt of contact. OR  $(X-x) \frac{\partial F}{\partial x} + (Y-y) \frac{\partial F}{\partial y} + (Z-z) \frac{\partial F}{\partial z} = 0$   
or  $(X-x)F_x + (Y-y)F_y + (Z-z)F_z = 0$  --- (3) Eq. of T.P.



## Equation of Normal.

Since normal of the surface  $F(x, y, z) = 0$  is along the gradient  $\nabla F$ . Hence eq of normal is for any current pt  $R(x, y, z)$

$$\underline{R} = \underline{r} + u \nabla F$$

$$\underline{R} - \underline{r} = u \nabla F$$

$$\text{or } (X-x, Y-y, Z-z) = u \left( \frac{\partial F}{\partial x}, \frac{\partial F}{\partial y}, \frac{\partial F}{\partial z} \right)$$

$$\text{or } X-x = u \frac{\partial F}{\partial x}$$

$$Y-y = u \frac{\partial F}{\partial y}$$

$$Z-z = u \frac{\partial F}{\partial z}$$

Eliminating  $u$  from these eqs, we have

$$\frac{X-x}{F_x} = \frac{Y-y}{F_y} = \frac{Z-z}{F_z}$$

Which are eqs of normal at point  $P(x, y, z)$ .

## Ex. on Page 39

Q(1) Prove that the Tangent plane to the Surface  $xyz = a^3$  and the coord. planes bound a Tetrahedron of constant volume.

Sol Eq of surface is  $xyz = a^3$

$$F = xyz - a^3$$

$$F_x = yz, \quad F_y = xz, \quad F_z = xy$$

Eq of Tangent plane

$$(\underline{R} - \underline{r}) \cdot \nabla F = 0$$

$$(X-x) \frac{\partial F}{\partial x} + (Y-y) \frac{\partial F}{\partial y} + (Z-z) \frac{\partial F}{\partial z} = 0$$

$$(X-x)yz + (Y-y)xz + (Z-z)xy = 0$$

$$Xyz - xyz + yxz - yxz + Zxy - xyz = 0$$

$$\text{or } Xyz + yxz + Zxy - 3xyz = 0$$

$$\text{or } Xyz + yxz + Zxy - 3a^3 = 0 \quad \text{--- (1)}$$

pt of  $X$  on  $yz$  axis with coord. plane. ( $Y=0, Z=0$ )

$$Xyz = 3a^3 \quad X = \frac{3a^3}{yz}$$

$$\text{Similarly for } y \text{ \& } z \text{ axis } \quad Y = \frac{3a^3}{xz}, \quad Z = \frac{3a^3}{yx}$$

The pts of  $X_n$  are  $(\frac{3a^3}{y^2}, 0, 0)$ ,  $(0, \frac{3a^3}{x^2}, 0)$  &  $(0, 0, \frac{3a^3}{xy})$   
 To find the volume of Tetrahedron through these pts with 4th pt as origin  $(0, 0, 0)$ , we have

$$V = \frac{1}{6} \begin{vmatrix} \frac{3a^3}{y^2} & 0 & 0 \\ 0 & \frac{3a^3}{x^2} & 0 \\ 0 & 0 & \frac{3a^3}{xy} \\ 0 & 0 & 0 \end{vmatrix} \begin{vmatrix} 1 \\ 1 \\ 1 \\ 1 \end{vmatrix} = \frac{1}{6} \left( \frac{27a^9}{x^2 y^2} \right)$$

$$= \frac{9}{2} \frac{a^9}{a^6} = \frac{9}{2} a^3$$

which is constant.

Q(2) Show that the Sum of Squares of the Intercepts on the coordinate axes by the Tangent plane to the surface  $x^{2/3} + y^{2/3} + z^{2/3} = a^{2/3}$  is constant.

Sol. Eq. of Surface  $F = x^{2/3} + y^{2/3} + z^{2/3} - a^{2/3} = 0$

$$\frac{\partial F}{\partial x} = \frac{2}{3} x^{-1/3}, \quad \frac{\partial F}{\partial y} = \frac{2}{3} y^{-1/3}$$

$$\frac{\partial F}{\partial z} = \frac{2}{3} z^{-1/3}$$

Eq. of Tangent plane.  $(R-z) \cdot \nabla F = 0$

$$\text{or } (X-x) \frac{\partial F}{\partial x} + (Y-y) \frac{\partial F}{\partial y} + (Z-z) \frac{\partial F}{\partial z} = 0$$

$$(X-x) \frac{2}{3} x^{-1/3} + (Y-y) \frac{2}{3} y^{-1/3} + (Z-z) \frac{2}{3} z^{-1/3} = 0$$

$$\Rightarrow \frac{X-x}{x^{1/3}} + \frac{Y-y}{y^{1/3}} + \frac{Z-z}{z^{1/3}} = 0$$

$$\frac{1}{x^{1/3}} X + \frac{1}{y^{1/3}} Y + \frac{1}{z^{1/3}} Z = x^{2/3} + y^{2/3} + z^{2/3} = a^{2/3} \quad \text{--- (2)}$$

For x Intercept. Put  $y=0=z$

$$\therefore \frac{X}{x^{1/3}} = a^{2/3} \Rightarrow X = a^{2/3} x^{1/3}$$

Similarly y and z intercepts are

$$\Rightarrow Y = a^{2/3} y^{1/3} \quad Z = a^{2/3} z^{1/3}$$

$$\text{Let } A(a^{2/3} x^{1/3}, 0, 0)$$

$$B(0, a^{2/3} y^{1/3}, 0)$$

$$\text{and } C = (0, 0, a^{2/3} z^{1/3})$$

Sum of Squares of Intercepts

$$\begin{aligned} (OA)^2 + (OB)^2 + (OC)^2 &= a^{2/3} x^{2/3} + a^{2/3} y^{2/3} + a^{2/3} z^{2/3} \\ &= a^{2/3} (x^{2/3} + y^{2/3} + z^{2/3}) \\ &= a^{2/3} (a^{2/3}) = a^2 = \text{Constant} \end{aligned}$$

Q(3) All pts common to the surface  $a(xy + yz + zx) = xyz$  and a sphere whose centre is origin, The Tangent plane to the surface make intercepts on the axis whose sum is constant.

Solution Let Surface be  $F(x, y, z) = a(xy + yz + zx) - xyz = 0$  (1)  
& eq of sphere is  $x^2 + y^2 + z^2 = a^2$  (2)

For Surface,

$$\frac{\partial F}{\partial x} = ay - yz + az$$

$$\frac{\partial F}{\partial y} = ax + az - xz$$

$$\frac{\partial F}{\partial z} = ax + ay - xy$$

Eq of Tangent plane.

$$(X-x)(ay+az-yz) + (Y-y)(ax+az-xz) + (Z-z)(ax+ay-xy) = 0$$

$$\Rightarrow X(ay+az-yz) + Y(ax+az-xz) + Z(ax+ay-xy) - 2[a(xy+yz+zx) - xyz] + xyz = 0$$

$$\Rightarrow X(ay+az-yz) + Y(ax+az-xz) + Z(ax+ay-xy) + xyz = 0 \quad (3)$$

For X Intercept. Put  $Y=0=Z$

$$X = \frac{-xyz}{ay+az-yz} = \frac{-x^2yz}{axy+ayz-xyz} = \frac{-x^2yz}{-ayz} = \frac{x^2}{a}$$

Similarly Y and Z Intercepts are

$$Y = \frac{y^2}{a} \quad \text{and} \quad Z = \frac{z^2}{a}$$

Sum of Intercepts

$$\frac{x^2}{a} + \frac{y^2}{a} + \frac{z^2}{a} = \frac{x^2 + y^2 + z^2}{a} \quad (4)$$

Pts of the surface which are common to sphere will satisfy the eq of sphere.

$$x^2 + y^2 + z^2 = a^2$$

Hence Sum of Intercepts for such pts is

$$\frac{1}{a}(x^2 + y^2 + z^2) = \frac{a^2}{a} \quad \text{which is constant}$$

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Q(u) The normal at a point P of Ellipsoid  $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$  meets the coordinate planes in  $G_1, G_2, G_3$ . Prove that the ratios  $PG_1 : PG_2 : PG_3$  are constant.

Sol The equation of surface is

$$F(x, y, z) = \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} - 1 = 0$$

$$\frac{\partial F}{\partial x} = \frac{2x}{a^2}, \quad \frac{\partial F}{\partial y} = \frac{2y}{b^2}, \quad \frac{\partial F}{\partial z} = \frac{2z}{c^2}$$

Equation of normal at  $P(x, y, z)$  is

$$\frac{X-x}{2x/a^2} = \frac{Y-y}{2y/b^2} = \frac{Z-z}{2z/c^2}$$

$$\Rightarrow a^2 \frac{(X-x)}{x} = b^2 \frac{(Y-y)}{y} = c^2 \frac{(Z-z)}{z} \quad \text{--- (1)}$$

$G_1$  is pt. of  $X$  on normal --- (1) to the  $YZ$  plane.

Put  $X = 0$

$$-\frac{a^2 x}{x} = \frac{b^2 (Y-y)}{y} = c^2 \frac{(Z-z)}{z}$$

$$Y = \frac{-a^2 y + b^2 y}{b^2} = \left(\frac{b^2 - a^2}{b^2}\right) y$$

Similarly

$$Z = \left(\frac{c^2 - a^2}{c^2}\right) z$$

$$G_1 = \left(0, \frac{(b^2 - a^2)y}{b^2}, \left(\frac{c^2 - a^2}{c^2}\right) z\right)$$

Similarly  $G_2 = \left(\left(\frac{a^2 - b^2}{a^2}\right) x, 0, \left(\frac{c^2 - b^2}{c^2}\right) z\right)$

$X$  on  $YZ$  plane

$$G_3 = \left(\left(\frac{a^2 - c^2}{a^2}\right) x, \left(\frac{b^2 - c^2}{b^2}\right) y, 0\right)$$

$X$  on  $YZ$  plane

$$\therefore |PG_1| = \sqrt{(x-0)^2 + \left(y - \frac{(b^2 - a^2)y}{b^2}\right)^2 + \left(z - z \cdot \frac{(c^2 - a^2)}{c^2}\right)^2}$$

$$= \sqrt{\frac{x^2}{a^2} + \frac{a^4}{b^4} y^2 + \frac{a^4}{c^4} z^2} = a^2 \sqrt{\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4}}$$

Similarly

$$|PG_2| = b^2 \sqrt{\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4}}$$

$$|PG_3| = c^2 \sqrt{\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4}}$$

Hence  $|PG_1| : |PG_2| : |PG_3| = a^2 : b^2 : c^2$

Which is constant.

## § ONE PARAMETER FAMILY OF SURFACES

An equation of the form  $F(x, y, z, a) = 0$ , where 'a' is constant, represents a surface. Since 'a' is arbitrary constant, therefore, there are infinitely many surfaces. The set of all surfaces corresponding to different values of 'a' is called one parameter family of surfaces with parameter 'a'.

Example. Family of spheres of constant radius 'b' and having their centres at the ~~circle~~ fixed circle  $x^2 + y^2 = a^2$  &  $z = 0$

Coordinates of a point on the given circle are  $x = a \cos \theta$ ,  $y = a \sin \theta$  &  $z = 0$

Therefore, eq. of sphere will be

$$(x - a \cos \theta)^2 + (y - a \sin \theta)^2 + z^2 = b^2$$

It is family of spheres.

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## § CHARACTERISTICS OF A SURFACE :-

Consider  $F(x, y, z, a) = 0$  or  $F(a) = 0$  (i)

&  $F(x, y, z, a + \delta a) = 0$  or  $F(a + \delta a) = 0$  (ii)

be two surfaces of the same family. The curve of intersection of two surfaces of the family, ~~the above eqs~~ can be written as

$$F(a) = 0$$

$$\& \frac{F(a + \delta a) - F(a)}{\delta a} = 0$$

If  $\delta a \rightarrow 0$  then the two eqs represent two consecutive surfaces and eqs become as

$$F(a) = 0$$

$$\& \frac{\partial}{\partial a} F(a) = 0$$

The curve of intersection of two consecutive surfaces is called the

Characteristic of the surface for the parametric value 'a'.

Two surfaces (i) & (ii)  
intersect at surface  
surface 1 & 2  
Antiderivative of 0  
B.P.

## § ENVELOPES

The locus of all characteristics is called an envelope of the family of surfaces. It is a surface whose equation is obtained by eliminating 'a' from the eqs  $F(a) = 0$  &  $\frac{\partial}{\partial a} F(a) = 0$

Exercise ON Page 41

Q(1) Find the Envelope of the family of Paraboloids

$$x^2 + y^2 = 4a(z - a)$$

is the circular cone  $x^2 + y^2 = z^2$

Sol

Let  $F(a) = x^2 + y^2 - 4a(z - a) = 0$  (1)

Diff partially w.r.t 'a'

$$\frac{\partial F(a)}{\partial a} = -4z + 8a = 0$$

Eliminating a, put  $z/2 = a$  in eq. (1)

$$x^2 + y^2 - 4 \cdot \frac{z}{2} (z - \frac{z}{2}) = 0$$

$$x^2 + y^2 - z^2 = 0 \quad \text{or} \quad x^2 + y^2 = z^2$$

(required Envelope)

Q(2) Spheres of constant Radius  $b$  have their centres on the fixed circle  $x^2 + y^2 = a^2$ ,  $z = 0$ , prove that their envelope is the surface

$$(x^2 + y^2 + z^2 + a^2 - b^2)^2 = 4a^2(x^2 + y^2)$$

Sol The eq. of sphere of radius  $b$  with centre on given circle  $x = a \cos \theta$ ,  $y = a \sin \theta$ , will be

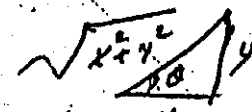
$$(x - a \cos \theta)^2 + (y - a \sin \theta)^2 + z^2 = b^2$$

$$\Rightarrow F = x^2 + y^2 + z^2 - 2a(x \cos \theta + y \sin \theta) + a^2 - b^2 = 0 \quad (1)$$

$$\frac{\partial F}{\partial \theta} = 2a x \sin \theta - 2a y \cos \theta = 0$$

$$\text{or} \quad 2a(x \sin \theta - y \cos \theta) = 0 \quad (2)$$

and  $\tan \theta = \frac{y}{x}$



$\sin \theta = \frac{y}{\sqrt{x^2 + y^2}}$        $\cos \theta = \frac{x}{\sqrt{x^2 + y^2}}$

Putting these values in eq (1), we get-

$$x^2 + y^2 + z^2 - 2a \left( \frac{x^2}{\sqrt{x^2 + y^2}} + \frac{y^2}{\sqrt{x^2 + y^2}} \right) + a^2 - b^2 = 0$$

$$x^2 + y^2 + z^2 + a^2 - b^2 = 2a\sqrt{x^2 + y^2}$$

Squaring both sides

$$(x^2 + y^2 + z^2 + a^2 - b^2)^2 = 4a^2(x^2 + y^2)$$

is the required Envelope

Q(3) Find the Envelope of the family of Surfaces  $F(x, y, z, a, b) = 0$  in which parameter  $a, b$  are connected by the eq  $f(a, b) = 0$

Solution: Given  $F(x, y, z, a, b) = 0$  (i)

$$f(a, b) = 0 \quad (ii)$$

Diff (i) & (ii) w.r.t  $a$

$$\frac{\partial F}{\partial a} + \frac{\partial F}{\partial b} \cdot \frac{\partial b}{\partial a} = 0 \quad (iii)$$

$$\text{and } \frac{\partial f}{\partial a} + \frac{\partial f}{\partial b} \cdot \frac{\partial b}{\partial a} = 0 \quad (iv)$$

From eq (iv) we have

$$\frac{\partial b}{\partial a} = -\frac{\frac{\partial f}{\partial a}}{\frac{\partial f}{\partial b}} = -\frac{f_a}{f_b}$$

Multiplying (iii), we have

$$F_a + F_b \left( -\frac{f_a}{f_b} \right) = 0$$

$$\Rightarrow \frac{F_a}{f_a} = \frac{F_b}{f_b} \quad (v)$$

Eqs (i) & (ii) are the

Required Eqs. of the Envelope.

Theorem: To prove that Envelope touches each member of the family of Surfaces at all pts of the characteristic.

Proof: The characteristic corresponding to the parameter value  $a$  lies both on the surface with the same parameter value and on the envelope.

Thus all pts of the characteristic are common to the surface and the envelope.

The normal to the surface  $F(x, y, z, a) = 0$  is parallel to the vector  $(\frac{\partial F}{\partial x}, \frac{\partial F}{\partial y}, \frac{\partial F}{\partial z}) \rightarrow \textcircled{1}$

The equation of the envelope is obtained by eliminating  $a$  from  $F(a) = 0, \frac{\partial}{\partial a} F(a) = 0$

The envelope is therefore, represented by

$F(x, y, z, a) = 0$  provided 'a' is regarded as a fn of  $x, y, z$  given by  $\frac{\partial F}{\partial a}(x, y, z, a) = 0$

The normal to the envelope is then parallel to the vector  $(\frac{\partial F}{\partial x} + \frac{\partial F}{\partial a} \frac{\partial a}{\partial x}, \frac{\partial F}{\partial y} + \frac{\partial F}{\partial a} \frac{\partial a}{\partial y}, \frac{\partial F}{\partial z} + \frac{\partial F}{\partial a} \frac{\partial a}{\partial z}) \rightarrow \textcircled{2}$

which in virtue of the preceding eq, is the same as vector  $\textcircled{1}$ . Thus <sup>at</sup> all common pts, the surface and the envelope have the same normal and therefore, the same tangent plane, so that they touch each other at all pts of the characteristic.

Note for (ii)  $\frac{\partial F}{\partial a} = 0$  and it reduces to

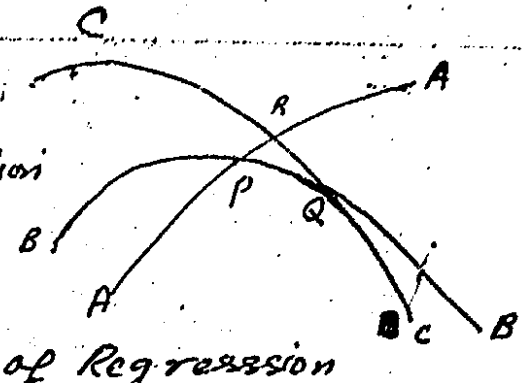
eq,  $(\frac{\partial F}{\partial x}, \frac{\partial F}{\partial y}, \frac{\partial F}{\partial z}) \Rightarrow \textcircled{3}$   
which is same as  $\textcircled{1}$



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### EDGE OF REGRESSION

The locus of ultimate intersection of consecutive characteristics of a one-parameter family of surfaces is called the Edge of Regression



~~Theorem~~ <sup>show</sup> that each characteristic touches edge of regression (ie to say that two curves have the same tangent at their common point.)

Proof:  
Suppose that A, B and C are three consecutive characteristics A and B intersecting at P and B and C intersect at Q. These two pts are consecutive pts on the characteristic B and also on the edge of regression. Hence ultimately as A and C tends to coincidence with B. The chord PQ becomes a common tangent to the characteristic and edge of regression.

### Equation of the Edge of Regression

Let  $F(x, y, z, a) = 0$  be a family of surfaces then eq of characteristics corresponding to parameter 'a' and  $a + \delta a$  are  ~~$F(a) = 0$  &  $F(a + \delta a)$~~

$$F(x, y, z, a) = 0$$

$$\& F_a(x, y, z, a) = 0 \quad \text{and} \quad F(x, y, z, a + \delta a) = 0$$

$$\& F_a(x, y, z, a + \delta a) = 0$$

It follows that

$$F_a(x, y, z, a + \delta a) - F_a(x, y, z, a) = 0$$

$$\text{ie } F_{aa}(x, y, z, a) = 0$$

The eqs of edge of regression are obtained by eliminating a from  $F(a) = 0$   $F_a(a) = 0$  and  $F_{aa}(a) = 0$

Q.1 Find the envelope of the family of planes  
 $3a^2x - 3ay + z = a^3$  and show  
 that its edge of regression is the curve of intersection  
 of the surfaces  $xz = y^2$ ,  $xy = z$

Solution Given Surface is

$$F(a) = 3a^2x - 3ay + z - a^3 = 0 \rightarrow (1)$$

$$\frac{\partial F}{\partial a} = 6ax - 3y - 3a^2 = 0 \rightarrow (2)$$

$$\frac{\partial^2 F}{\partial a^2} = 6x - 6a = 0 \rightarrow (3)$$

Multiply eq (1) by 3 and eq (2) by -a

$$9a^2x - 9ay + 3z - 3a^3 = 0$$

adding 
$$-6a^2x + 3ay + 3a^3 = 0$$

$$3a^2x - 6ay + 3z = 0$$

$$\Rightarrow a^2x - 2ay + z = 0 \rightarrow (4)$$

Eq (2) is  $3a^2 - 6ax + 3y = 0$

or  $a^2 - 2ax + y = 0 \rightarrow (5)$

Scaling (4) & (5) 
$$\frac{a^2}{-2y^2 + 2xz} = \frac{-a}{xy - z} = \frac{1}{-2x^2 + 2y}$$

$$\Rightarrow a^2 = \frac{-2y^2 + 2xz}{-2x^2 + 2y} \quad \& \quad a = \frac{z - xy}{-2x^2 + 2y}$$

$$a^2 = \frac{-2y^2 + 2xz}{-2x^2 + 2y} = \frac{y^2 - xz}{x^2 - y} = \frac{(z - xy)^2}{4(x^2 - y)^2}$$

$$(z - xy)^2 = 4(x^2 - y)(y^2 - xz)$$

required eq of Envelope

For edge of regression

From eq (3)

$$x - a = 0$$

$$x = a$$

Putting in (1)  $3x^3 - 3xy + z - x^3 = 0$

$$2x^3 - 3xy + z = 0 \rightarrow (6)$$

and in (11)

$$3x^2 - 3y = 0 \Rightarrow \boxed{x^2 = y}$$

Putting  $y = x^2$  in  $2x^3 - 3xy + z = 0$

$$2x^3 - 3x^3 + z = 0$$

$$-x^3 + z = 0$$

put  $x^2 = y \Rightarrow -xy + z = 0$

$$\boxed{z = xy}$$

Multiply eq  $x^2 - y = 0$  by  $y$

$$x^2y - y^2 = 0$$

$$x(xy) - y^2 = 0$$

$$xz - y^2 = 0$$

$$\boxed{y^2 = xz}$$

The eqs of edge of regression

$$xz = y^2 \text{ and } xy = z$$

Q(2) Find the edge of regression of the envelope of family of planes

$$x \sin \theta - y \cos \theta + z = a \theta \quad (\theta \text{ parameter})$$

Solution

Let  $F(\theta) = x \sin \theta - y \cos \theta + z - a \theta = 0$  (1)

$$F_{\theta}(\theta) = x \cos \theta + y \sin \theta - a = 0 \quad (2)$$

$$F_{\theta\theta}(\theta) = -x \sin \theta + y \cos \theta = 0 \quad (3)$$

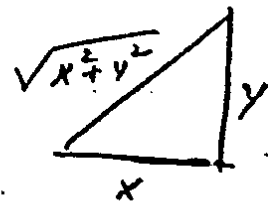
From (3)

$$\boxed{+x \sin \theta = y \cos \theta}$$

$$\tan \theta = \frac{y}{x}$$

$$\sin \theta = \frac{y}{\sqrt{x^2 + y^2}}$$

$$\cos \theta = \frac{x}{\sqrt{x^2 + y^2}}$$



$$\boxed{y = x \tan \theta} \quad (4)$$

Putting in eq (1)

$$z = a \theta \Rightarrow \boxed{\theta = \frac{z}{a}}$$

Hence  $y = x \tan\left(\frac{z}{a}\right)$  (5)

From eq (2) Squaring

$$x^2 \cos^2 \theta + y^2 \sin^2 \theta + 2xy \sin \theta \cos \theta = a^2$$

$$x^2 (1 - \sin^2 \theta) + y^2 \sin^2 \theta + 2y(y \cos \theta) \cos \theta = a^2$$

$$x^2 - x^2 \sin^2 \theta + y^2 \sin^2 \theta + 2y^2 \cos^2 \theta = a^2$$

$$x^2 - y^2 \cos^2 \theta + y^2 \sin^2 \theta + 2y^2 \cos^2 \theta = a^2$$

$$x^2 + y^2 (\cos^2 \theta + \sin^2 \theta) = a^2$$

$$\boxed{x^2 + y^2 = a^2} \rightarrow \textcircled{6} \quad \& y = x \tan\left(\frac{\theta}{a}\right)$$

Eqs (6) & (5) are eqs of edge of regressions

Q(3) Find the Envelope of the family of cones

$$(ax + x + y + z - 1)(ay + z) = ax(x + y + z - 1) \quad a \text{ is parameter}$$

Solution:

$$F(a) = (ax + x + y + z - 1)(ay + z) - ax(x + y + z - 1) = 0$$

$$F_a(a) = x(ay + z) + (ax + x + y + z - 1)y - x^2 - xy - xz + x = 0$$

$$\Rightarrow axy + xz + axy + xy + y^2 + zy - y - x^2 - xy - xz + x = 0$$

$$\Rightarrow 2axy = x^2 - y^2 - x + y - zy$$

$$\Rightarrow a = \frac{x^2 - y^2 - x + y - zy}{2xy} \rightarrow \textcircled{2}$$

Eliminating (a)

Putting the value of a in (1), we have eq of Envelope.

Q(4) Find the Envelope and the edge of regression of the family of ellipsoids

$$\text{Sol} \quad c^2 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) + \frac{z^2}{c^2} = 1 \quad (c \text{ is parameter})$$

The given eq

$$F(c) = c^2 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) + \frac{z^2}{c^2} - 1 = 0 \quad \textcircled{1}$$

$$\frac{\partial F}{\partial c} = 2c \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) + \frac{-2z^2}{c^3} = 0$$

$$\Rightarrow c^2 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) - \frac{z^2}{c^2} = 0 \quad \textcircled{2}$$

$$\text{From } \textcircled{2} \quad c^4 = \frac{z^2}{\frac{x^2}{a^2} + \frac{y^2}{b^2}}$$

Putting in (1) (square eq (1))

$$c^4 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) + \frac{z^4}{c^4} + 2z^2 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) = 1$$

Putting (2)

$$z^2 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) + z^2 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) + 2z^2 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) = 1$$

$\Rightarrow 4z^2 \left( \frac{x^2}{a^2} + \frac{y^2}{b^2} \right) = 1$  is eq of Envelope

Now, For the edge of regression

Diff eq<sup>n</sup> wrt  $c$

$$\frac{d^2F}{dc^2} = 2\left(\frac{x^2}{a^2} + \frac{y^2}{b^2}\right) + \frac{6z^2}{c^4} = 0$$

$$\text{OR } c^2\left(\frac{x^2}{a^2} + \frac{y^2}{b^2}\right) + \frac{3z^2}{c^2} = 0$$

Eliminating  $c$  from (1) & (2) and (3)

$$c^2\left(\frac{x^2}{a^2} + \frac{y^2}{b^2}\right) + \frac{2z}{c^2} - 1 = 0 \quad (i)$$

$$c^2\left(\frac{x^2}{a^2} + \frac{y^2}{b^2}\right) - \frac{2z}{c^2} = 0 \quad (ii)$$

Subtract

$$\frac{4z}{c^2} = 1$$

$$2z^2 = 1$$

$$\boxed{c^2 = 2z^2}$$

Putting in (1)

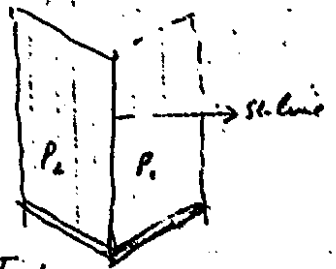
$$z^2\left(\frac{x^2}{a^2} + \frac{y^2}{b^2}\right) = \frac{1}{4}$$

$$\text{and } z^2\left(\frac{x^2}{a^2} + \frac{y^2}{b^2}\right) = -\frac{3}{4}$$

which are the eqs of edge of regression

## § DEVELOPABLE SURFACES

We know, in one-parameter family of planes, the characteristics, being the intersection of planes consecutive planes, are st. lines. These st. lines are called the generators of the envelope, and the envelope is called a developable surface or simply a developable.



The reason for the name lies in the fact that the surface may be unrolled or developed into a plane without stretching or tearing.

Also note that, each plane in one-parameter family of planes touches the envelope along its generator. It follows that the tangent plane to a developable surface at all pts of a generator corresponding to a plane in the family is the plane itself. Thus a developable surface has a constant tangent plane along the generator. So that the tangent planes depends on only one parameter.

The Edge of Regression of the developable is the locus of intersection of consecutive generators and is touched by each of the generators.

The Osculating planes of the edge of regression at any point is the Tangent plane to the developable at that point.

Theorem To find the condition that a surface is a developable. (Let  $z = f(x, y)$  be eq. of Sur.

Proof: The eq. of Tangent-plane at a point.

$$(x_1, y_1, z_1) \text{ is } z - z_1 = (x - x_1) \frac{\partial F}{\partial x} - (y - y_1) \frac{\partial F}{\partial y} \dots$$

Since Tangent plane to a developable depends on only one parameter, therefore, there must be some relation between  $\frac{\partial F}{\partial x}$  and  $\frac{\partial F}{\partial y}$  which, we may write

$$\frac{\partial F}{\partial x} = \phi \left( \frac{\partial F}{\partial y} \right)$$

On differentiation, this gives (w.r.t. x & y separately)

$$\frac{\partial^2 F}{\partial x^2} = \phi' \left( \frac{\partial F}{\partial y} \right) \frac{\partial^2 F}{\partial x \partial y} \quad \text{--- (i)}$$

$$\text{and } \frac{\partial^2 F}{\partial x \partial y} = \phi' \left( \frac{\partial F}{\partial y} \right) \frac{\partial^2 F}{\partial y^2} \quad \text{--- (ii)}$$

From (i) & (ii)

$$\left( \frac{\partial^2 F}{\partial x^2} \right) \left( \frac{\partial^2 F}{\partial y^2} \right) = \left( \frac{\partial^2 F}{\partial x \partial y} \right)^2$$

which is the required condition.

Example Prove that  $xy = (z-c)^2$  is a developable surface

$$F(x, y, z) = z^2 - 2cz + c^2 - xy = 0$$

$$\frac{\partial F}{\partial x} = -y \quad \& \quad \frac{\partial^2 F}{\partial x^2} = 0$$

$$\frac{\partial F}{\partial y} = -x \quad \& \quad \frac{\partial^2 F}{\partial y^2} = 0$$

$$\frac{\partial^2 F}{\partial x \partial y} = -1 \quad \& \quad \frac{\partial F}{\partial y} = \frac{1}{2} \frac{x}{\sqrt{xy}}$$

$$\frac{\partial^2 F}{\partial x \partial y} = \frac{1}{4} \left( \frac{y}{x} \right)^{-1/2} \cdot \frac{1}{2}$$

$$\frac{\partial^2 F}{\partial y^2} = \frac{1}{4} \left( \frac{x}{y} \right)^{-1/2} \cdot \left( -\frac{x}{y^2} \right)$$

$$\frac{1}{16} \left( \frac{x}{y} \right)^{1/2} \cdot \frac{1}{\sqrt{xy}} \cdot \frac{1}{\sqrt{xy}} = \frac{1}{16} \left( \frac{y}{xy} \right)$$

$$z - c = \sqrt{xy}$$

$$z = \sqrt{xy} + c$$

$$\frac{\partial F}{\partial x} = \frac{1}{2} (xy)^{-1/2} y = \frac{y}{2\sqrt{xy}}$$

$$\frac{\partial F}{\partial x} = \frac{1}{2} \sqrt{\frac{y}{x}}$$

$$\frac{\partial^2 F}{\partial x^2} = \frac{1}{4} \left( \frac{y}{x} \right)^{-1/2} \cdot \left( -\frac{y}{x^2} \right)$$

$$\left( \frac{\partial^2 F}{\partial x \partial y} \right)^2 = \left( \frac{1}{4} \left( \frac{y}{x} \right)^{1/2} \right)^2 = \frac{1}{16} \left( \frac{y}{x} \right)$$

LHS = RHS.

## § OSCULATING DEVELOPABLE

Def. The envelope of the osculating plane is called the osculating developable. Since the intersection of consecutive osculating planes are the tangents to the curve, it follows that the tangents are the generators of the developable. And consecutive tangents intersect at a point on the curve; so that the curve itself is the edge of regression of the osculating developable.

Theorem Prove that

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(i) The generators of the osculating developable of a twisted curve are the tangents to the curve.

(ii) The edge of regression is the curve itself.

Proof: At a point  $\underline{r}$  on the curve, the eq. of the osculating plane is

$$(\underline{R} - \underline{r}) \cdot \underline{b} = 0 \quad \text{--- (1)}$$

where  $\underline{r}$  and  $\underline{b}$  are fns of  $s$ . Diff (1) wrt  $s$ .

$$(0 - \underline{r}') \cdot \underline{b} + (\underline{R} - \underline{r}) \cdot \underline{b}' = 0$$

$$-\underline{t} \cdot \underline{b} + (\underline{R} - \underline{r}) \cdot (-\tau \underline{n}) = 0$$

$$0 - \tau (\underline{R} - \underline{r}) \cdot \underline{n} = 0$$

$$\text{but } \underline{t} \cdot \underline{b} = 0$$

$$\Rightarrow (\underline{R} - \underline{r}) \cdot \underline{n} = 0 \quad \text{--- (2)}$$

which is the equation of rectifying plane. Thus the characteristic which is given by (i) & (ii) is the intersection of the osculating and rectifying planes and is therefore, the tangent to the curve at  $\underline{r}$ .

To find the edge of regression, differentiating (1) wrt  $s$ ,

$$(\underline{R} - \underline{r}) \cdot \underline{n}' + (0 - \underline{r}') \cdot \underline{n} = 0$$

$$(\tau \underline{b} - \kappa \underline{t}) \cdot (\underline{R} - \underline{r}) - \underline{t} \cdot \underline{n} = 0$$

$$\tau (\underline{R} - \underline{r}) \cdot \underline{b} - \kappa (\underline{R} - \underline{r}) \cdot \underline{t} - \underline{t} \cdot \underline{n} = 0$$

$$\Rightarrow \tau (\underline{R} - \underline{r}) \cdot \underline{b} - \kappa (\underline{R} - \underline{r}) \cdot \underline{t} - 0 = 0$$

From eq ①  $(R-\underline{r}) \cdot \underline{b} = 0$ . Hence from the last eq, we have  $K(R-\underline{r}) \cdot \underline{b} = 0$  — ③

From ① & ③ it is clear that:  $R-\underline{r}$  is  $\perp$  to  $\underline{b}$ .  
Hence eq ③ implies that

$$(R-\underline{r}) = 0 \Rightarrow R = \underline{r}$$

The edge of regression is the curve itself:

### § POLAR DEVELOPABLE.

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The envelope of the normal plane of a twisted curve is called the polar developable and its generators are called polar lines.

Theorem. Show that: A Polar line is the axis of the circle of curvature and the edge of regression of the polar developable is the locus of centre of spherical curvature.

Proof. Let  $P(\underline{r})$  be a point on the curve whose normal plane is  $(R-\underline{r}) \cdot \underline{t} = 0$  — ①

Diff w.r.t  $s$ .

$$(R-\underline{r}) \cdot \underline{t}' + (0-\underline{t}') \cdot \underline{t} = 0$$

$$K(R-\underline{r}) \cdot \underline{n} - \underline{t} \cdot \underline{t} = 0$$

$$\Rightarrow (R-\underline{r}) \cdot \underline{n} = \frac{1}{K}$$

$$\Rightarrow (R-\underline{r}) \cdot \underline{n} = \rho(\underline{n} \cdot \underline{n})$$

$$\Rightarrow [(R-\underline{r}) - \rho \underline{n}] \cdot \underline{n} = 0 \text{ — ②}$$

which represents a plane through the centre of curvature  $\perp$  to the principal normal.

It intersects the normal plane in a straight line through the centre of curvature  $\parallel$  to the binormal. Thus the polar line is the axis of the circle of curvature.

For II part.

$$\text{From eq: } K(R-\underline{r}) \cdot \underline{n} = 1$$

$$(R-\underline{r}) \cdot \underline{n} = \frac{1}{K} = \rho$$

Diff w.r.t  $s$



$$(R - \underline{r}) \cdot \underline{n}' + (0 - \underline{r}') \cdot \underline{n} = \rho'$$

$$(R - \underline{r}) \cdot (\tau \underline{b} - \kappa \underline{t}) - \underline{t} \cdot \underline{n} = \rho'$$

$$\underline{t} \cdot \underline{n} = 0$$

$$\tau (R - \underline{r}) \cdot \underline{b} - \kappa (R - \underline{r}) \cdot \underline{t} = \rho'$$

since from (1)  $\kappa (R - \underline{r}) \cdot \underline{t} = 0$

$$\therefore \tau (R - \underline{r}) \cdot \underline{b} = \rho'$$

$$(R - \underline{r}) \cdot \underline{b} = \sigma \rho' \rightarrow (3) \quad \frac{1}{\tau} = \sigma$$

From (1), (2) and (3) it follows that

$$(R - \underline{r}) = \rho \underline{n} + \sigma \rho' \underline{b}$$

(Take dot prod with  $\underline{b}$  for (3))

$$\text{or } \underline{R} = \underline{r} + \rho \underline{n} + \sigma \rho' \underline{b}$$

This is the equation of spherical curvature. Hence the edge of regression of Polar developable is the locus of the centre of Spherical curvature.

RECTIFYING DEVELOPABLE:-

The envelope of the rectifying plane of a curve is called the rectifying developable and its generators are the rectifying lines.

Thus the rectifying line at a pt P of the curve is the intersection of consecutive rectifying planes.

Theorem: Prove that (i) The rectifying line is  $\parallel$  to the vector  $(\tau \underline{t} + \kappa \underline{b})$

(ii) A point on the edge of regression corresponding to a point  $\underline{r}$  on the curve is given by 
$$\underline{R} = \underline{r} + \frac{\kappa (\tau \underline{t} + \kappa \underline{b})}{\kappa' \tau - \kappa \tau'}$$

Proof The equation of rectifying plane at the point  $\underline{r}$  is  $(R - \underline{r}) \cdot \underline{n} = 0 \rightarrow (1)$   
Diff it wrt  $s$

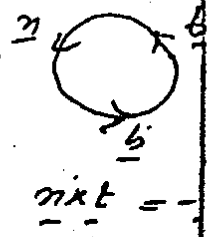
we have  $(R-1) \cdot \underline{n} + (0-1') \cdot \underline{n} = 0$   
 $(R-1) \cdot (\tau \underline{b} - k \underline{t}) - \underline{t} \cdot \underline{n} = 0$

$(R-1) \cdot (\tau \underline{b} - k \underline{t}) = 0 \quad \text{--- (2)} \quad \underline{t} \cdot \underline{n} = 0$

Since  $(R-1)$  is  $\perp$  to  $\underline{n}$  and  $(\tau \underline{b} - k \underline{t})$   
 so it is  $\parallel$  to the vector product of these two.

From eqs (1) and (2), It follows: Each  
 rectifying line is  $\perp$  to both  $\underline{n}$  &  $(\tau \underline{b} - k \underline{t})$   
 $\therefore$  hence  $\parallel$  to  $\underline{n} \times (\tau \underline{b} - k \underline{t})$

$= \tau (\underline{n} \times \underline{b}) - k (\underline{n} \times \underline{t})$   
 $= \tau \underline{t} + k \underline{b}$



So the rectifying line is  $\parallel$  to  $\tau \underline{t} + k \underline{b}$

(ii) Diff (2)  $(R-1) \cdot (\tau \underline{b} - k \underline{t}) = 0$  wrts  
 for the edge of regression.

$\Rightarrow (R-1) \cdot (\tau \underline{b}' + \tau' \underline{b} - k' \underline{t} - k \underline{t}') = 0$   
 $+ (0-1') \cdot (\tau \underline{b} - k \underline{t}) = 0$

$\Rightarrow \underline{\tau}^2 (R-1) \cdot \underline{n} + (R-1) \tau' \underline{b} - k^2 (R-1) \cdot \underline{n}$   
 $- k' (R-1) \cdot \underline{t} - \tau \underline{t} \cdot \underline{b} + k \underline{t} \cdot \underline{t} = 0$

$\therefore$  From (1)  $(R-1) \cdot \underline{n} = 0$

$\Rightarrow (R-1) \cdot (\tau' \underline{b} - k' \underline{t}) + k = 0 \quad \text{--- (3)}$

Also since  $(R-1)$  is  $\parallel$  to  $(\tau \underline{t} + k \underline{b})$   
 we can write

$(R-1) = \lambda (\tau \underline{t} + k \underline{b}) \quad \text{--- (4)}$

Putting in (3)

$\underline{t} \cdot \underline{b} = 0$   
 $\lambda (\tau \underline{t} + k \underline{b}) \cdot ((\tau' \underline{b} - k' \underline{t}) + k) = 0$

$\Rightarrow \lambda (\tau' k - k' \tau) + k = 0 \quad \Rightarrow \lambda = \frac{k}{k' \tau - k \tau'}$   
 Putting in (4)

A(X+Y) + XYZ = 0 means it again  
 is a conic whose projection on the plane  
 of XY is a rectangular hyperbola.

$$R = \frac{1}{1} + \frac{K(\tau_b - K_b)}{K\tau - K\tau'}$$

Hence the result.

Ex. on Page (39)

Eq of Surface,  $F(x,y,z) = a(x^2+y^2) + xyz = 0$

$$\frac{\partial F}{\partial x} = 2ax + yz, \quad \frac{\partial F}{\partial y} = 2ay + xz$$

$$\frac{\partial F}{\partial z} = xy$$

For any pt. on the surface  $P(\alpha, \beta, \gamma)$

$$\left(\frac{\partial F}{\partial x}\right)_{at P} = 2a\alpha + \beta\gamma$$

$$\left(\frac{\partial F}{\partial y}\right)_{at P} = 2a\beta + \alpha\gamma \quad \left(\frac{\partial F}{\partial z}\right)_{at P} = \alpha\beta$$

The eq of Tangent plane in cartesian form is

$$(x-\alpha)\frac{\partial F}{\partial x} + (y-\beta)\frac{\partial F}{\partial y} + (z-\gamma)\frac{\partial F}{\partial z} = 0$$

$$(x-\alpha)(2a\alpha + \beta\gamma) + (y-\beta)(2a\beta + \alpha\gamma) + (z-\gamma)\alpha\beta = 0$$

$$\Rightarrow x(2a\alpha + \beta\gamma) + y(2a\beta + \alpha\gamma) + z\alpha\beta - 2a\alpha^2 - \alpha\beta\gamma - 2a\beta^2 - \alpha\beta\gamma - \alpha\beta\gamma = 0$$

$$\Rightarrow (2a\alpha + \beta\gamma)x + (2a\beta + \alpha\gamma)y + \alpha\beta z - 2a(\alpha^2 + \beta^2) - 3\alpha\beta\gamma = 0$$

As the pt lies on the surface, therefore we have

$$a(\alpha^2 + \beta^2) + \alpha\beta\gamma = 0 \Rightarrow \gamma = -\frac{a(\alpha^2 + \beta^2)}{\alpha\beta}$$

For Projection on xy plane  $z=0$

$$x\left(2a\alpha - \frac{a(\alpha^2 + \beta^2)}{\alpha\beta}\right) + \left(2a\beta - \frac{a(\alpha^2 + \beta^2)}{\alpha\beta}\right)y - 2a(\alpha^2 + \beta^2) + 3a(\alpha^2 + \beta^2) = 0$$

$$\Rightarrow x\left[\frac{2a\alpha^2 - a\alpha^2 - a\beta^2}{\alpha\beta}\right] + y\left[\frac{2a\beta^2 - a\alpha^2 - a\beta^2}{\alpha\beta}\right] + a(\alpha^2 + \beta^2) = 0$$

$$\Rightarrow \frac{x}{\alpha} - \frac{y}{\beta} = 1$$

$$\frac{x}{\alpha} - \frac{y}{\beta} = 1$$

Ex. on Page (50)

Q(1) Find the envelope of the planes through the centre of an ellipsoid and cutting it in sections of constant area.

Sol

Sol. Eq. of Ellipsoid be  $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$  — (1)

& let  $lx + my + nz = 0$  — (2) be eq.

of plane passing through the centre of Ellipsoid.

Then the area of the section of the Ellipsoid cut by plane 2 is given by

$$= \frac{\pi abc}{\sqrt{a^2 l^2 + b^2 m^2 + c^2 n^2}} = \text{constant} = K \quad \text{--- (3)}$$

$$F(x, y, z; l, m, n) = (lx + my + nz = 0$$

$$F_l = x, \quad F_m = y, \quad F_n = z$$

$$f(l, m, n) = \frac{\pi abc}{\sqrt{a^2 l^2 + b^2 m^2 + c^2 n^2}} - K = 0$$

$$f_l = \frac{-\pi abc l}{(a^2 l^2 + b^2 m^2 + c^2 n^2)^{3/2}} \quad \text{Similarly } f_m = \frac{-\pi abc m}{(a^2 l^2 + b^2 m^2 + c^2 n^2)^{3/2}}$$

$$f_n = \frac{-\pi abc n}{(a^2 l^2 + b^2 m^2 + c^2 n^2)^{3/2}}$$

Now  $\frac{F_l}{f_l} = \frac{F_m}{f_m} = \frac{F_n}{f_n}$  is  $\frac{x}{a^2 l} = \frac{y}{b^2 m} = \frac{z}{c^2 n} = k$  (sc)

$$l = \frac{x}{a^2 k}, \quad m = \frac{y}{b^2 k}, \quad n = \frac{z}{c^2 k}$$

Putting these values of  $l, m, n$  in — (2), we have

$$\frac{x^2}{a^2 k} = \frac{y^2}{b^2 k} = \frac{z^2}{c^2 k} = 0$$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 0$$

which is the required eq. of envelope.

Q(2). A plane makes intercepts  $a, b, c$  on the coordinate axes s.t.  $\frac{1}{a^2} + \frac{1}{b^2} + \frac{1}{c^2} = \frac{1}{k^2}$ . Prove that its envelope is a conicoid with equi-conjugate diameters along the axes.

Solution: Let the eq. of plane be  $\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$   $\rightarrow$  (1)

Then  $F(x, y, z, a, b, c) = \frac{x}{a} + \frac{y}{b} + \frac{z}{c} - 1 = 0$   $\rightarrow$  (1)

$f(a, b, c) = \frac{1}{a^2} + \frac{1}{b^2} + \frac{1}{c^2} - \frac{1}{k^2} = 0$   $\rightarrow$  (2)

$F_a = -\frac{x}{a^2}$ ,  $F_b = -\frac{y}{b^2}$ ,  $F_c = -\frac{z}{c^2}$

$f_a = -\frac{2}{a^3}$ ,  $f_b = -\frac{2}{b^3}$ ,  $f_c = -\frac{2}{c^3}$

Then  $\frac{F_a}{f_a} = \frac{F_b}{f_b} = \frac{F_c}{f_c}$  i.e.  $\frac{-\frac{x}{a^2}}{-\frac{2}{a^3}} = \frac{-\frac{y}{b^2}}{-\frac{2}{b^3}} = \frac{-\frac{z}{c^2}}{-\frac{2}{c^3}}$

$\Rightarrow \frac{ax}{2} = \frac{by}{2} = \frac{cz}{2} = l$

$a = \frac{l}{x}$ ,  $b = \frac{l}{y}$ ,  $c = \frac{l}{z}$

Putting in (1)  $\frac{x^2}{l} + \frac{y^2}{l} + \frac{z^2}{l} = 1$

$x^2 + y^2 + z^2 = l$

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Q(3) Prove that the envelope of a plane, the sum of squares of whose intercepts on the axes is constant & it is a surface  $x^{\frac{2}{3}} + y^{\frac{2}{3}} + z^{\frac{2}{3}} = \text{constant}$ .

Solution

Let Eq. of a plane be  $lx + my + nz - 1 = 0$

This plane's intercepts coordinate axes at pts

$(\frac{1}{l}, 0, 0)$ ,  $(0, \frac{1}{m}, 0)$  &  $(0, 0, \frac{1}{n})$

Sum of Squares of intercepts is

$\frac{1}{l^2} + \frac{1}{m^2} + \frac{1}{n^2} = \text{constant}$  (Given)  $\rightarrow$  (1)

$f(l, m, n) = \frac{1}{l^2} + \frac{1}{m^2} + \frac{1}{n^2} - c = 0$

$f_l = -\frac{2}{l^3}$ ,  $f_m = -\frac{2}{m^3}$ ,  $f_n = -\frac{2}{n^3}$

Also  $F(x, y, z, l, m, n) = lx + my + nz - 1 = 0$

$F_l = x$ ,  $F_m = y$ ,  $F_n = z$

Now  $\frac{F_x}{f_x} = \frac{F_y}{f_y} = \frac{F_z}{f_z}$  is written as

$$\frac{x}{-2/l^3} = \frac{y}{-2/m^3} = \frac{z}{-2/n^3} = k$$

$$lx = m^2 y + n^2 z = -2k = K$$

$$x = \frac{K}{l^3}, \quad y = \frac{K}{m^3}, \quad z = \frac{K}{n^3}$$

Then  $x^{2/3} + y^{2/3} + z^{2/3} = \left(\frac{K}{l^3}\right)^{2/3} + \left(\frac{K}{m^3}\right)^{2/3} + \left(\frac{K}{n^3}\right)^{2/3}$   
 $= K^{2/3} \left[ \frac{1}{l^2} + \frac{1}{m^2} + \frac{1}{n^2} \right]$   
 $= \text{Const. by } \textcircled{1}$

Q(3) Prove that the envelope of surface  $F(x, y, z, a, b, c) = 0$  where  $a, b, c$  are parameters connected by the relation  $f(a, b, c) = 0$  is obtained by eliminating  $a, b, c$  from the eqs  $F=0$  and  $f=0$  is  $\frac{F_a}{f_a} = \frac{F_b}{f_b} = \frac{F_c}{f_c}$

Solution

Let  $F(x, y, z, a, b, c) = 0$  —  $\textcircled{1}$

&  $f(a, b, c) = 0$  —  $\textcircled{2}$

Diff  $\textcircled{1}$  &  $\textcircled{2}$  totally,

$$dF = \frac{\partial F}{\partial a} da + \frac{\partial F}{\partial b} db + \frac{\partial F}{\partial c} dc = 0$$
 —  $\textcircled{3}$

$$df = \frac{\partial f}{\partial a} da + \frac{\partial f}{\partial b} db + \frac{\partial f}{\partial c} dc = 0$$
 —  $\textcircled{4}$

Multiply  $\textcircled{3}$  by  $\frac{\partial f}{\partial c}$  and  $\textcircled{4}$  by  $\frac{\partial F}{\partial c}$  & Subtract

$$\left( \frac{\partial f}{\partial c} \frac{\partial F}{\partial a} - \frac{\partial F}{\partial c} \frac{\partial f}{\partial a} \right) da + \left( \frac{\partial f}{\partial c} \frac{\partial F}{\partial b} - \frac{\partial F}{\partial c} \frac{\partial f}{\partial b} \right) db = 0$$

$$(f_c F_a - F_c f_a) da + (F_b f_c - f_b F_c) db = 0$$
 —  $\textcircled{5}$

Let  $\frac{da}{db} = k$ , when  $da, db$  are the changes in parameters  $a$  &  $b$ . For different values of  $da$  &  $db$ ,  $k$  will be different and non zero. Equation (5) is satisfied only if

$$f_c F_a - F_c f_a = 0 \quad \& \quad f_c F_b - F_c f_b = 0$$

$$f_c F_a = F_c f_a \quad \& \quad f_c F_b = F_c f_b \quad \text{or}$$

$$\frac{F_a}{f_a} = \frac{F_c}{f_c} \quad (6) \quad \& \quad \frac{F_b}{f_b} = \frac{F_c}{f_c} \quad (7)$$

From (6) and (7) implies

$$\frac{F_a}{f_a} = \frac{F_b}{f_b} = \frac{F_c}{f_c} \quad \text{Required result.}$$

Q(4) Prove that the envelope of a plane which forms with the coordinate planes a tetrahedron of constant volume is a surface  $XYZ = \text{constant}$ .

Solution: Let the eq of a plane be

$$lx + my + nz = 1$$

This plane meets with the coordinate axes in the point  $(\frac{1}{l}, 0, 0)$ ,  $(0, \frac{1}{m}, 0)$  &  $(0, 0, \frac{1}{n})$  so the volume of tetrahedron is

$$|V| = \frac{1}{6} \begin{vmatrix} 0 & 0 & 0 & 1 \\ \frac{1}{l} & 0 & 0 & 1 \\ 0 & \frac{1}{m} & 0 & 1 \\ 0 & 0 & \frac{1}{n} & 1 \end{vmatrix} = -\frac{1}{6} \begin{vmatrix} \frac{1}{l} & 0 & 0 \\ 0 & \frac{1}{m} & 0 \\ 0 & 0 & \frac{1}{n} \end{vmatrix} = \frac{1}{6lmn}$$

As volume is constant

$$\frac{1}{6lmn} = C \quad \Rightarrow \quad \frac{1}{lmn} = 6C = C'$$

$$lmn = \frac{1}{C'} = C = 0$$

$$f_l = \frac{1}{-l^2 mn}, \quad f_m = -\frac{1}{l m^2 n}, \quad f_n = \frac{-1}{l m n^2}$$

Also  $F(x, y, z, l, m, n) = lx + my + nz - 1 = 0$

$$F_l = x, \quad F_m = y \quad \& \quad F_n = z$$

Then  $\frac{F_l}{f_l} = \frac{F_m}{f_m} = \frac{F_n}{f_n}$

$$\Rightarrow \frac{x}{\frac{-1}{l^2 mn}} = \frac{y}{\frac{-1}{l m^2 n}} = \frac{z}{\frac{-1}{l m n^2}} = k \text{ (say)}$$

$$\Rightarrow \frac{lx}{\frac{-1}{l mn}} = \frac{my}{\frac{-1}{l mn}} = \frac{nz}{\frac{-1}{l mn}} = k$$

$$\Rightarrow lx + my + nz = \frac{-k}{l mn} \quad \text{by (1)}$$

$$\Rightarrow lx + my + nz = -kC$$

$$\Rightarrow lx = my = nz = k'$$

$$x = \frac{k'}{l}, \quad y = \frac{k'}{m}, \quad z = \frac{k'}{n}$$

Then  $xyz = \frac{(k')^3}{l m n} = k''C \quad \text{by (1)}$   
 $= \text{constant}$