

(Exercise 6.3)

Q1 Check which of the following define linear transformations from \mathbb{R}^3 to \mathbb{R}^2 ?

$$(i) T(x_1, x_2, x_3) = (x_1 - x_2, x_1 - x_3)$$

Sol: Given transformation is

$$T(x_1, x_2, x_3) = (x_1 - x_2, x_1 - x_3)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

$$\text{and } u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$$

$$(i) \text{ Then we prove } T(u_1 + u_2) = T(u_1) + T(u_2)$$

$$\begin{aligned} \text{Now } T(u_1 + u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\ &= T(x_1 + y_1, x_2 + y_2, x_3 + y_3) \\ &= ((x_1 + y_1) - (x_2 + y_2), (x_1 + y_1) - (x_3 + y_3)) \\ &= (x_1 + y_1 - x_2 - y_2, x_1 + y_1 - x_3 - y_3) \\ &= (x_1 - x_2 + y_1 - y_2, x_1 - x_3 + y_1 - y_3) \\ &= (x_1 - x_2, x_1 - x_3) + (y_1 - y_2, y_1 - y_3) \\ &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\ &= T(u_1) + T(u_2) \end{aligned}$$

$$(ii) \text{ Let } \alpha \in \mathbb{R} \text{ and } u_1 = (x_1, x_2, x_3) \in \mathbb{R}^3$$

$$\text{Then we prove } T(\alpha u_1) = \alpha T(u_1)$$

$$\begin{aligned} \text{Now } T(\alpha u_1) &= T(\alpha(x_1, x_2, x_3)) \\ &= T(\alpha x_1, \alpha x_2, \alpha x_3) \\ &= (\alpha x_1 - \alpha x_2, \alpha x_1 - \alpha x_3) \\ &= \alpha(x_1 - x_2, x_1 - x_3) \\ &= \alpha T(x_1, x_2, x_3) \\ &= \alpha T(u_1) \end{aligned}$$

Hence, T is a linear transformation from \mathbb{R}^3 to \mathbb{R}^2

$$(ii) T(x_1, x_2, x_3) = (|x_1|, x_2 - x_3)$$

Sol. Given transformation is

$$T(x_1, x_2, x_3) = (|x_1|, x_2 - x_3)$$

$$\text{let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove
 (i) $T(u_1 + u_2) = T(u_1) + T(u_2)$

Now

$$\begin{aligned} T(u_1 + u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\ &= T(x_1 + y_1, x_2 + y_2, x_3 + y_3) \\ &= (|x_1 + y_1|, (x_2 + y_2) - (x_3 + y_3)) \end{aligned}$$

$$\therefore T(u_1 + u_2) = (|x_1 + y_1|, x_2 + y_2 - x_3 - y_3) \quad \text{--- (1)}$$

Now

$$\begin{aligned} T(u_1) + T(u_2) &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\ &= (|x_1|, x_2 - x_3) + (|y_1|, y_2 - y_3) \\ &= (|x_1| + |y_1|, x_2 - x_3 + y_2 - y_3) \\ \therefore T(u_1) + T(u_2) &= (|x_1| + |y_1|, x_2 + y_2 - x_3 - y_3) \quad \text{--- (2)} \end{aligned}$$

From (1) & (2)

$$T(u_1 + u_2) \neq T(u_1) + T(u_2)$$

Hence T is not a linear transformation from \mathbb{R}^3 to \mathbb{R}^2 .

$$(iii) T(x_1, x_2, x_3) = (x_1 + 1, x_2 + x_3)$$

Sol. Given transformation is

$$T(x_1, x_2, x_3) = (x_1 + 1, x_2 + x_3)$$

$$\text{let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove

$$(i) T(u_1 + u_2) = T(u_1) + T(u_2)$$

Now

$$T(u_1 + u_2) = T((x_1, x_2, x_3) + (y_1, y_2, y_3))$$

$$\begin{aligned}
 T(u_1+u_2) &= T(x_1+y_1, x_2+y_2, x_3+y_3) \\
 &= (x_1+y_1+1, x_2+y_2+x_3+y_3) \\
 T(u_1+u_2) &= (x_1+y_1+1, x_2+x_3+y_2+y_3) \quad \text{--- (1)}
 \end{aligned}$$

Now

$$\begin{aligned}
 T(u_1) + T(u_2) &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\
 &= (x_1+1, x_2+x_3) + (y_1+1, y_2+y_3) \\
 &= (x_1+1+y_1+1, x_2+x_3+y_2+y_3) \\
 T(u_1) + T(u_2) &= (x_1+y_1+2, x_2+x_3+y_2+y_3) \quad \text{--- (2)}
 \end{aligned}$$

From (1) & (2)

$$T(u_1+u_2) \neq T(u_1) + T(u_2)$$

Hence T is not a linear transformation from \mathbb{R}^3 to \mathbb{R}^2 .

$$(iv) \dots T(x_1, x_2, x_3) = (0, x_3)$$

Sol: Given transformation is

$$T(x_1, x_2, x_3) = (0, x_3)$$

$$\text{let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove.

$$(i) T(u_1+u_2) = T(u_1) + T(u_2)$$

Now:

$$\begin{aligned}
 T(u_1+u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\
 &= T(x_1+y_1, x_2+y_2, x_3+y_3) \\
 &= (0, x_3+y_3) \\
 &= (0, x_3) + (0, y_3) \\
 &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3)
 \end{aligned}$$

$$\therefore T(u_1+u_2) = T(u_1) + T(u_2)$$

(ii) Let $a \in \mathbb{R}$ & $u_1 = (x_1, x_2, x_3) \in \mathbb{R}^3$ then we prove

$$T(au_1) = aT(u_1)$$

$$\text{Now } T(au_1) = T(a(x_1, x_2, x_3))$$

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$$\begin{aligned}
 T(\alpha u_1) &= T(\alpha x_1, \alpha x_2, \alpha x_3) \\
 &= (\alpha, \alpha x_3) \\
 &= \alpha(0, x_3) \\
 &= \alpha T(x_1, x_2, x_3)
 \end{aligned}$$

$$T(\alpha u_1) = \alpha T(u_1)$$

Hence T is a linear transformation from \mathbb{R}^3 to \mathbb{R}^1 .

$$(v) T(x_1, x_2, x_3) = \left(\frac{x_1+x_2}{x_3}, x_3 \right)$$

Sol. Given transformation is

$$T(x_1, x_2, x_3) = \left(\frac{x_1+x_2}{x_3}, x_3 \right)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove

$$(i) T(u_1+u_2) = T(u_1) + T(u_2)$$

Now,

$$\begin{aligned}
 T(u_1+u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\
 &= T(x_1+y_1, x_2+y_2, x_3+y_3) \\
 &= \left(\frac{x_1+y_1+x_2+y_2}{x_3+y_3}, x_3+y_3 \right) \quad ①
 \end{aligned}$$

Now

$$\begin{aligned}
 T(u_1) + T(u_2) &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\
 &= \left(\frac{x_1+x_2}{x_3}, x_3 \right) + \left(\frac{y_1+y_2}{y_3}, y_3 \right) \\
 &= \left(\frac{x_1+x_2}{x_3} + \frac{y_1+y_2}{y_3}, x_3+y_3 \right) \\
 &= \left(\frac{y_3(x_1+x_2) + x_3(y_1+y_2)}{x_3 y_3}, x_3+y_3 \right) \quad ②
 \end{aligned}$$

From ① & ②

$$T(u_1+u_2) \neq T(u_1) + T(u_2)$$

Hence T is not a linear transformation from \mathbb{R}^3 to \mathbb{R}^1 .

$$(vi) T(x_1, x_2, x_3) = (3x_1 - 2x_2 + x_3, x_3 - 3x_2 - 2x_1)$$

Sol. Given transformation is

$$T(x_1, x_2, x_3) = (3x_1 - 3x_2 + x_3, x_3 - 3x_2 - 2x_1)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in R^3$ then we prove

$$(i) T(u_1 + u_2) = T(u_1) + T(u_2)$$

Now

$$\begin{aligned} T(u_1 + u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\ &= T(x_1 + y_1, x_2 + y_2, x_3 + y_3) \\ &= (3(x_1 + y_1) - 2(x_2 + y_2) + (x_3 + y_3), (x_3 + y_3) - 3(x_2 + y_2) - 2(x_1 + y_1)) \\ &= (3x_1 - 2x_2 + x_3 + 3y_1 - 2y_2 + y_3, x_3 - 3x_2 - 2x_1 + y_3 - 3y_2 - 2y_1) \\ &= (3x_1 - 2x_2 + x_3, x_3 - 3x_2 - 2x_1) + (3y_1 - 2y_2 + y_3, y_3 - 3y_2 - 2y_1) \\ &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\ &= T(u_1) + T(u_2) \end{aligned}$$

$$(ii) \text{ Let } \alpha \in R \text{ & } u_1 = (x_1, x_2, x_3) \in R^3 \text{ then we prove}$$

$$T(\alpha u_1) = \alpha T(u_1)$$

$$\text{Now } T(\alpha u_1) = T(\alpha(x_1, x_2, x_3))$$

$$= T(\alpha x_1, \alpha x_2, \alpha x_3)$$

$$= (3\alpha x_1 - 2\alpha x_2 + \alpha x_3, \alpha x_3 - 3\alpha x_2 - 2\alpha x_1)$$

$$= \alpha(3x_1 - 2x_2 + x_3, x_3 - 3x_2 - 2x_1)$$

$$= \alpha T(x_1, x_2, x_3)$$

$$= \alpha T(u_1)$$

Hence T is a linear transformation from R^3 to R^2 .

Q2 Show that each of the following defines linear transformation from R^3 to R^3 .

$$(i) T(x_1, x_2, x_3) = (x_1 - x_2, x_2 - x_3, x_1)$$

Sol. Given transformation is

$$T(x_1, x_2, x_3) = (x_1 - x_2, x_2 - x_3, x_1)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove

$$(i) T(u_1 + u_2) = T(u_1) + T(u_2)$$

Now

$$\begin{aligned} T(u_1 + u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\ &= T(x_1 + y_1, x_2 + y_2, x_3 + y_3) \\ &= ((x_1 + y_1) - (x_2 + y_2), (x_2 + y_2) - (x_3 + y_3), x_1 + y_1) \\ &= (x_1 + y_1 - x_2 - y_2, x_2 + y_2 - x_3 - y_3, x_1 + y_1) \\ &= (x_1 - x_2 + y_1 - y_2, x_2 - x_3 + y_2 - y_3, x_1 + y_1) \\ &= (x_1 - x_2, x_2 - x_3, x_1) + (y_1 - y_2, y_2 - y_3, y_1) \\ &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\ &= T(u_1) + T(u_2) \end{aligned}$$

Now

$$\begin{aligned} T(\alpha u_1) &= T(\alpha(x_1, x_2, x_3)) \\ &= T(\alpha x_1, \alpha x_2, \alpha x_3) \\ &= (\alpha x_1 - \alpha x_2, \alpha x_2 - \alpha x_3, \alpha x_1) \\ &= \alpha(x_1 - x_2, x_2 - x_3, x_1) \\ &= \alpha T(x_1, x_2, x_3) \\ &= \alpha T(u_1) \end{aligned}$$

Hence T is a linear transformation from \mathbb{R}^3 to \mathbb{R}^3

$$(ii) T(x_1, x_2, x_3) = (x_1 + x_2, -x_1 - x_2, x_3)$$

Sol. Given Transformation is

$$T(x_1, x_2, x_3) = (x_1 + x_2, -x_1 - x_2, x_3)$$

$$\text{let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove

$$(i) T(u_1 + u_2) = T(u_1) + T(u_2)$$

Now

$$\begin{aligned}
 T(u_1+u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\
 &= T(x_1+y_1, x_2+y_2, x_3+y_3) \\
 &= (x_1+y_1+x_2+y_2, -x_1-y_1-(x_2+y_2), x_3+y_3) \\
 &= (x_1+y_1+x_2+y_2, -x_1-y_1-x_2-y_2, x_3+y_3) \\
 &= (x_1+x_2+y_1+y_2, -x_1-x_2-y_1-y_2, x_3+y_3) \\
 &= (x_1+x_2, -x_1-x_2, x_3) + (y_1+y_2, -y_1-y_2, y_3) \\
 &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\
 &= T(u_1) + T(u_2).
 \end{aligned}$$

(ii) Let $\alpha \in \mathbb{R}$ & $u_1 = (x_1, x_2, x_3) \in \mathbb{R}^3$ then we prove

$$T(\alpha u_1) = \alpha T(u_1)$$

Now

$$\begin{aligned}
 T(\alpha u_1) &= T(\alpha(x_1, x_2, x_3)) \\
 &= T(\alpha x_1, \alpha x_2, \alpha x_3) \\
 &= (\alpha x_1 + \alpha x_2, -\alpha x_1 - \alpha x_2, \alpha x_3) \\
 &= \alpha(x_1 + x_2, -x_1 - x_2, x_3) \\
 &= \alpha T(x_1, x_2, x_3) \\
 &= \alpha T(u_1)
 \end{aligned}$$

Hence T is a linear transformation from \mathbb{R}^3 to \mathbb{R}^3 .

$$(iii) T(x_1, x_2, x_3) = (x_2, -x_1, -x_3)$$

Soln Given transformation is

$$T(x_1, x_2, x_3) = (x_2, -x_1, -x_3)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove

$$(i) T(u_1+u_2) = T(u_1) + T(u_2)$$

Now

$$T(u_1+u_2) = T((x_1, x_2, x_3) + (y_1, y_2, y_3))$$

$$\begin{aligned}
 T(u_1+u_2) &= T(x_1+y_1, x_2+y_2, x_3+y_3) \\
 &= (x_1+y_1, -x_1-y_1, -x_3-y_3) \\
 &= (x_2+y_2, -x_1-y_1, -x_3-y_3) \\
 &= (x_2, -x_1, -x_3) + (y_2, -y_1, -y_3) \\
 &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\
 &= T(u_1) + T(u_2)
 \end{aligned}$$

(iii) Let $\alpha \in \mathbb{R}$ & $u_1 = (x_1, x_2, x_3) \in \mathbb{R}^3$ Then we prove

$$T(\alpha u_1) = \alpha T(u_1)$$

Now

$$\begin{aligned}
 T(\alpha u_1) &= T(\alpha(x_1, x_2, x_3)) \\
 &= T(\alpha x_1, \alpha x_2, \alpha x_3) \\
 &= (\alpha x_2, -\alpha x_1, -\alpha x_3) \\
 &= \alpha(x_2, -x_1, -x_3) \\
 &= \alpha T(x_1, x_2, x_3) \\
 &= \alpha T(u_1)
 \end{aligned}$$

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Hence T is a linear transformation from \mathbb{R}^3 to \mathbb{R}^3 .

$$(iv) T(x_1, x_2, x_3) = (x_1 - 3x_2 - 2x_3, x_2 - 4x_3, x_3)$$

Sol. Given transformation is

$$T(x_1, x_2, x_3) = (x_1 - 3x_2 - 2x_3, x_2 - 4x_3, x_3)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ Then we prove

$$(i) T(u_1+u_2) = T(u_1) + T(u_2)$$

Now

$$\begin{aligned}
 T(u_1+u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\
 &= T(x_1+y_1, x_2+y_2, x_3+y_3) \\
 &= ((x_1+y_1) - 3(x_2+y_2) - 2(x_3+y_3), (x_2+y_2) - 4(x_3+y_3), x_3+y_3) \\
 &= (x_1 - 3x_2 - 2x_3 + y_1 - 3y_2 - 2y_3, x_2 - 4x_3 + y_2 - 4y_3, x_3 + y_3)
 \end{aligned}$$

$$\begin{aligned}
 T(u_1+u_2) &= (x_1-3x_2-2x_3, x_2-4x_3, x_3) + (y_1-3y_2-2y_3, y_2-4y_3, y_3) \\
 &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\
 &= T(u_1) + T(u_2)
 \end{aligned}$$

(ii) let $\alpha \in \mathbb{R}$ & $u_1 = (x_1, x_2, x_3) \in \mathbb{R}^3$ then we have
 $T(\alpha u_1) = \alpha T(u_1)$

Now

$$\begin{aligned}
 T(\alpha u_1) &= T(\alpha(x_1, x_2, x_3)) \\
 &= T(\alpha x_1, \alpha x_2, \alpha x_3) \\
 &= (3\alpha x_1 - 3\alpha x_2 - 2\alpha x_3, \alpha x_2 - 4\alpha x_3, \alpha x_3) \\
 &= \alpha(3x_1 - 3x_2 - 2x_3, x_2 - 4x_3, x_3) \\
 &= \alpha T(x_1, x_2, x_3) \\
 &= \alpha T(u_1)
 \end{aligned}$$

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Hence T is a linear transformation from \mathbb{R}^3 to \mathbb{R}^3 .

$$(v) T(x_1, x_2, x_3) = (x_1+x_3, x_1-x_3, x_2)$$

Sol. Given Transformation is

$$T(x_1, x_2, x_3) = (x_1+x_3, x_1-x_3, x_2)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we have

$$T(u_1+u_2) = T(u_1) + T(u_2)$$

Now

$$\begin{aligned}
 T(u_1+u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\
 &= T(x_1+y_1, x_2+y_2, x_3+y_3) \\
 &= ((x_1+y_1)+(x_3+y_3), (x_1+y_1)-(x_3+y_3), x_2+y_2) \\
 &= (x_1+x_3+y_1+y_3, x_1-x_3+y_1-y_3, x_2+y_2) \\
 &= (x_1+x_3, x_1-x_3, x_2) + (y_1+y_3, y_1-y_3, y_2) \\
 &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\
 &= T(u_1) + T(u_2)
 \end{aligned}$$

(ii) Let $\alpha \in \mathbb{R}$ & $u_1 = (x_1, x_2, x_3) \in \mathbb{R}^3$ then we prove

$$T(\alpha u_1) = \alpha T(u_1)$$

Now

$$\begin{aligned} T(\alpha u_1) &= T(\alpha(x_1, x_2, x_3)) \\ &= T(\alpha x_1, \alpha x_2, \alpha x_3) \\ &= (\alpha x_1 + \alpha x_3, \alpha x_1 - \alpha x_3, \alpha x_2) \\ &= \alpha(x_1 + x_3, x_1 - x_3, x_2) \\ &= \alpha T(x_1, x_2, x_3) \\ &= \alpha T(u_1) \end{aligned}$$

Hence T is a linear transformation from \mathbb{R}^3 to \mathbb{R}^3 .

Q3 Show that each of the following transformations is not linear.

(i) $T: \mathbb{R}^2 \rightarrow \mathbb{R}$ defined by $T(x_1, x_2) = x_1 x_2$

Sol. Given transformation is

$$T(x_1, x_2) = x_1 x_2$$

$$\text{Let } u_1 = (x_1, x_2)$$

& $u_2 = (y_1, y_2) \in \mathbb{R}^2$ then we prove

$$(i) T(u_1 + u_2) = T(u_1) + T(u_2)$$

Now

$$\begin{aligned} T(u_1 + u_2) &= T((x_1, x_2) + (y_1, y_2)) \\ &= T(x_1 + y_1, x_2 + y_2) \\ &= (x_1 + y_1)(x_2 + y_2) \quad \text{--- (1)} \end{aligned}$$

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$$T(u_1) + T(u_2) = T(x_1, x_2) + T(y_1, y_2)$$

$$= x_1 y_2 + y_1 y_2 \quad \text{--- (2)}$$

$$\text{from (1) & (2) } T(u_1 + u_2) \neq T(u_1) + T(u_2).$$

Hence T is not a linear transformation from \mathbb{R}^2 to \mathbb{R}

(ii) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by $T(x_1, x_2) = (x_1+1, 2x_2, x_1+x_2)$

Sol: Given transformation is

$$T(x_1, x_2) = (x_1+1, 2x_2, x_1+x_2)$$

$$\text{Let } u_1 = (x_1, x_2)$$

& $u_2 = (y_1, y_2) \in \mathbb{R}^2$ then we prove

$$(i) T(u_1+u_2) = T(u_1) + T(u_2)$$

Now

$$T(u_1+u_2) = T((x_1, x_2) + (y_1, y_2))$$

$$= T(x_1+y_1, x_2+y_2)$$

$$= (x_1+y_1+1, 2(x_2+y_2), (x_1+y_1)+(x_2+y_2))$$

$$= (x_1+y_1+1, 2x_2+2y_2, x_1+x_2+y_1+y_2) \quad \text{--- (1)}$$

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$$T(u_1)+T(u_2) = T(x_1, x_2) + T(y_1, y_2)$$

$$= (x_1+1, 2x_2, x_1+x_2) + (y_1+1, 2y_2, y_1+y_2)$$

$$= (x_1+y_1+2, 2x_2+2y_2, x_1+x_2+y_1+y_2) \quad \text{--- (2)}$$

from (1) & (2)

$$T(u_1+u_2) \neq T(u_1) + T(u_2)$$

Hence T is not a linear transformation from \mathbb{R}^2 to \mathbb{R}^3 .

(iii) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $T(x_1, x_2, x_3) = (|x_1|, 0)$

Sol: Given transformation is

$$T(x_1, x_2, x_3) = (|x_1|, 0)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove

$$(i) T(u_1+u_2) = T(u_1) + T(u_2)$$

Now

$$T(u_1+u_2) = T((x_1, x_2, x_3) + (y_1, y_2, y_3))$$

$$= T(x_1+y_1, x_2+y_2, x_3+y_3)$$

$$T(u_1+u_2) = (|x_1+y_1|, 0) \quad \text{--- } ①$$

4

$$\begin{aligned} T(u_1)+T(u_2) &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\ &= (|x_1|, 0) + (|y_1|, 0) \\ &= (|x_1| + |y_1|, 0) \quad \text{--- } ② \end{aligned}$$

From ① & ②

$$T(u_1+u_2) \neq T(u_1) + T(u_2)$$

Hence T is not a linear transformation from \mathbb{R}^3 to \mathbb{R}^2 .

(iv) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(x_1, x_2) = (x_1^2, x_2^2)$.

Given transformation is

$$T(x_1, x_2) = (x_1^2, x_2^2)$$

$$\text{Let } u_1 = (x_1, x_2)$$

& $u_2 = (y_1, y_2) \in \mathbb{R}^2$ then we prove

$$(i) T(u_1+u_2) = T(u_1) + T(u_2)$$

Now

$$\begin{aligned} T(u_1+u_2) &= T((x_1, x_2) + (y_1, y_2)) \\ &= T(x_1+y_1, x_2+y_2) \\ &= ((x_1+y_1)^2, (x_2+y_2)^2) \quad \text{--- } ① \end{aligned}$$

4

$$\begin{aligned} T(u_1)+T(u_2) &= T(x_1, x_2) + T(y_1, y_2) \\ &= (x_1^2, x_2^2) + (y_1^2, y_2^2) \\ &= (x_1^2 + y_1^2, x_2^2 + y_2^2) \quad \text{--- } ② \end{aligned}$$

from ① & ②

$$T(u_1+u_2) \neq T(u_1) + T(u_2)$$

Hence T is not a linear transformation from \mathbb{R}^2 to \mathbb{R}^2 .

(v) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(x_1, x_2, x_3) = (x_1, x_2, x_3) + (1, 1, 1)$

Sol: Given transformation is

$$T(x_1, x_2, x_3) = (x_1, x_2, x_3) + (1, 1, 1)$$

$$\text{Let } u_1 = (x_1, x_2, x_3)$$

& $u_2 = (y_1, y_2, y_3) \in \mathbb{R}^3$ then we prove

$$(i) T(u_1 + u_2) = T(u_1) + T(u_2)$$

Now

$$\begin{aligned} T(u_1 + u_2) &= T((x_1, x_2, x_3) + (y_1, y_2, y_3)) \\ &= T(x_1 + y_1, x_2 + y_2, x_3 + y_3) \\ &= (x_1 + y_1, x_2 + y_2, x_3 + y_3) + (1, 1, 1) \\ &= (x_1 + y_1 + 1, x_2 + y_2 + 1, x_3 + y_3 + 1) \quad \text{--- (1)} \end{aligned}$$

&

$$\begin{aligned} T(u_1) + T(u_2) &= T(x_1, x_2, x_3) + T(y_1, y_2, y_3) \\ &= (x_1, x_2, x_3) + (1, 1, 1) + (y_1, y_2, y_3) + (1, 1, 1) \\ &= (x_1 + 1, x_2 + 1, x_3 + 1) + (y_1 + 1, y_2 + 1, y_3 + 1) \\ &= (x_1 + y_1 + 2, x_2 + y_2 + 2, x_3 + y_3 + 2) \quad \text{--- (2)} \end{aligned}$$

From (1) & (2)

$$T(u_1 + u_2) \neq T(u_1) + T(u_2)$$

Hence T is not a linear transformation from \mathbb{R}^3 to \mathbb{R}^3 .

Q3 Determine which of the following transformations are linear:

(a) $T: M_{22} \rightarrow \mathbb{R}$ defined by

$$(ii) T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = a+d$$

Sol: Given transformation is

$$T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = a+d$$

$$\text{Let } A_1 = \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}$$

$$\text{& } A_2 = \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix} \in M_{22} \text{ then we prove}$$

$$(i) T(A_1 + A_2) = T(A_1) + T(A_2)$$

Now

$$T(A_1 + A_2) = T\left(\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix} + \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix}\right)$$

$$= T\left(\begin{bmatrix} a_1+a_2 & b_1+b_2 \\ c_1+c_2 & d_1+d_2 \end{bmatrix}\right)$$

$$= a_1 + a_2 + d_1 + d_2 \quad \text{--- (1)}$$

$$T(A_1) + T(A_2) = T\left(\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}\right) + T\left(\begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix}\right)$$

$$= a_1 + d_1 + a_2 + d_2$$

$$= a_1 + a_2 + d_1 + d_2 \quad \text{--- (2)}$$

from (1) & (2)

$$T(A_1 + A_2) = T(A_1) + T(A_2)$$

$$(ii) \text{ Let } a \in R \text{ & } A_1 = \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix} \in M_{22} \text{ then we prove}$$

$$T(aA_1) = aT(A_1)$$

$$\text{Now } T(aA_1) = T\left(a\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}\right)$$

$$= T\left(\begin{bmatrix} aa_1 & ab_1 \\ ac_1 & ad_1 \end{bmatrix}\right)$$

$$= aa_1 + ad_1$$

$$= a(a_1 + d_1)$$

$$= aT\left(\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}\right)$$

$$= aT(A_1)$$

Hence T is a linear transformation from M_{22} to R

(ii) $T: M_{22} \rightarrow R$ defined by

$$T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = ad - bc$$

Sol. Given transformation is

$$T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = ad - bc$$

$$\text{Let } A_1 = \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}$$

$$\text{& } A_2 = \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix}$$

Then we prove

$$T(A_1 + A_2) = T(A_1) + T(A_2)$$

Now

$$T(A_1 + A_2) = T\left(\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix} + \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix}\right)$$

$$= T\left(\begin{bmatrix} a_1+a_2 & b_1+b_2 \\ c_1+c_2 & d_1+d_2 \end{bmatrix}\right)$$

$$= (a_1+a_2)(d_1+d_2) - (b_1+b_2)(c_1+c_2) \quad \text{--- (1)}$$

Now

$$T(A_1) + T(A_2) = T\left(\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}\right) + T\left(\begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix}\right)$$

$$= a_1d_1 - b_1c_1 + a_2d_2 - b_2c_2 \quad \text{--- (2)}$$

From (1) & (2)

$$T(A_1 + A_2) \neq T(A_1) + T(A_2)$$

Hence T is a linear transformation from M_{22} to R .

(b) $T: P_2(x) \rightarrow P_2(x)$ defined by

$$(i) T(a+bx+cx^2) = a+(b+c)x+(2a-3b)x^2$$

Sol. Given transformation is

$$T(a+bx+cx^2) = a+(b+c)x+(2a-3b)x^2$$

$$\text{Let } u = a + bx + cx^2$$

& $v = p + qx + rx^2 \in P_2(x)$ then we prove

$$(i) T(u+v) = T(u) + T(v)$$

Now

$$\begin{aligned} T(u+v) &= T((a+bx+cx^2)+(p+qx+rx^2)) \\ &= T(a+p+(b+q)x+(c+r)x^2) \\ &= (a+p)+(b+q+c+r)x+(2a+2p-3b-3q)x^2 \\ &= (a+p)+(b+c+q+r)x+(2a-3b+2p-3q)x^2 \\ &= (a+(b+c)x+(2a-3b)x^2)+(p+(q+r)x+(2p-3q)x^2) \\ &= T(a+bx+cx^2)+T(p+qx+rx^2) \\ &= T(u)+T(v) \end{aligned}$$

$$(ii) \text{ Let } k \in \mathbb{R} \text{ & } u = a + bx + cx^2 \text{ then we prove}$$

$$T(ku) = kT(u)$$

Now

$$\begin{aligned} T(ku) &= T(k(a+bx+cx^2)) \\ &= T(ka+kbx+kcx^2) \\ &= ka+(kb+kc)x+(2kd-3kb)x^2 \\ &= k(a+(b+c)x+(2a-3b)x^2) \\ &= kT(a+bx+cx^2) \\ &= kT(u) \end{aligned}$$

Hence T is a linear transformation from $P_2(x)$ to $P_2(x)$.

(ii). $T: P_2(x) \rightarrow P_2(x)$ defined by

$$T(a+bx+cx^2) = (a+1) + bx + cx^2$$

Sol. Given transformation is

$$T(a+bx+cx^2) = (a+1) + bx + cx^2$$

$$\text{Let } u = a + bx + cx^2$$

& $v = p + qx + rx^2 \in P_2(x)$ then we prove

$$(i) T(u+v) = T(u) + T(v)$$

Now

$$\begin{aligned} T(u+v) &= T((a+bx+cx^2) + (b+gx+hx^2)) \\ &= T((a+b) + (b+g)x + (c+h)x^2) \\ &= (a+b+1) + (b+g)x + (c+h)x^2 \quad \text{--- } ① \end{aligned}$$

4

$$\begin{aligned} T(u) + T(v) &= T(a+bx+cx^2) + T(b+gx+hx^2) \\ &= (a+1) + bx + cx^2 + (b+1) + gx + hx^2 \\ &= (a+b+2) + (b+g)x + (c+h)x^2 \quad \text{--- } ② \end{aligned}$$

From ① & ②

$$T(u+v) \neq T(u) + T(v)$$

Hence T is not a linear transformation from $P_2(x)$ to $P_2(x)$.

Q5. If A is an $m \times n$ matrix, show that

$T(x) = Ax$ is a linear transformation from \mathbb{R}^n to \mathbb{R}^m

where

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \in \mathbb{R}^n$$

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Sol: Given transformation is

$$T(x) = Ax$$

Suppose

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \hline \cdots & \cdots & \cdots & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \text{and} \quad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \in \mathbb{R}^n$$

Then we prove

$$T(x+y) = T(x) + T(y)$$

Now

$$T(u+y) =$$

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Q6 Determine whether or not the following linear transformation

are one-to-one:

$$(i) T: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \text{ defined by } T(x_1, x_2) = (x_1 + x_2, x_1 - x_2, x_1 + 2x_2)$$

Sol: Given linear transformation is

$$T(x_1, x_2) = (x_1 + x_2, x_1 - x_2, x_1 + 2x_2)$$

$$\text{Let } \mathbf{x} = (x_1, x_2)$$

$$\text{And } \mathbf{y} = (y_1, y_2) \in \mathbb{R}^2$$

$$\text{Then } T(\mathbf{x}) = (x_1 + x_2, x_1 - x_2, x_1 + 2x_2)$$

$$\text{And } T(\mathbf{y}) = (y_1 + y_2, y_1 - y_2, y_1 + 2y_2)$$

$$\text{Suppose } T(\mathbf{x}) = T(\mathbf{y})$$

$$\Rightarrow (x_1 + x_2, x_1 - x_2, x_1 + 2x_2) = (y_1 + y_2, y_1 - y_2, y_1 + 2y_2)$$

$$\Rightarrow x_1 + x_2 = y_1 + y_2 \quad \dots \textcircled{1}$$

$$x_1 - x_2 = y_1 - y_2 \quad \dots \textcircled{2}$$

$$x_1 + 2x_2 = y_1 + 2y_2 \quad \dots \textcircled{3}$$

Adding $\textcircled{1}$ & $\textcircled{2}$

$$2x_1 = 2y_1$$

$$\boxed{x_1 = y_1}$$

Put in $\textcircled{1}$

$$x_1 + x_2 = x_1 + y_2$$

$$\Rightarrow \boxed{x_2 = y_2}$$

$$\text{Hence } (x_1, x_2) = (y_1, y_2)$$

$$\text{or } \mathbf{x} = \mathbf{y}$$

$$\text{Hence } T(\mathbf{x}) = T(\mathbf{y}) \Rightarrow \mathbf{x} = \mathbf{y}$$

Hence T is one-to-one

$$(ii) T: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \text{ defined by } T(x_1, x_2, x_3) = (x_1 - x_2, x_3)$$

Sol: Given linear transformation is

$$T(x_1, x_2, x_3) = (x_1 - x_2, x_3)$$

Let $x = (x_1, x_2, x_3)$
 $\& y = (y_1, y_2, y_3) \in \mathbb{R}^3$

Then $T(x) = (x_1 - x_2, x_3)$

$\& T(y) = (y_1 - y_2, y_3)$

Suppose $T(x) = T(y)$

$\Rightarrow (x_1 - x_2, x_3) = (y_1 - y_2, y_3)$

$\Rightarrow x_1 - x_2 = y_1 - y_2 \quad \text{--- (1)}$

$x_3 = y_3 \quad \text{--- (2)}$

From (1) we cannot conclude that

$x_1 = y_1 \& x_2 = y_2$

Hence $T(x) = T(y) \not\Rightarrow x = y$

So T is not one-to-one.

(iii) $T: \mathbb{R}^2 \longrightarrow \mathbb{R}^3$ defined by $T(x_1, x_2) = (x_1, x_1 + x_2, x_1 - x_2)$

Sol. Given linear transformation is

$T(x_1, x_2) = (x_1, x_1 + x_2, x_1 - x_2)$

Let $x = (x_1, x_2)$

$\& y = (y_1, y_2) \in \mathbb{R}^2$

Then $T(x) = (x_1, x_1 + x_2, x_1 - x_2)$

$\& T(y) = (y_1, y_1 + y_2, y_1 - y_2)$

Suppose $T(x) = T(y)$

$\Rightarrow (x_1, x_1 + x_2, x_1 - x_2) = (y_1, y_1 + y_2, y_1 - y_2)$

or $x_1 = y_1 \quad \text{--- (1)}$

$x_1 + x_2 = y_1 + y_2 \quad \text{--- (2)}$

$x_1 - x_2 = y_1 - y_2 \quad \text{--- (3)}$

(1) \Rightarrow $\boxed{x_1 = y_1}$

Sub. (2) + (3)

$2x_2 = 2y_2 \Rightarrow \boxed{x_2 = y_2}$

$$\text{Hence } (x_1, x_2) = (y_1, y_2)$$

$$\text{or } x = y$$

$$\text{So } T(x) = T(y) \Rightarrow x = y$$

Hence T is one-to-one.

Q7 Let C be the vector space of complex numbers over the field of reals & $T: C \rightarrow C$ be defined by $T(z) = \bar{z}$ where \bar{z} denotes the complex conjugate of z . Show that T is linear.

Sol. Given transformation is

$$T(z) = \bar{z}$$

Let $z_1, z_2 \in C$ then we have

$$(i) \quad T(z_1 + z_2) = T(z_1) + T(z_2)$$

Now

$$\begin{aligned} T(z_1 + z_2) &= \overline{z_1 + z_2} \\ &= \bar{z}_1 + \bar{z}_2 \\ &= T(z_1) + T(z_2) \end{aligned}$$

(ii) Let $a \in R$ & $z_1 \in C$ then we have

$$T(az_1) = aT(z_1)$$

Now

$$\begin{aligned} T(az_1) &= \overline{az_1} \\ &= a\bar{z}_1 \quad \because a \in R \\ &= aT(z_1) \end{aligned}$$

Hence T is a linear transformation from C to C .

Q8 Let V be the vector space $P_n(x)$ of polynomials $p(x)$ with real coefficients & of degree not exceeding n together with the zero polynomial. Let $T: V \rightarrow V$

be defined by $T(p(x)) = p(x+1)$

Show that T is linear.

Ques: Given transformation is

$$T(p(x)) = p(x+1)$$

$$\text{Let } p_1(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$$

$$\text{& } p_2(x) = b_0 + b_1x + b_2x^2 + \dots + b_nx^n \in V$$

$$\text{Then we prove } T(p_1(x) + p_2(x)) = T(p_1(x)) + T(p_2(x))$$

Now

$$\begin{aligned} T(p_1(x) + p_2(x)) &= T((a_0 + a_1x + \dots + a_nx^n) + (b_0 + b_1x + \dots + b_nx^n)) \\ &= T((a_0 + b_0) + (a_1 + b_1)x + \dots + (a_n + b_n)x^n) \\ &= (a_0 + b_0) + (a_1 + b_1)(x+1) + \dots + (a_n + b_n)(x+1)^n \\ &= [a_0 + a_1(x+1) + \dots + a_n(x+1)^n] + [b_0 + b_1(x+1) + \dots + b_n(x+1)^n] \\ &= T(a_0 + a_1x + \dots + a_nx^n) + T(b_0 + b_1x + \dots + b_nx^n) \\ &= T(p_1(x)) + T(p_2(x)) \end{aligned}$$

$$(ii) \text{ Let } a \in R \text{ & } p_1(x) = a_0 + a_1x + \dots + a_nx^n$$

$$\text{then we prove } T(ap_1(x)) = aT(p_1(x))$$

Now

$$\begin{aligned} T(ap_1(x)) &= T(a(a_0 + a_1x + \dots + a_nx^n)) \\ &= T(aa_0 + aax_1 + \dots + aax_n) \\ &= a a_0 + a a_1(x+1) + \dots + a a_n(x+1)^n \\ &= a(a_0 + a_1(x+1) + \dots + a_n(x+1)^n) \\ &= aT(a_0 + a_1x + \dots + a_nx^n) \\ &= aT(p_1(x)) \end{aligned}$$

Hence T is a linear transformation from V to V .

Q.9 Let $v_1 = (1, 1, 1)$, $v_2 = (1, 1, 0)$ & $v_3 = (1, 0, 0)$ be a basis for R^3 . Find a linear transformation $T: R^3 \rightarrow R^2$ s.t. $T(v_1) = (1, 0)$, $T(v_2) = (2, -1)$ & $T(v_3) = (4, 3)$.

Sol. Let $\mathbf{x} = (x_1, x_2, x_3)$ be any vector of \mathbb{R}^3 then
for scalars $\alpha_1, \alpha_2, \alpha_3$

$$\mathbf{x} = \alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \alpha_3 \mathbf{v}_3$$

$$= \alpha_1(1, 1, 1) + \alpha_2(1, 1, 0) + \alpha_3(1, 0, 0)$$

$$(x_1, x_2, x_3) = (\alpha_1 + \alpha_2 + \alpha_3, \alpha_1 + \alpha_2, \alpha_1)$$

$$\Rightarrow \alpha_1 + \alpha_2 + \alpha_3 = x_1 \quad \text{--- (1)}$$

$$\alpha_1 + \alpha_2 = x_2 \quad \text{--- (2)}$$

$$\alpha_1 = x_3 \quad \text{--- (3)}$$

$$(3) \Rightarrow \boxed{\alpha_1 = x_3}$$

Put in (2)

$$x_3 + \alpha_2 = x_2 \Rightarrow \boxed{\alpha_2 = x_2 - x_3}$$

Put in (1)

$$x_3 + x_2 - x_3 + \alpha_3 = x_1$$

$$\boxed{\alpha_3 = x_1 - x_2}$$

So,

$$\mathbf{x} = x_3 \mathbf{v}_1 + (x_2 - x_3) \mathbf{v}_2 + (x_1 - x_2) \mathbf{v}_3$$

Applying T on both sides

$$T(\mathbf{x}) = T(x_3 \mathbf{v}_1 + (x_2 - x_3) \mathbf{v}_2 + (x_1 - x_2) \mathbf{v}_3)$$

$$= x_3 T(\mathbf{v}_1) + (x_2 - x_3) T(\mathbf{v}_2) + (x_1 - x_2) T(\mathbf{v}_3) \quad \text{(As } T \text{ is linear)}$$

$$= x_3(1, 0) + (x_2 - x_3)(2, -1) + (x_1 - x_2)(4, 3)$$

$$= (x_3, 0) + (2x_2 - 2x_3, -x_2 + x_3) + (4x_1 - 4x_2, 3x_1 - 3x_2)$$

$$= (x_3 + 2x_2 - 2x_3 + 4x_1 - 4x_2, -x_2 + x_3 + 3x_1 - 3x_2)$$

$$T(x_1, x_2, x_3) = (4x_1 - 2x_2 - x_3, 3x_1 - 4x_2 + x_3)$$

Which is req. linear transformation from \mathbb{R}^3 to \mathbb{R}^2

Q10 Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}$ be the linear transformation for which

$$T(1, 1) = 3 \text{ & } T(0, 1) = -2 \text{ Find, } T(x_1, x_2)$$

Bol. First we prove that the vectors $(1,1)$ & $(0,1)$ form a basis for \mathbb{R}^2 .

Suppose for scalars $a, b \in \mathbb{R}$

$$a(1,1) + b(0,1) = 0$$

$$(a, a) + (0, b) = 0$$

$$(a, a+b) = 0$$

$$\Rightarrow a = 0 \quad \text{--- (1)}$$

$$a+b = 0 \quad \text{--- (2)}$$

$$(1) \Rightarrow a = 0$$

$$(2) \Rightarrow b = 0$$

Hence vectors $(1,1)$ & $(0,1)$ are linearly independent.

As there are two linearly independent vectors in \mathbb{R}^2

So $(1,1)$ & $(0,1)$ form a basis for \mathbb{R}^2

Suppose $(x_1, x_2) \in \mathbb{R}^2$ be an arbitrary vector

$$\text{then } (x_1, x_2) = a(1,1) + b(0,1) \quad \text{where } a, b \in \mathbb{R}$$

$$\text{or } (x_1, x_2) = (a, a+b)$$

$$\Rightarrow a = x_1 \quad \text{--- (1)}$$

$$a+b = x_2 \quad \text{--- (2)}$$

$$(1) \Rightarrow a = x_1$$

Put in (2)

$$x_1 + b = x_2 \Rightarrow b = x_2 - x_1$$

So

$$(x_1, x_2) = x_1(1,1) + (x_2 - x_1)(0,1)$$

Applying T on both sides

$$T(x_1, x_2) = T(x_1(1,1) + (x_2 - x_1)(0,1))$$

$$= x_1 T(1,1) + (x_2 - x_1) T(0,1)$$

$$= x_1(3) + (x_2 - x_1)(-2)$$

$$= 3x_1 - 2x_2 + 2x_1$$

$$T(x_1, x_2) = 5x_1 - 2x_2 \text{ which is } T \text{ in terms of co-ords.}$$

Q11. Let $D : P_2(x) \rightarrow P_2(x)$ be the differentiation operator

& $D(p(x)) = p'(x)$ for all $p(x) \in P_2(x)$. Find $N(D)$.

Sol. Given operator is.

$$D(p(x)) = p'(x)$$

Here $N(D)$ will consist of those polynomials in $P_2(x)$ for which $D(p(x)) = 0$.

Since we know that

$$D(p(x)) = 0 \text{ if } p(x) = \text{Const. polynomial}$$

So $N(D)$ will consist of all Const. polynomials.

Q12. Define $T : R^3 \rightarrow R^3$ by $T(x_1, x_2, x_3) = (-x_3, x_1, x_1 + x_3)$.

Find $N(T)$. Is T one-to-one?

Sol. Given transformation is

$$T(x_1, x_2, x_3) = (-x_3, x_1, x_1 + x_3)$$

$$\text{Here } N(T) = \{(x_1, x_2, x_3) \in R^3 : T(x_1, x_2, x_3) = (0, 0, 0)\}$$

$$\text{Now } T(x_1, x_2, x_3) = (0, 0, 0)$$

$$\Rightarrow (-x_3, x_1, x_1 + x_3) = (0, 0, 0)$$

$$\Rightarrow -x_3 = 0 \quad \text{--- (1)}$$

$$x_1 = 0 \quad \text{--- (2)}$$

$$x_1 + x_3 = 0 \quad \text{--- (3)}$$

$$(1) \Rightarrow x_3 = 0$$

$$(2) \Rightarrow x_1 = 0$$

which shows that $N(T)$ will consist of all vectors of the form $(0, x_2, 0)$. Which is x_2 -axis.

$$\text{i.e., } N(T) = \{(0, x_2, 0) \in R^3 : x_2 \in R\}$$

Since $N(T) = (0, x_2, 0) \neq (0, 0, 0)$. So T is not one-to-one.

Q13 Suppose U, V & W are vector spaces over the same field F . Let $T: U \rightarrow V$ & $S: V \rightarrow W$ be linear transformations. The transformation $S \circ T: U \rightarrow W$ is defined by $(S \circ T)(u) = S(T(u))$, for all $u \in U$. Show that $S \circ T$ is a linear transformation.

Sol:

Here $S \circ T: U \rightarrow W$ be defined as

$$(S \circ T)(u) = S(T(u)) \quad \text{for all } u \in U$$

Let $u_1, u_2 \in U$ then we prove

$$(S \circ T)(u_1 + u_2) = (S \circ T)(u_1) + (S \circ T)(u_2)$$

Now

$$\begin{aligned} (S \circ T)(u_1 + u_2) &= S(T(u_1 + u_2)) && \text{By def. of } S \circ T \\ &= S(T(u_1) + T(u_2)) && \because T \text{ is linear} \\ &= S(T(u_1)) + S(T(u_2)) && \because S \text{ is linear} \\ &= (S \circ T)(u_1) + (S \circ T)(u_2) \end{aligned}$$

(ii). Let $\alpha \in F$ & $u \in U$ then we prove

$$(S \circ T)(\alpha u) = \alpha(S \circ T)(u)$$

Now

$$\begin{aligned} (S \circ T)(\alpha u) &= S(T(\alpha u)) && \text{By def of } S \circ T \\ &= S(\alpha T(u)) && \because T \text{ is linear} \\ &= \alpha S(T(u)) && \because S \text{ is linear} \\ &= \alpha(S \circ T)(u) \end{aligned}$$

Hence $S \circ T$ is a linear transformation from U to W .

Q14 Let U & V be two vector spaces over the same field F . Denote the set of all linear transformations from U into V by $L(U, V)$. Show that $L(U, V)$ is a vector space over F with vector space operations as defined in example 31.

Sol. Consider the set $L(U, V)$. Let $S, T \in L(U, V)$ then $S: U \rightarrow V$ & $T: U \rightarrow V$ be two linear transformations. Define

$S+T: U \rightarrow V$ & $\alpha S: U \rightarrow V$ by

$$(S+T)(u) = S(u) + T(u)$$

$$(\alpha S)(u) = \alpha S(u) \quad \text{for all } u \in U \text{ & } \alpha \in F$$

First we show that $L(U, V)$ is an abelian gr. under +.

(i) closure law

Let $S, T \in L(U, V)$, then we show $S+T \in L(U, V)$.

$$\text{Now } (S+T)(u_1 + u_2) = S(u_1 + u_2) + T(u_1 + u_2) \quad \text{By def. of } S+T$$

$$= S(u_1) + S(u_2) + T(u_1) + T(u_2) \quad \because S, T \text{ are linear}$$

$$= S(u_1) + T(u_1) + S(u_2) + T(u_2)$$

$$= (S+T)(u_1) + (S+T)(u_2)$$

Let $K \in F$ & $u \in U$

$$(S+T)(Ku) = S(Ku) + T(Ku)$$

$$= KS(u) + KT(u) \quad \because S, T \text{ are linear}$$

$$= K(S(u) + T(u))$$

$$= K(S+T)(u)$$

Hence $S+T$ is linear & so $S+T \in L(U, V)$.

(ii) Associative law

Let $R, S, T \in L(U, V)$ then we prove

$$R + (S+T) = (R+S)+T$$

Now Consider for $u \in U$

$$[R + (S + T)](u) = R(u) + (S + T)(u) \quad (\text{By def. of sum})$$

$$= R(u) + [S(u) + T(u)]$$

$$= [R(u) + S(u)] + T(u)$$

$$= [(R + S)(u)] + T(u)$$

$$= [(R + S)(u) + T(u)]$$

$$= [(R + S) + T](u)$$

$$\Rightarrow R + (S + T) = (R + S) + T$$

So, $+$ is associative in $L(U, V)$.

(iii) Identity law

Clearly the zero transformation Ω defined by

$$\Omega(u) = 0 \quad \text{for all } u \in U$$

is a linear transformation from U to V & it is the additive identity in $L(U, V)$

(iv) Inverse law

For each $T \in L(U, V)$, we define

$-T \in L(U, V)$ by

$$(-T)(u) = -T(u)$$

then $-T$ is the additive inverse of T .

(v) Commutative law

Let $S, T \in L(U, V)$. then we show $S + T = T + S$

Now consider

$$(S + T)(u) = S(u) + T(u) \quad \text{By def. of sum}$$

$$= T(u) + S(u) \quad \therefore S(u), T(u) \in F$$

$$= (T + S)(u)$$

$$\Rightarrow S + T = T + S$$

Hence $+$ is commutative in $L(U, V)$

s. $L(U, V)$ is an abelian grp under $+$.

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Now we check scalar multiplication axioms.

(i) Let $\alpha \in F$ & $S \in L(U, V)$ then we prove $\alpha S \in L(U, V)$.

$$\begin{aligned} \text{Now } (\alpha S)(u_1 + u_2) &= \alpha [S(u_1 + u_2)] \\ &= \alpha [S(u_1) + S(u_2)] \quad \Rightarrow S \text{ is linear} \\ &= \alpha S(u_1) + \alpha S(u_2) \end{aligned}$$

Suppose $k \in F$ & $u \in U$ then

$$\begin{aligned} (k\alpha S)(u) &= \alpha [S(ku)] \\ &= \alpha [kS(u)] \quad \Rightarrow S \text{ is linear} \\ &= (k\alpha) S(u) \\ &= k(\alpha S)(u) \end{aligned}$$

Hence αS is linear & so $\alpha S \in L(U, V)$.

(ii) Let $a, b \in F$ & $S \in L(U, V)$ then we prove $a(bS) = (ab)S$

$$\begin{aligned} \text{Now } [a(bS)](u) &= a.(bS)(u) \\ &= a[b.S(u)] \\ &= (ab).S(u) \\ &= [(ab)S](u) \end{aligned}$$

$$\Rightarrow a(bS) = (ab)S$$

(iii) Let $a, b \in F$ & $S \in L(U, V)$ then we prove $(a+b)S = aS + bS$

$$\begin{aligned} \text{Now } [(a+b)S](u) &= (a+b).S(u) \\ &= a.S(u) + b.S(u) \\ &= (aS)(u) + (bS)(u) \\ &= [aS + bS](u) \end{aligned}$$

(iv) Let $\alpha \in F$ & $S, T \in L(U, V)$ then we prove $\alpha(S+T) = \alpha S + \alpha T$

$$\begin{aligned} \text{Now } [\alpha(S+T)](u) &= \alpha[(S+T)(u)] \\ &= \alpha[S(u) + T(u)] \\ &= \alpha.S(u) + \alpha.T(u) \\ &= (\alpha S)(u) + (\alpha T)(u) \end{aligned}$$

$$\text{S. } [\alpha(S+T)](u) = [\alpha S + \alpha T](u)$$

$$\Rightarrow \alpha(S+T) = \alpha S + \alpha T$$

(iv) Let $1 \in F$ & $S \in L(U,V)$ then we prove $1.S = S$

$$\text{Now. } (1.S)(u) = 1.S(u)$$

$$= S(u)$$

$$\Rightarrow 1.S = S$$

Since all the conditions are satisfied. S. $L(U,V)$ is a vector space over F .

Q15 Find a basis & dimension of each of $R(T) \& N(T)$, where

(ii) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is defined by

$$T(x_1, x_2, x_3) = (x_1 + 2x_2 - x_3, x_2 + x_3, x_1 + x_2 - 2x_3)$$

Soln. Given transformation is

$$T(x_1, x_2, x_3) = (x_1 + 2x_2 - x_3, x_2 + x_3, x_1 + x_2 - 2x_3)$$

Since \mathbb{R}^3 is generated by $(1, 0, 0), (0, 1, 0) \& (0, 0, 1)$. So

$R(T)$ will be generated by $T(1, 0, 0), T(0, 1, 0) \& T(0, 0, 1)$

$$\text{Here } T(1, 0, 0) = (1, 0, 1)$$

$$T(0, 1, 0) = (2, 1, 1)$$

$$\& T(0, 0, 1) = (-1, 1, -2)$$

Hence $R(T)$ is generated by $(1, 0, 1), (2, 1, 1) \& (-1, 1, -2)$

$$\text{Since } (2, 1, 1) = 3(1, 0, 1) + 1(-1, 1, -2)$$

So casting out the vector $(2, 1, 1)$, the set $\{(1, 0, 1), (-1, 1, -2)\}$ also spans $R(T)$. Since none of the two vectors is a multiple of other, so the set $\{(1, 0, 1), (-1, 1, -2)\}$ is linearly independent & so forms a basis for $R(T)$.

$$\text{Hence } \dim R(T) = 2$$

Now we find $\dim N(T)$:

A vector $(x_1, x_2, x_3) \in N(T)$ if $T(x_1, x_2, x_3) = 0$

i.e., if $(x_1 + 2x_2 - x_3, x_2 + x_3, x_1 + x_2 - 2x_3) = (0, 0, 0)$

$$\Rightarrow x_1 + 2x_2 - x_3 = 0 \quad \text{--- (1)}$$

$$x_2 + x_3 = 0 \quad \text{--- (2)}$$

$$x_1 + x_2 - 2x_3 = 0 \quad \text{--- (3)}$$

Adding (1) + (2)

$$x_1 + 3x_2 = 0$$

$$\text{or } \boxed{x_1 = -3x_2}$$

Put. in ③

$$-3x_2 + x_2 - 2x_3 = 0$$

$$-2x_2 - 2x_3 = 0$$

$$x_2 + x_3 = 0$$

$$\text{or } \boxed{x_3 = -x_2}$$

If $x_2 = 1$

then $x_1 = -3$, $x_2 = 1$, $x_3 = -1$

So the vector $(-3, 1, -1)$ spans $N(T)$. Also $(-3, 1, -1)$ is linearly independent. So $\{(-3, 1, -1)\}$ forms a basis for $N(T)$.

Hence $\dim N(T) = 1$

(ii) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^4$ is defined by

$$T(x_1, x_2, x_3) = (2x_1 + x_3, 4x_1 + x_2, x_1 + x_3, x_3 - 4x_2)$$

Sol. Given transformation is

$$T(x_1, x_2, x_3) = (2x_1 + x_3, 4x_1 + x_2, x_1 + x_3, x_3 - 4x_2)$$

Since \mathbb{R}^3 is generated by $(1, 0, 0)$, $(0, 1, 0)$ & $(0, 0, 1)$. So $R(T)$ will be generated by $T(1, 0, 0)$, $T(0, 1, 0)$ & $T(0, 0, 1)$

$$\text{Here } T(1, 0, 0) = (2, 4, 1, 0)$$

$$T(0, 1, 0) = (0, 1, 0, -4)$$

$$T(0, 0, 1) = (1, 0, 1, 1)$$

Hence $R(T)$ will be generated by $(2, 4, 1, 0)$, $(0, 1, 0, -4)$, $(1, 0, 1, 1)$

Now we check whether these vectors are linearly independent. For this let

$$a(2, 4, 1, 0) + b(0, 1, 0, -4) + c(1, 0, 1, 1) = (0, 0, 0, 0) \quad \text{where } a, b, c \in F$$

$$\text{or } (2a+c, 4a+b, a+c, -4b+c) = (0, 0, 0, 0)$$

$$\begin{aligned} \Rightarrow 2a+c = 0 & \quad \text{--- (1)} \\ 4d+b = 0 & \quad \text{--- (2)} \\ a+c = 0 & \quad \text{--- (3)} \\ -4b+c = 0 & \quad \text{--- (4)} \end{aligned}$$

$$(1) - (2) \Rightarrow a = 0$$

$$(3) \Rightarrow 0+c=0 \Rightarrow c=0$$

$$(2) \Rightarrow 0+b=0 \Rightarrow b=0$$

Hence vectors $(2, 4, 1, 0), (0, 1, 0, -4)$ & $(1, 0, 1, 1)$ are linearly independent. Hence $\{(2, 4, 1, 0), (0, 1, 0, -4), (1, 0, 1, 1)\}$ form a basis for $R(T)$.

$$\text{Hence } \dim R(T) = 3$$

Q16 Show that linear transformations preserve linear dependence.

Soln. Let $T: U \rightarrow V$ be a linear transformation, where U & V are vector spaces over the same field F . Suppose a set $\{u_1, u_2, \dots, u_n\}$ in U is linearly dependent. We want to show that $\{T(u_1), T(u_2), \dots, T(u_n)\}$ is a linearly dependent set in V .

Since $\{u_1, u_2, \dots, u_n\}$ is linearly dependent, so there exist scalars a_1, a_2, \dots, a_n , not all zero, such that

$$a_1u_1 + a_2u_2 + \dots + a_nu_n = 0$$

Applying T on both sides

$$T(a_1u_1 + a_2u_2 + \dots + a_nu_n) = T(0)$$

$$\text{or } a_1T(u_1) + a_2T(u_2) + \dots + a_nT(u_n) = 0. \quad (\because T \text{ is linear})$$

Since a_1, a_2, \dots, a_n are not all zero, so the above eq. shows that $\{T(u_1), T(u_2), \dots, T(u_n)\}$ are linearly dependent in V . Hence T preserves linear dependence.

Q17 Find the rank of each matrix in problem 8 of exercise 3.2 by the method of 6.42

(i)

$$\begin{bmatrix} 1 & 3 \\ 0 & -2 \\ 5 & -1 \\ -2 & 3 \end{bmatrix}$$

Sol:

Let $A = \begin{bmatrix} 1 & 3 \\ 0 & -2 \\ 5 & -1 \\ -2 & 3 \end{bmatrix}$ Then

$$\begin{aligned} \text{rank } A &= 1 + \text{rank} \begin{bmatrix} 1 & 3 \\ 0 & -2 \\ 5 & -1 \\ -2 & 3 \end{bmatrix} \\ &= 1 + \text{rank} \begin{bmatrix} -2 & 0 \\ -1 & 15 \\ 3 & 6 \end{bmatrix} \\ &= 1 + \text{rank} \begin{bmatrix} -2 \\ -16 \\ 9 \end{bmatrix} \\ &= 2 + \text{rank} \begin{bmatrix} -2 & 0 \\ -16 & 0 \\ 9 & 0 \end{bmatrix} \\ &= 2 + \text{rank} \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

$$\text{rank } A = 2$$

(ii)

$$\begin{bmatrix} 1 & 2 & -3 \\ 2 & 1 & 0 \\ -2 & -1 & 3 \\ -1 & 4 & -2 \end{bmatrix}$$

Sol:

Let $A = \begin{bmatrix} 1 & 2 & -3 \\ 2 & 1 & 0 \\ -2 & -1 & 3 \\ -1 & 4 & -2 \end{bmatrix}$ Then

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$$\text{rank } A = 1 + \text{rank} \begin{bmatrix} |1 & 2| & |1 & -3| \\ |2 & 1| & |2 & 6| \\ |1 & 2| & |1 & -3| \\ |-2 & -1| & |-2 & 3| \\ |1 & 2| & |1 & -3| \\ |-1 & 4| & |-1 & -2| \end{bmatrix}$$

$$= 1 + \text{rank} \begin{bmatrix} -3 & 6 \\ 3 & -3 \\ 6 & -5 \end{bmatrix}$$

$$= 2 + \text{rank} \begin{bmatrix} -3 & 6 \\ 3 & -3 \\ -3 & 6 \\ 6 & -5 \end{bmatrix}$$

$$= 2 + \text{rank} \begin{bmatrix} 9-18 \\ 15-36 \end{bmatrix}$$

$$= 2 + \text{rank} \begin{bmatrix} -9 \\ -21 \end{bmatrix}$$

$$= 3 + \text{rank} \begin{bmatrix} -9 & 0 \\ -21 & 0 \end{bmatrix}$$

$$= 3 + \text{rank} [0]$$

$$= 3$$

(iii)

$$\left[\begin{array}{ccccc} 1 & 3 & 1 & -2 & -3 \\ 1 & 4 & 3 & -1 & -4 \\ 2 & 3 & -4 & -7 & -3 \\ 3 & 8 & 1 & -7 & -8 \end{array} \right] \quad \overline{\overline{\quad}}$$

Sol.

Let $A = \left[\begin{array}{ccccc} 1 & 3 & 1 & -2 & -3 \\ 1 & 4 & 3 & -1 & -4 \\ 2 & 3 & -4 & -7 & -3 \\ 3 & 8 & 1 & -7 & -8 \end{array} \right]$

then

$$\begin{aligned}
 \text{rank } A &= 1 + \text{rank} \begin{bmatrix} \begin{vmatrix} 1 & 3 \\ 1 & 4 \end{vmatrix} & \begin{vmatrix} 1 & 1 \\ 1 & 3 \end{vmatrix} & \begin{vmatrix} 1 & -2 \\ 1 & -1 \end{vmatrix} & \begin{vmatrix} 1 & -3 \\ 1 & -4 \end{vmatrix} \\ \begin{vmatrix} 1 & 3 \\ 2 & 3 \end{vmatrix} & \begin{vmatrix} 1 & 1 \\ 2 & -4 \end{vmatrix} & \begin{vmatrix} 1 & -2 \\ 2 & -7 \end{vmatrix} & \begin{vmatrix} 1 & -3 \\ 2 & -3 \end{vmatrix} \\ \begin{vmatrix} 1 & 3 \\ 3 & 8 \end{vmatrix} & \begin{vmatrix} 1 & 1 \\ 3 & 1 \end{vmatrix} & \begin{vmatrix} 1 & -2 \\ 3 & -7 \end{vmatrix} & \begin{vmatrix} 1 & -3 \\ 3 & -8 \end{vmatrix} \end{bmatrix} \\
 &= 1 + \text{rank} \begin{bmatrix} 1 & 2 & 1 & -1 \\ -3 & -6 & -3 & 3 \\ -1 & -2 & -1 & 1 \end{bmatrix} \\
 &= 2 + \text{rank} \begin{bmatrix} \begin{vmatrix} 1 & 2 \\ -3 & -6 \end{vmatrix} & \begin{vmatrix} 1 & 1 \\ -3 & -3 \end{vmatrix} & \begin{vmatrix} 1 & -1 \\ -3 & 3 \end{vmatrix} \\ \begin{vmatrix} 1 & 2 \\ -1 & -2 \end{vmatrix} & \begin{vmatrix} 1 & 1 \\ -1 & -1 \end{vmatrix} & \begin{vmatrix} 1 & -1 \\ -1 & 1 \end{vmatrix} \end{bmatrix} \\
 &= 2 + \text{rank} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \\
 &= 2 + 0 \\
 &= 2
 \end{aligned}$$

(iv)

$$\begin{bmatrix} 1 & 3 & -2 & 5 & 4 \\ 1 & 4 & 1 & 3 & 5 \\ 1 & 4 & 2 & 4 & 3 \\ 2 & 7 & -3 & 6 & 13 \end{bmatrix}$$

Sol.

$$\text{Let } A = \begin{bmatrix} 1 & 3 & -2 & 5 & 4 \\ 1 & 4 & 1 & 3 & 5 \\ 1 & 4 & 2 & 4 & 3 \\ 2 & 7 & -3 & 6 & 13 \end{bmatrix} \quad \text{then}$$

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$$\text{rank } A = 1 + \text{rank} \begin{bmatrix} |1 \ 3| & |1 \ -2| & |1 \ 5| & |1 \ 5| \\ |1 \ 4| & |1 \ -1| & |1 \ 3| & |1 \ 5| \\ |1 \ 3| & |1 \ -2| & |1 \ 4| & |1 \ 4| \\ |1 \ 7| & |1 \ -3| & |1 \ 5| & |1 \ 4| \end{bmatrix}$$

$$= 1 + \text{rank} \begin{bmatrix} 1 & 3 & -2 & 1 \\ 1 & 4 & -1 & -1 \\ 1 & 1 & -4 & 5 \end{bmatrix}$$

$$= 2 + \text{rank} \begin{bmatrix} |1 \ 3| & |1 \ -2| & |1 \ 1| \\ |1 \ 4| & |1 \ -1| & |1 \ -1| \\ |1 \ 1| & |1 \ -4| & |1 \ 5| \end{bmatrix}$$

$$= 2 + \text{rank} \begin{bmatrix} 1 & 3 & -2 \\ -2 & -2 & 4 \end{bmatrix}$$

$$= 3 + \text{rank} \begin{bmatrix} |1 \ 1| & |1 \ -2| \\ |-2 \ -2| & |-2 \ 4| \end{bmatrix}$$

$$= 3 + \text{rank} \begin{bmatrix} 0 & 0 \end{bmatrix}$$

$$= 3 + 0$$

$$\text{rank } A = 3$$

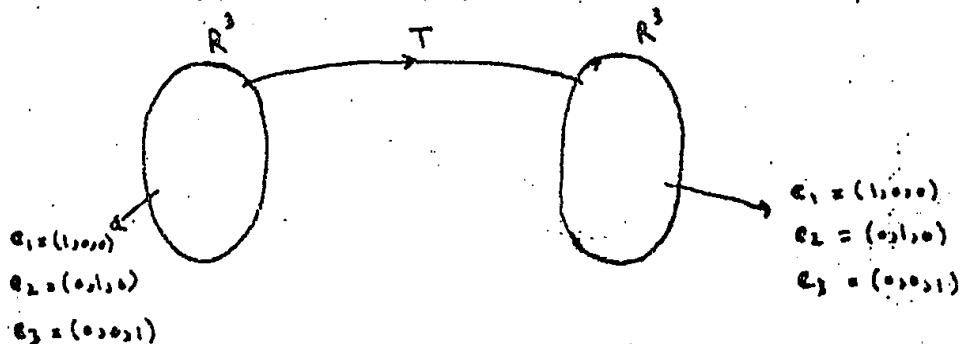
Exercise No. 6.4

Q1 Find the matrix of each of the following linear transformations from \mathbb{R}^3 to \mathbb{R}^3 with respect to the standard basis for \mathbb{R}^3 :

$$(i) \quad T(x_1, x_2, x_3) = (x_1, x_2, 0)$$

Sol: Given linear transformation is

$$T(x_1, x_2, x_3) = (x_1, x_2, 0)$$



Now

$$T(1, 0, 0) = (1, 0, 0) = 1(1, 0, 0) + 0(0, 1, 0) + 0(0, 0, 1)$$

$$T(0, 1, 0) = (0, 1, 0) = 0(1, 0, 0) + 1(0, 1, 0) + 0(0, 0, 1)$$

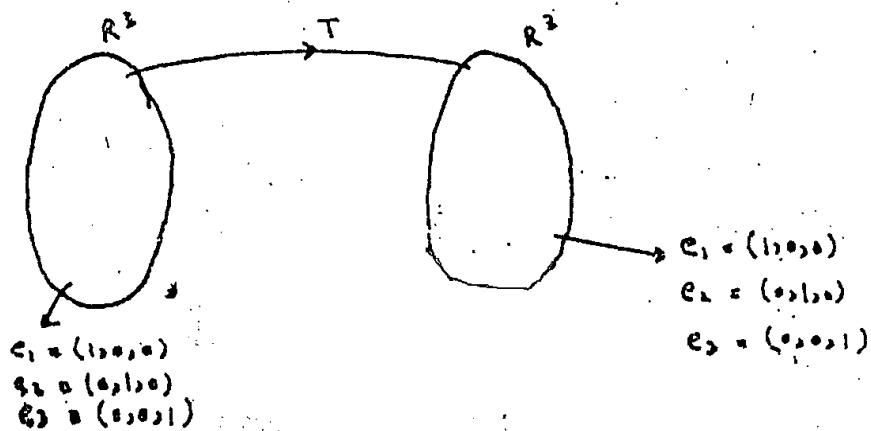
$$T(0, 0, 1) = (0, 0, 0) = 0(1, 0, 0) + 0(0, 1, 0) + 0(0, 0, 1)$$

Hence matrix of linear transformation T is

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$(ii) \quad T(x_1, x_2, x_3) = (x_1 + x_2, -x_1 - x_2, x_3)$$

Sol:



Here $T(x_1, x_2, x_3) = (x_1+x_2, -x_1-x_2, x_3)$

Then $T(1, 0, 0) = (1, -1, 0) = 1(1, 0, 0) + (-1)(0, 1, 0) + 0(0, 0, 1)$

$T(0, 1, 0) = (1, -1, 0) = 1(1, 0, 0) + (-1)(0, 1, 0) + 0(0, 0, 1)$

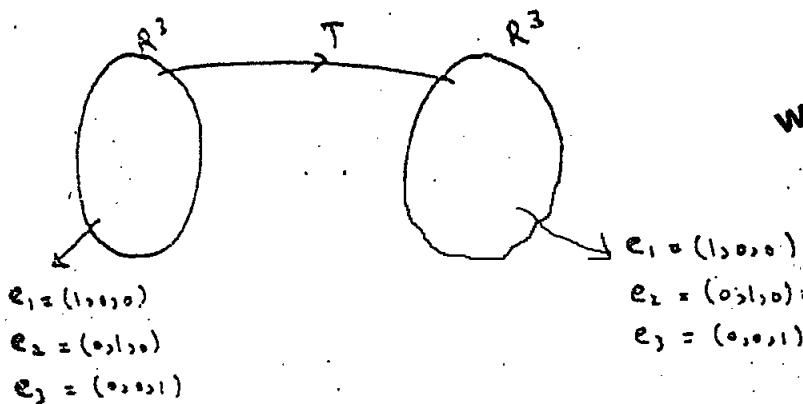
$T(0, 0, 1) = (0, 0, 1) = 0(1, 0, 0) + 0(0, 1, 0) + 1(0, 0, 1)$

Hence matrix of linear transformation T is

$$\begin{bmatrix} 1 & 1 & 0 \\ -1 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(iii) $T(x_1, x_2, x_3) = (x_2, -x_1, -x_3)$

Sol.



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Here $T(x_1, x_2, x_3) = (x_2, -x_1, -x_3)$

Then $T(1, 0, 0) = (0, -1, 0) = 0(1, 0, 0) + (-1)(0, 1, 0) + 0(0, 0, 1)$

$T(0, 1, 0) = (1, 0, 0) = 1(1, 0, 0) + 0(0, 1, 0) + 0(0, 0, 1)$

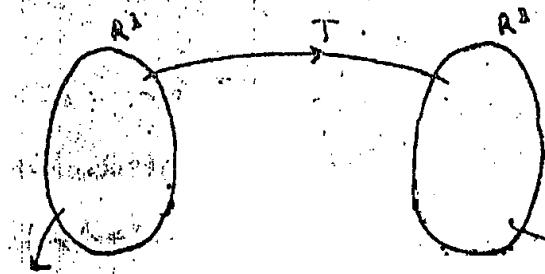
$T(0, 0, 1) = (0, 0, -1) = 0(1, 0, 0) + 0(0, 1, 0) + (-1)(0, 0, 1)$

Hence matrix of linear transformation T is

$$\begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

(iv) $T(x_1, x_2, x_3) = (x_1, x_2+x_3, x_1+x_2+x_3)$

Sol.



$$e_1 = (1,0,0)$$

$$e_2 = (0,1,0)$$

$$e_3 = (0,0,1)$$

$$\text{Here } T(x_1, x_2, x_3) = (x_1, x_2 + x_3, x_1 + x_2 + x_3)$$

$$\text{Then } T(1,0,0) = (1,0,1) = 1(1,0,0) + 0(0,1,0) + 1(0,0,1)$$

$$T(0,1,0) = (0,1,1) = 0(1,0,0) + 1(0,1,0) + 1(0,0,1)$$

$$T(0,0,1) = (0,0,1) = 0(1,0,0) + 1(0,1,0) + 1(0,0,1)$$

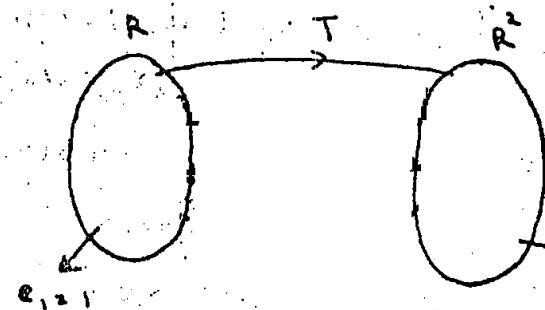
Hence matrix of linear transformation T is

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

Q2. Find the matrix of each of the following linear transformations with respect to the standard bases of the given spaces:

$$(i) T : \mathbb{R} \rightarrow \mathbb{R}^2 \text{ defined by } T(x) = (3x, 5x)$$

Sol:-



$$e_1 = (1,0)$$

$$e_2 = (0,1)$$

$$\text{Here } T(x) = (3x, 5x)$$

$$\text{then } T(1) = (3,5) = 3(1,0) + 5(0,1)$$

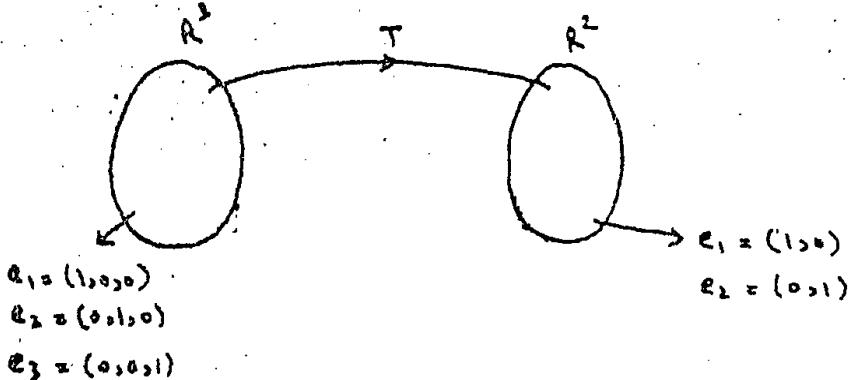
Hence matrix of linear transformation T is

$$\begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

(ii) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by

$$T(x_1, x_2, x_3) = (3x_1 - 4x_2 + 9x_3, 5x_1 + 3x_2 - 2x_3)$$

Sol.



$$\text{Here, } T(x_1, x_2, x_3) = (3x_1 - 4x_2 + 9x_3, 5x_1 + 3x_2 - 2x_3)$$

$$\text{Then } T(1, 0, 0) = (3, 5) = 3(1, 0) + 5(0, 1)$$

$$T(0, 1, 0) = (-4, 3) = -4(1, 0) + 3(0, 1)$$

$$T(0, 0, 1) = (9, -5) = 9(1, 0) + (-5)(0, 1)$$

Hence matrix of linear transformation T is

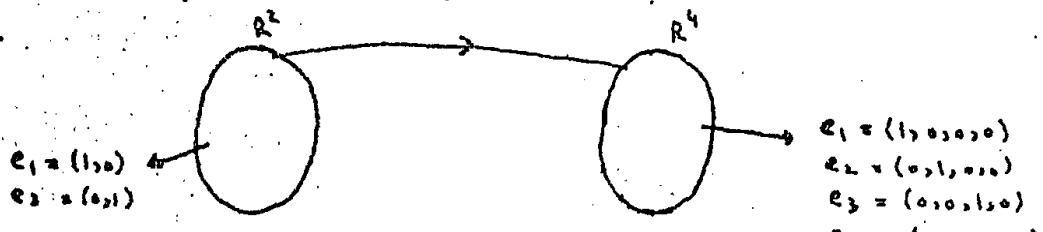
$$\begin{bmatrix} 3 & -4 & 9 \\ 5 & 3 & -5 \end{bmatrix}$$

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(iii) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$ defined by

$$T(x_1, x_2) = (3x_1 + 4x_2, 5x_1 - 2x_2, x_1 + 7x_2, 4x_1)$$

Sol.



$$\text{Here } T(x_1, x_2) = (3x_1 + 4x_2, 5x_1 - 2x_2, x_1 + 7x_2, 4x_1)$$

$$\text{Then } T(1, 0) = (3, 5, 1, 4) = 3(1, 0, 0, 0) + 5(0, 1, 0, 0) + 1(0, 0, 1, 0) + 4(0, 0, 0, 1)$$

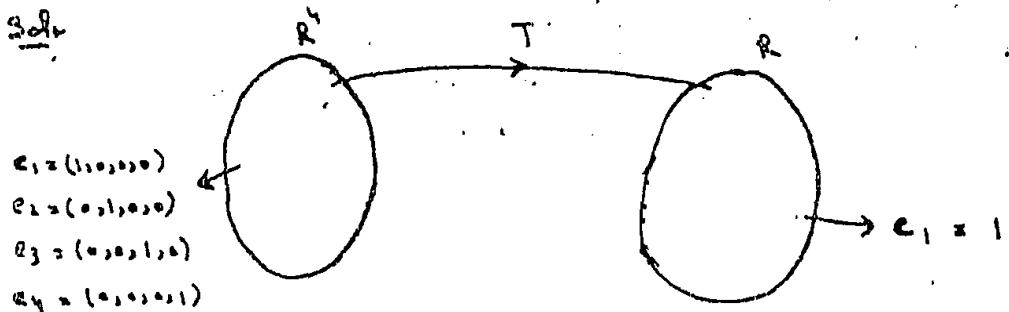
$$T(0, 1) = (4, -2, 7, 0) = 4(1, 0, 0, 0) - 2(0, 1, 0, 0) + 7(0, 0, 1, 0) + 0(0, 0, 0, 1)$$

Hence matrix of linear transformation T is

$$\begin{bmatrix} 3 & 4 \\ 5 & -2 \\ 1 & 7 \\ 4 & 0 \end{bmatrix}$$

(IV) $T: \mathbb{R}^4 \rightarrow \mathbb{R}$ defined by

$$T(x_1, x_2, x_3, x_4) = 2x_1 + 3x_2 - 7x_3 + x_4$$

Soln

$$\text{Here } T(x_1, x_2, x_3, x_4) = 2x_1 + 3x_2 - 7x_3 + x_4$$

$$\text{Then } T(1, 0, 0, 0) = 2 = 2 \cdot 1$$

$$T(0, 1, 0, 0) = 3 = 3 \cdot 1$$

$$T(0, 0, 1, 0) = -7 = -7 \cdot 1$$

$$T(0, 0, 0, 1) = 1 = 1 \cdot 1$$

Hence matrix of linear transformation T is

$$\underline{\begin{bmatrix} 2 & 3 & -7 & 1 \end{bmatrix}}$$

Q3 Each of the following is the matrix of a linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$. Determine m, n & express T in terms of co-ordinates.

(i)

$$\begin{bmatrix} 3 & 1 & 0 & 2 & 0 \\ 1 & 0 & 0 & 1 & 1 \\ 0 & -1 & 1 & 1 & 1 \end{bmatrix}$$

Soln Given linear transformation is

$$T: \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

Here $n = \text{no. of columns} = 5$ and $m = \text{no. of rows} = 3$

Now

$$\text{let } \mathbf{x} = (x_1, x_2, x_3, x_4, x_5) \in \mathbb{R}^5$$

Then T is defined as

$$= \begin{bmatrix} 3 & 1 & 0 & 2 & 1 \\ 1 & 0 & 0 & 1 & 1 \\ 0 & -1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}$$

$$T(x) = \begin{bmatrix} 3x_1 + x_2 + 0x_3 + 2x_4 + x_5 \\ x_1 + 0x_2 + 0x_3 + x_4 + x_5 \\ 0x_1 - x_2 + x_3 + x_4 + x_5 \end{bmatrix}$$

or

$$T(x_1, x_2, x_3, x_4, x_5) = (3x_1 + x_2 + 2x_4 + x_5, x_1 + x_4 + x_5, -x_2 + x_3 + x_4 + x_5)$$

which is T in terms of Co-ordinates.

(iii)

$$\begin{bmatrix} 6 & -1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix}$$

Sol: Given linear transformation is

$$T : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

Here $n = \text{no. of Columns} = 2$

& $m = \text{no. of rows} = 3$

Now let $x = (x_1, x_2) \in \mathbb{R}^2$

then T is defined as

$$T(x) = Ax$$

$$= \begin{bmatrix} 6 & -1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\text{or } T(x) = \begin{bmatrix} 6x_1 - x_2 \\ x_1 + 2x_2 \\ x_1 + 3x_2 \end{bmatrix}$$

$$\text{or } T(x_1, x_2) = (6x_1 - x_2, x_1 + 2x_2, x_1 + 3x_2)$$

which is T in terms of co-ords.

$$(iii) \quad \begin{bmatrix} 1 & 1 & 2 \\ 2 & 5 & 6 \\ -2 & 3 & -1 \end{bmatrix}$$

Sol. Given linear transformation is

$$T: \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

$$\text{Here } n = \text{no. of Columns} = 3$$

$$\text{& } m = \text{no. of rows} = 3$$

$$\text{Let } x = (x_1, x_2, x_3) \in \mathbb{R}^3 \text{ then}$$

T is defined as

$$T(x) = Ax$$

$$= \begin{bmatrix} 1 & 1 & 2 \\ 2 & 5 & 6 \\ -2 & 3 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$T(x) = \begin{bmatrix} x_1 + x_2 + 2x_3 \\ 2x_1 + 5x_2 + 6x_3 \\ -2x_1 + 3x_2 - x_3 \end{bmatrix}$$

or

$$T(x_1, x_2, x_3) = (x_1 + x_2 + 2x_3, 2x_1 + 5x_2 + 6x_3, -2x_1 + 3x_2 - x_3)$$

which is T in terms of co-ords.

Q4 The matrix of a linear transformation

$$T: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$$

$$\begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & -1 \\ -1 & -1 & 0 \end{bmatrix}$$

Find T in terms of co-ords.

& its matrix w.r.t. the basis

$$V_1 = (0, 1, 2), V_2 = (1, 1, 1), V_3 = (1, 0, -2).$$

Sol. Given linear transformation is

$$T: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$$

Let $x = (x_1, x_2, x_3) \in \mathbb{R}^3$ then T is defined as

$$T(x) = Ax$$

$$= \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & -1 \\ -1 & -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$T(x) = \begin{bmatrix} 0x_1 + x_2 + x_3 \\ x_1 + 0x_2 - x_3 \\ -x_1 - x_2 + 0x_3 \end{bmatrix}$$

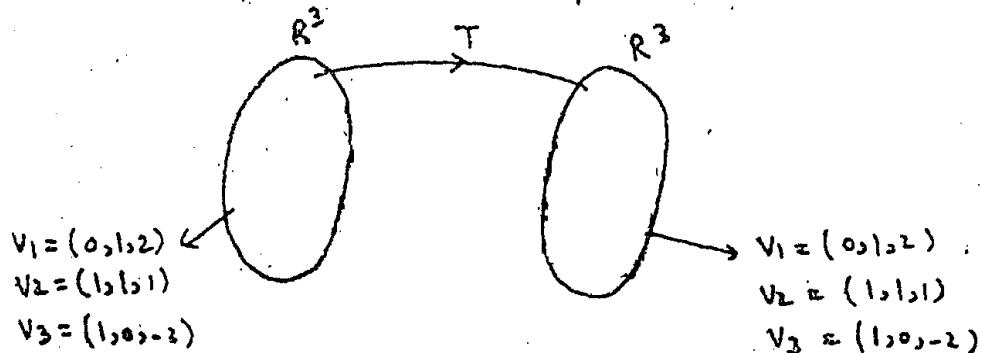
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or

$$T(x_1, x_2, x_3) = (x_2 + x_3, x_1 - x_3, -x_1 - x_2)$$

which is T in terms of co-ords.

Now we find matrix of T



$$\text{Here } T(x_1, x_2, x_3) = (x_2 + x_3, x_1 - x_3, -x_1 - x_2)$$

$$\text{Then } T(0, 1, 2) = (0, -2, -1) = a(0, 1, 2) + b(1, 1, 1) + c(1, 0, -2)$$

$$(0, -2, -1) = (b+c, a+b, 2a+b-2c)$$

$$\Rightarrow b+c = 0 \quad \text{--- (1)}$$

$$a+b = -2 \quad \text{--- (2)}$$

$$2a+b-2c = -1 \quad \text{--- (3)}$$

$$(1) - (2) \Rightarrow c-a = 2 \quad \text{--- (4)}$$

$$(2) - (3) \Rightarrow -a+2c = -1 \quad \text{--- (5)}$$

Solv. (4) from (1)

$$-c = 6$$

$$\Rightarrow \boxed{c = -6}$$

Put in ①

$$b - 6 = 3$$

$$\Rightarrow \boxed{b = 9}$$

Put in ④

$$a + 9 = -2$$

$$\boxed{a = -11}$$

Now

$$\begin{aligned} T(1,1,1) &= (2,0,-2) = \overset{-2}{a}(0,1,2) + \overset{1}{b}(1,1,1) + \overset{0}{c}(1,0,-2) \\ &= (b+c, a+b, 2a+b-2c) \end{aligned}$$

$$\Rightarrow b+c = 2 \quad \text{--- } ①$$

$$a+b = 0 \quad \text{--- } ②$$

$$2a+b-2c = -2 \quad \text{--- } ③$$

$$\begin{aligned} ① - ② &\Rightarrow c - a = 2 \\ &-a + 2c = 2 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\}$$

put. we get

$$-c = 0 \Rightarrow \boxed{c = 0}$$

Put in ①

$$b + 0 = 2 \Rightarrow \boxed{b = 2}$$

Put in ②

$$a + 2 = 0 \Rightarrow \boxed{a = -2}$$

Now

$$\begin{aligned} T(1,0,-2) &= (-2,3,-1) = \overset{14}{a}(0,1,2) + \overset{-11}{b}(1,1,1) + \overset{9}{c}(1,0,-2) \\ &= (b+c, a+b, 2a+b-2c) \end{aligned}$$

$$\Rightarrow b+c = -2 \quad \text{--- } ①$$

$$a+b = 3 \quad \text{--- } ②$$

$$2a+b-2c = -1 \quad \text{--- } ③$$

$$① - ② \Rightarrow$$

Adding ① & ②

$$2a = 0 \Rightarrow a = 0$$

Put in ①

$$0 - b = 0 \Rightarrow b = 0$$

Hence vectors $(1,1)$ & $(-1,1)$ are linearly independent & since they are two in number, so they form a basis for \mathbb{R}^2 .

Let (x_1, x_2) be an arbitrary vector of \mathbb{R}^2
then (x_1, x_2) can be expressed as

$$\begin{aligned}(x_1, x_2) &= a(1,1) + b(-1,1) \\ &= (a-b, a+b)\end{aligned}$$

\Rightarrow

$$a-b = x_1 \quad \text{--- ①}$$

$$a+b = x_2 \quad \text{--- ②}$$

$$2a = x_1 + x_2$$

$$\therefore a = \frac{x_1+x_2}{2}$$

Put in ①

$$\frac{x_1+x_2}{2} - b = x_1$$

$$b = \frac{x_1+x_2}{2} - x_1$$

$$= \frac{x_1+x_2-2x_1}{2}$$

$$b = \frac{x_2-x_1}{2}$$

$$\text{So } (x_1, x_2) = \left(\frac{x_1+x_2}{2}\right)(1,1) + \left(\frac{x_2-x_1}{2}\right)(-1,1)$$

Applying T on both sides

$$\begin{aligned}T(x_1, x_2) &= T\left\{\left(\frac{x_1+x_2}{2}\right)(1,1) + \left(\frac{x_2-x_1}{2}\right)(-1,1)\right\} \\ &= \left(\frac{x_1+x_2}{2}\right)T(1,1) + \left(\frac{x_2-x_1}{2}\right)T(-1,1) \quad \because T \text{ is linear}\end{aligned}$$

$$c - a = -5 \quad \text{---}$$

$$\textcircled{1} - \textcircled{2} \Rightarrow -a + 2c = 4 \quad \text{---}$$

Solving we get

$$-c = -9 \Rightarrow c = 9$$

Put in \textcircled{1}

$$b + 9 = -2 \Rightarrow b = -11$$

Put in \textcircled{2}

$$a - 11 = 3 \Rightarrow a = 14$$

Hence matrix of linear transformation T

$$\begin{bmatrix} -11 & -2 & 14 \\ 9 & 2 & -11 \\ -6 & 0 & 9 \end{bmatrix}$$

Q5 A linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ maps the vector $(1, 1)$ into $(0, 1, 2)$ & the vector $(-1, 1)$ into $(2, 1, 0)$. What matrix does T represent with respect to the standard bases for \mathbb{R}^2 & \mathbb{R}^3 ?

Sol Given linear transformation is

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

We are given that

$$T(1, 1) = (0, 1, 2)$$

$$T(-1, 1) = (2, 1, 0)$$

First we check linear independence of vectors $(1, 1)$ & $(-1, 1)$ suppose for scalars a, b

$$a(1, 1) + b(-1, 1) = 0$$

$$(a-b, a+b) = (0, 0)$$

$$\Rightarrow a-b = 0 \quad \text{---} \textcircled{1}$$

$$a+b = 0 \quad \text{---} \textcircled{2}$$

$$T(x_1, x_2) = \left(\frac{x_1+x_2}{2}, (x_1+2x_2), x_1+x_2 \right)$$

$$= (x_2-x_1, \frac{x_1+x_2}{2} + \frac{x_1-x_2}{2}, x_1+x_2)$$

$$\therefore T(x_1, x_2) = (x_2-x_1, x_2, x_1+x_2)$$

which is T in terms of co-ords.

$$\text{Now as } T(x_1, x_2) = (x_2-x_1, x_2, x_1+x_2)$$

$$\text{then } T(1, 0) = (-1, 0, 1).$$

$$= -1(1, 0, 0) + 0(0, 1, 0) + 1(0, 0, 1)$$

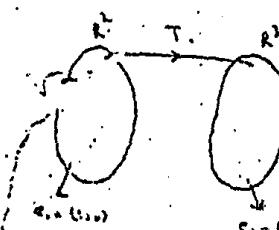
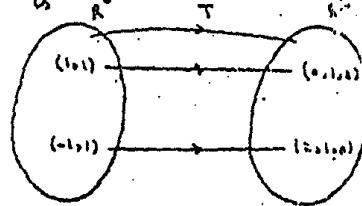
$$+ T(0, 1) = (1, 1, 1)$$

$$= 1(1, 0, 0) + 1(0, 1, 0) + 1(0, 0, 1)$$

Hence matrix of linear transformation T is

$$\begin{bmatrix} -1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$$

GOOD LUCK



$$\begin{aligned} e_1 &= (1, 0, 0) \\ e_2 &= (0, 1, 0) \\ e_3 &= (0, 0, 1) \end{aligned}$$